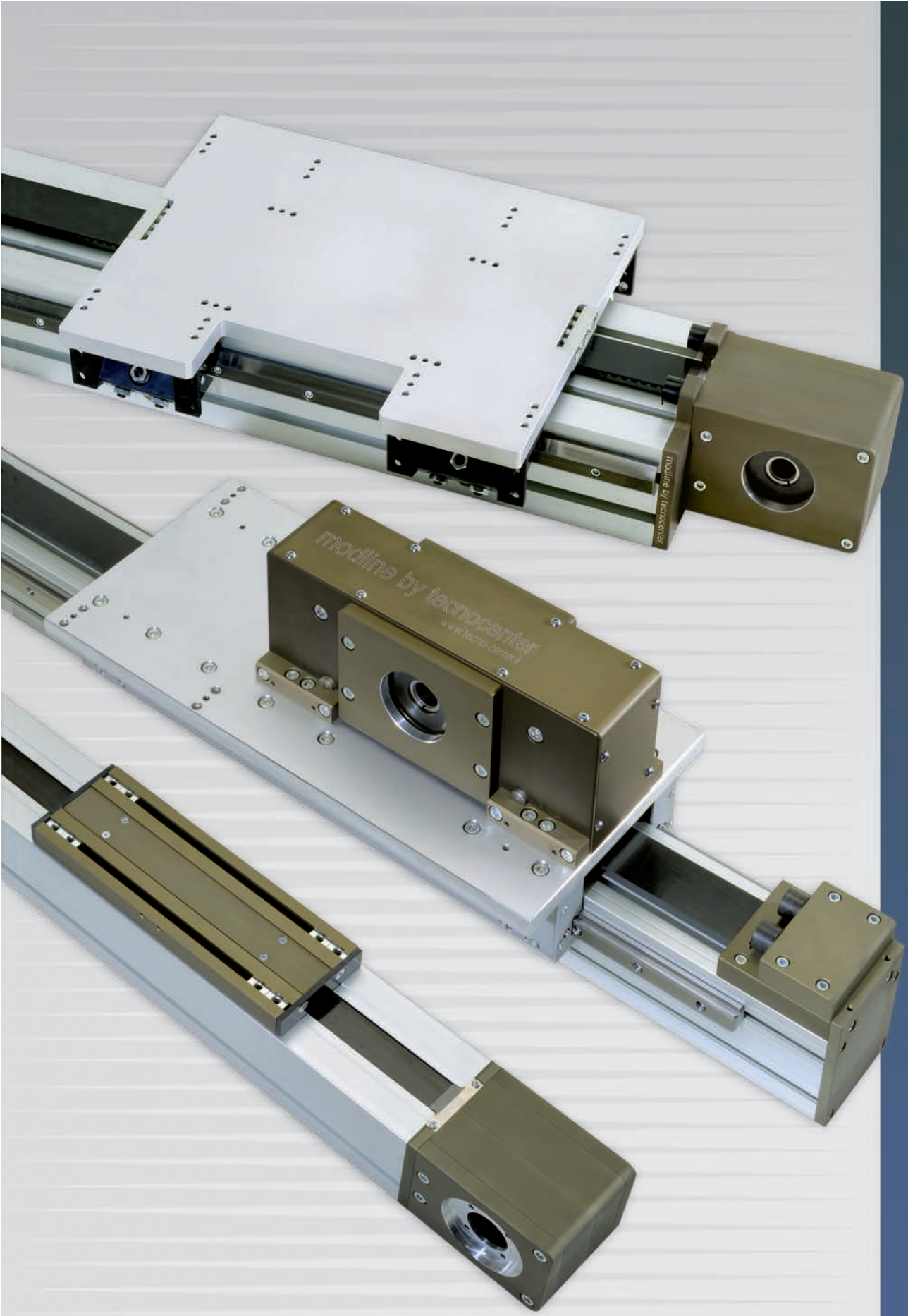

modline

tecnocenter

Belt and screw type linear modules

Contents

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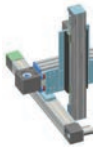
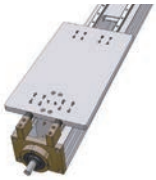
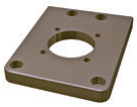






Construction characteristics

Beams
Obtained from Tecno Center extruded and anodised aluminium alloy profiles. Material features: Al Mg Si 0.5 hardened and tempered, F25 quality, Rm 245 N/mm2, tolerance as per EN 755-9 and EN 12020-2. Profiles have been specially designed to achieve high stiffness and long lengths (up to 12 m), in order to obtain solid, lightweight structures, suitable for the construction of linear transfer machines.

Plates
Obtained from aluminium alloy rolled sections, tensile strength Rm 290 N/mm2, HB 77, high performance. On request we perform machining work on all standard plates (D code) and according to detailed customer drawings.

V-shaped guide rails
In hardened and ground high carbon steel (min. hardness 58 HRC). (Anti-oxidation coating upon request).

Guide rails for caged ball roller slides
S version: high performance, with cage, primary producers. L version: high dynamics, medium loads.
H version: standard performance and limited dynamics.

Roller slides
Body in aluminium alloy G AL SI 5 hardened and tempered according to UNI 3600 or Alloy 6082, rollers with double rows of angular contact ball bearings, backlash-free, long life lubrication: Ø 30, Ø 40, Ø 52, Ø 62 mm rollers. Adjustable tolerance between rollers and guide rails. Complete with new felt scrapers.

Toothed drive and driven pulleys
In C40 steel with coupling toothing on the polyurethane belt, backlash-free, with anti-oxidation treatment. Equipped with large, watertight bearings, capable of withstanding high work performance, due to the use of the multicarriage with durable, alternating backlash-free movements.

Toothed belts
In durable polyurethane, fitted with high-resistance reinforced steel wobblers, which prevent the belt from lengthening over time. They are grease, oil and gasoline-proof and can work at temperatures from - 30° up to +80°. The belt is fastened to the plate by means of a hooked support. The belt can be serviced without disassembling the equipment on the plate (standard versions).

Shrink-discs, shafts and pulleys
All models shown in the catalogue work with the standard conical shrink-disc drive system to lock the driving shaft and the driven shaft if present. Gearbox or shaft adapting plates are supplied upon request, as per drawing.

Stop pads
Important: the rubber stop pads provided with standard linear models are suitable and regarded as static limit switches. For special needs, such as safety stops if the drive breaks, please specify loads, dynamics, details and discuss the use of specific parts, accessories and devices (reinforced plates and attachments - shock absorbers, safety and/or anti-drop devices, etc.) with our technical dept.

Anodizing
We supply all linear modules equipped with: natural, anodised aluminium alloy profiles (min. 11μ), driving heads, driven heads, carriages (MC series), counter plates, in dark bronze anodizing (min. 11μ).

Anti-oxidation parts and coatings
Modules are also available with anti-oxidation coating. Materials and coatings are selected according to the environment of use (food industry, marine environment, etc.).

Assembly specifications

Main features of the roller translation system
The translation system consists of a plate to which two roller slides with concentric pins and two with eccentric pins are fixed. The eccentric pins are suitable for adjusting backlash between the roller slide and the sliding track. Check that the angular position of the rollers is such that they can support the max. working load (page 10).

Guide rails and roller slides are particularly suitable for use in dusty and aggressive environments.

Important: during adjustment, overloading is easily achieved: this may result in premature wear.

NB: always keep friction low. If friction is high, loosen and repeat the adjustment.

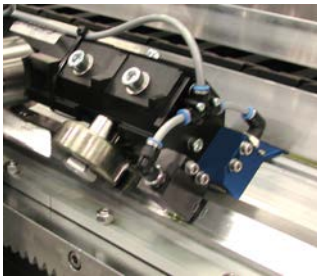
Main features of the caged ball roller slides translation system
The sliding system guarantees high performance in terms of precision and load resistance, reduced maintenance and stiffness thanks to the connecting slots of the profile.

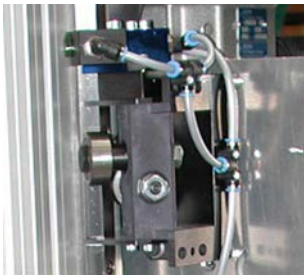
All guide rails are directly fixed onto the profile surface, appropriately machined to guarantee geometric and dimensional tolerances, paying attention to the parallelism between them. In large modules, any profile flatness or parallelism errors are corrected by means of the appropriate machining procedures. Please inform our technical dept. of any specific application requirements.

Lubrication

Roller slides and caged ball roller slides
Roller slides are provided with a permanent lubrication system which, if properly used, eliminates the need for any further maintenance, also considering the average life of any handling device. As for screw modules, the caged ball or V screw requires periodical lubrication.

For applications on plants with a high number of daily cycles, or with a significant build-up of impurities, please check the need for lubrication, seals and additional tanks with our technical dept. Do not use solvents to clean rollers or roller slides, as you could unintentionally remove the grease lubricating coat applied to the rolling elements during assembly.
Use grease and lithium soap according to DIN 51825 - K3N. Read the instruction manual





Complete central lubrication system. Grease cartridge upon request.

Guide rails
If properly assembled, guide rails do not require any lubrication, which would attract impurities and have negative consequences. Should there be any surface defects on the guide rails and/or on the rolling parts, such as pitting or erosion, this might be due to an excessive load. In this case, all worn parts must be replaced and the load geometry and alignment checked.

Introduction - operation and control unit

On request, we can supply systems complete with specific motor drives for industrial automation applications, suitable for specific handling tasks according to the customer's needs (moving loads, accelerations, speeds, cycle times, resolution, repeatability).
These can be equipped with gearboxes, servomotors, mechanical limit switches, proximity switches and various accessories, such as energy chains, interface plates, fixing supports.

Our technical dept. is at your complete disposal for any scaling requirements and the choice of moving unit and electromechanical parts suitable to achieve the required performance levels. We can draw on our experience to help our customers in their choice of linear unit and the following parts:
gearboxes: worm screw, planetary, bevel;
motors: stepper, brushless, DC, asynchronous.

For each of these we can propose drives manufactured by primary producers marketed in Italy and abroad suitable for the calculated power ratings.
Tecno Center is able to support the customer in choosing complete systems equipped with axis control, with or without interpolation, with or without PLC, suitable for operating handling cycles and machine management. The customer has only to provide for piping and wiring.

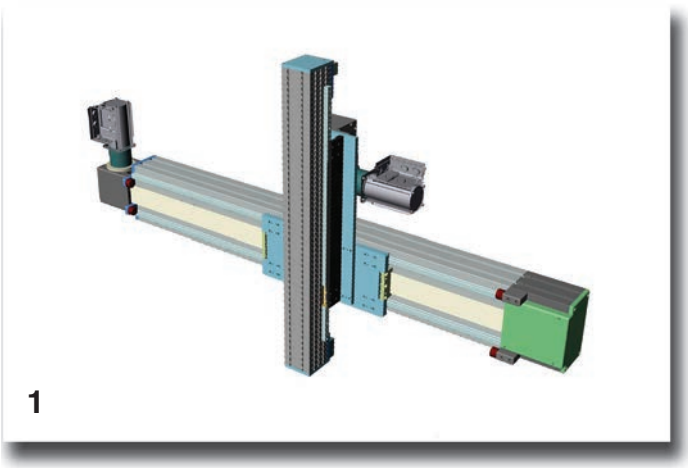
Application examples:

glue releasing units
paint or resin distribution units
load/unload of manufacturing machines
pick and place systems
control and sensing instrument handling
drilling boards
cartesian robots with 2, 3 or more axes

Tightening specifications

During set-up, make sure all parts are locked with the appropriate screws and with the right tightening torques.

Standard assembly solutions



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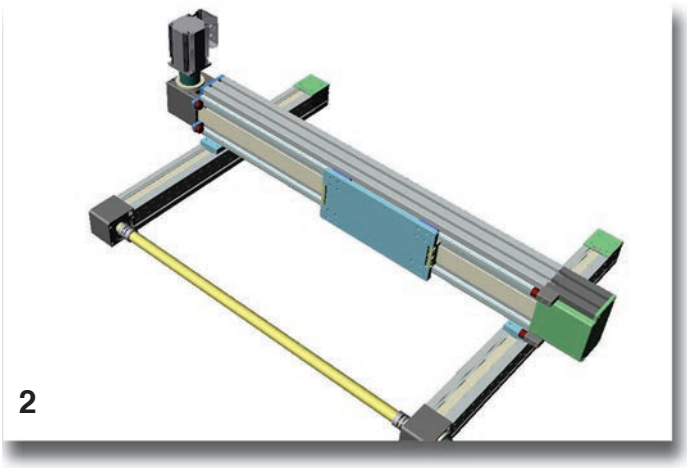

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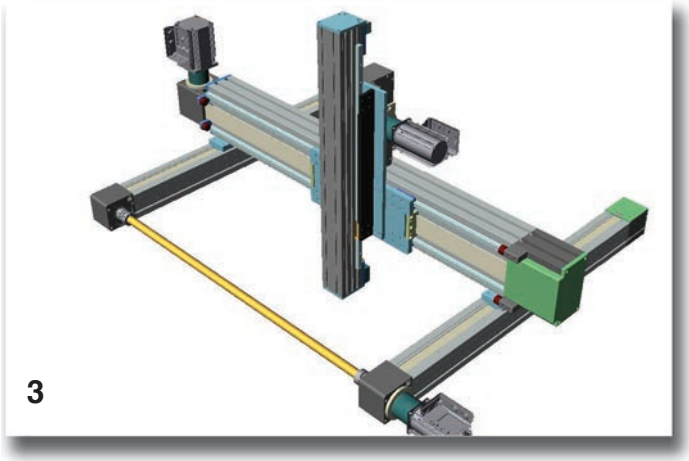

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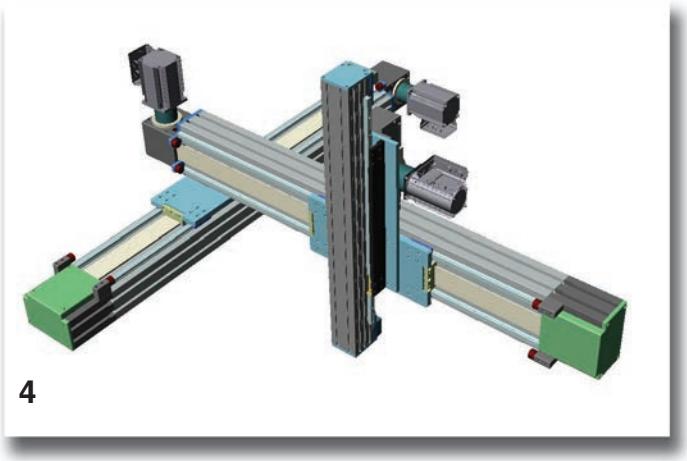

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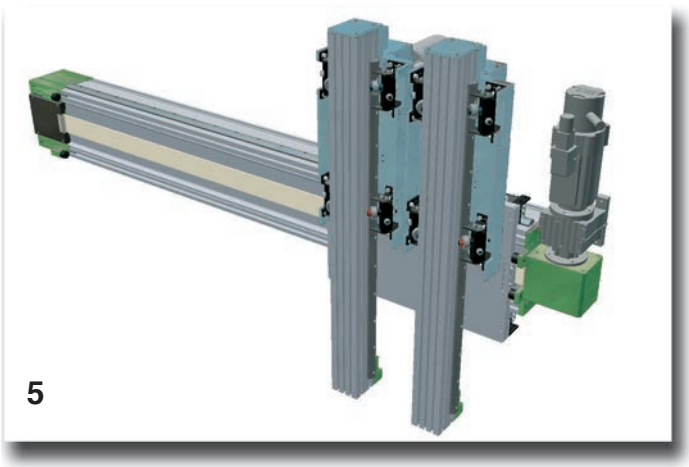

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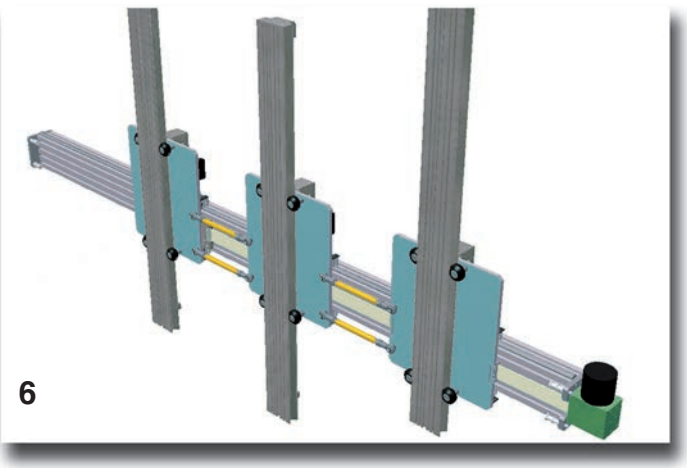

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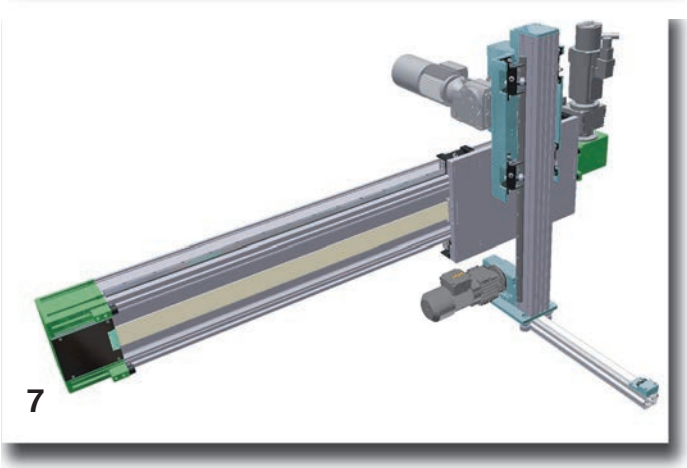

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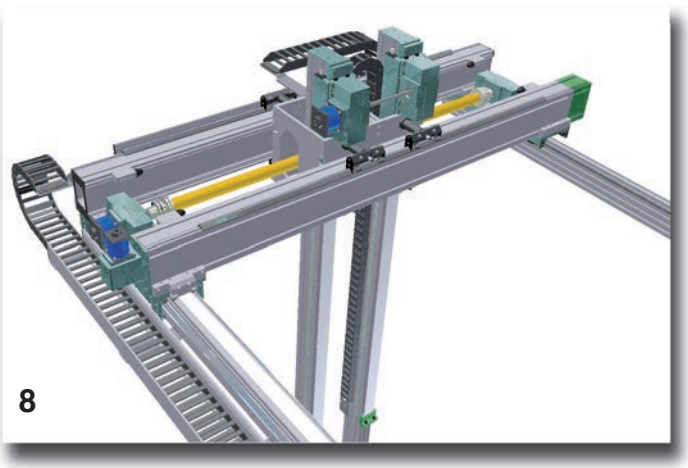

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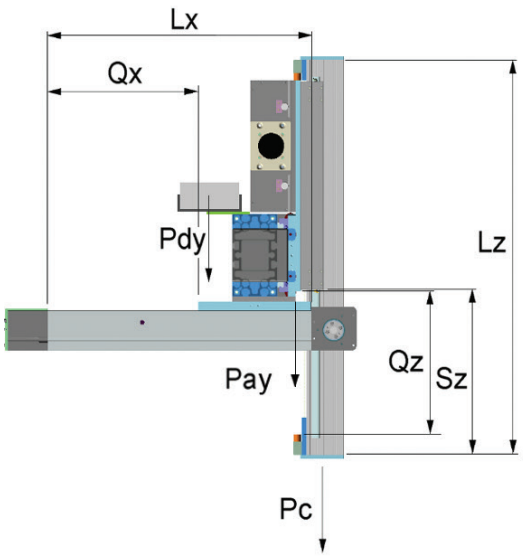
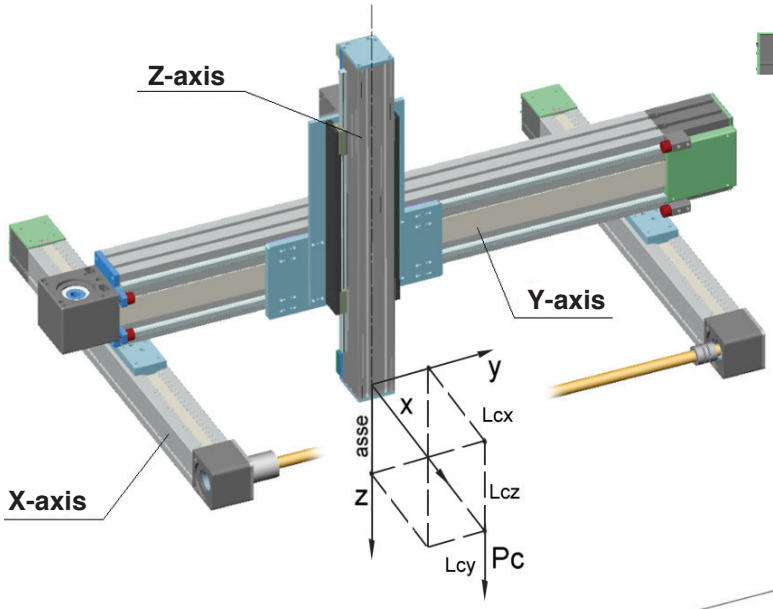
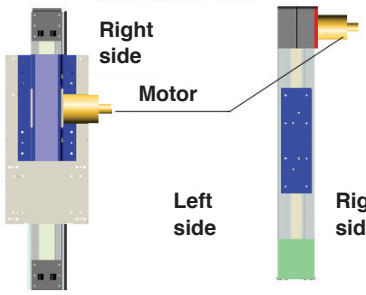
Sizing template

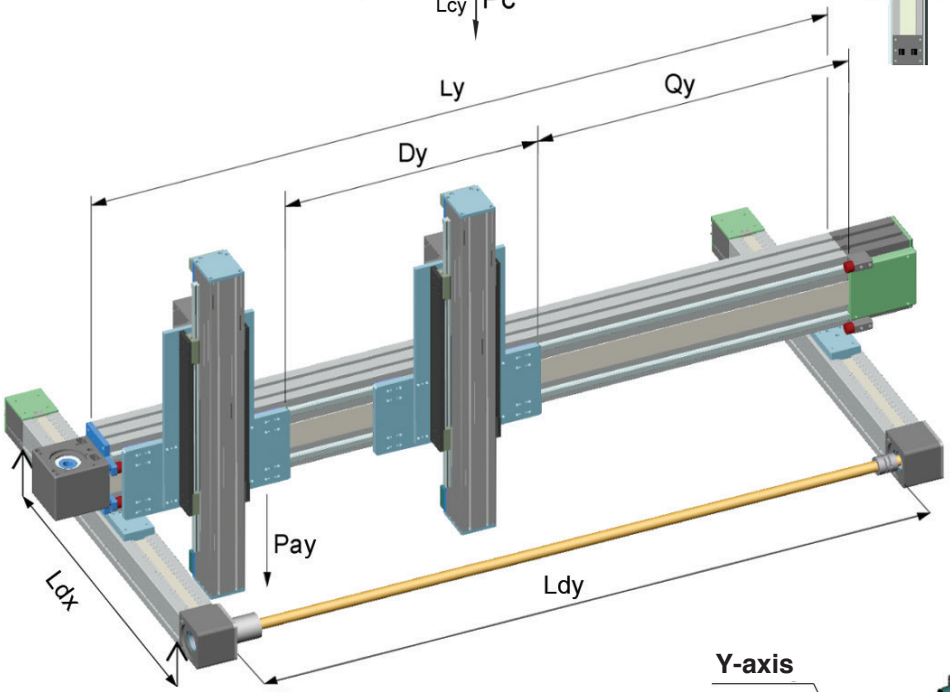
Our Technical Support dept.
is available to check sizing calculations. Please fill in the form with all the necessary data and send it to our technical dept., which will suggest the most suitable size according to the forces applied and precision required.





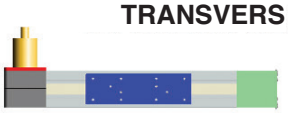
VERTICAL

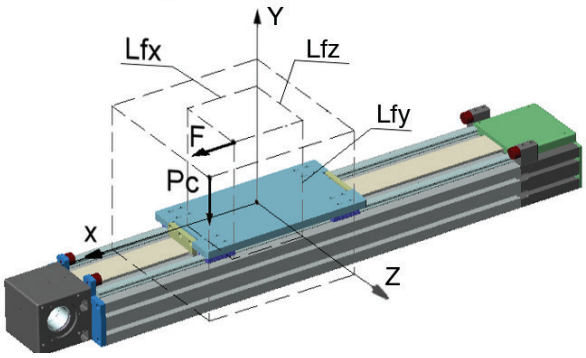


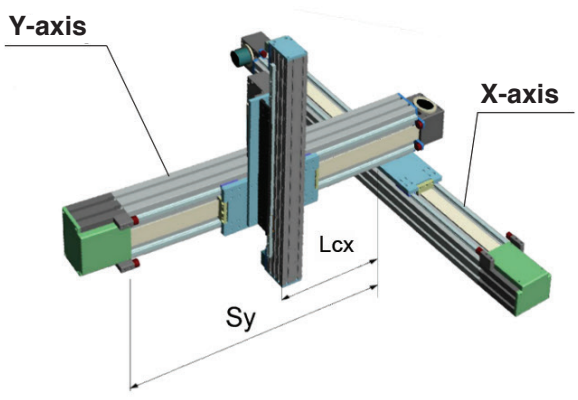


HORIZONTAL

TRANSVERS







Sizing request form

For a proper definition of the linear units, fill in the scaling request form and send it to the Technical Support Department.

Date: .....**Request N°:**.....

Filled in by:.....

Company: .....

Address:.....

Tel.: .....**Fax:**.....

E-mail:.....

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Sizing template

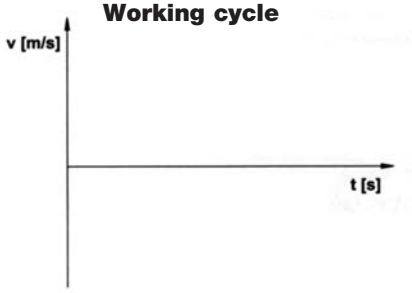
required data | optional data

MODLINE linear modules

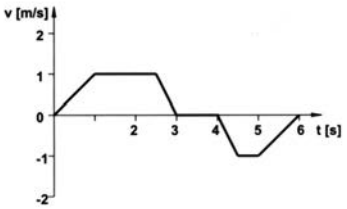
ASSEMBLY SOLUTIONS (see page 5) n°

	Z-axis		Y-axis		X-axis	
Total length of profile (excluding heads)	Lz		Ly		Lx	[mm]
Total working load including gripper (add Z axis for Y and X axes)	Pc		Py		Px	[kg]
Equipment weight on carriage (gearbox, cylinder, OPTIONAL)	Paz		Pay		Pax	[kg]
Weight distributed on the beam (energy chain)	Pdz		Pdy		Pdx	[kg/m]
Profile supports			n°		n°	
Max. projection (any overhang, the biggest)	Sz		Sy		Sx	[mm]
Max. span			Ldy		Ldx	[mm]
Offset load's centre of gravity (X-axis)	Lcx					[mm]
Offset load's centre of gravity (Y-axis)	Lcy					[mm]
Offset load's centre of gravity (Z-axis)	Lcz					[mm]
Any additional force	F					[N]
Offset additional force (X-axis)	Lfx					[mm]
Offset additional force (Y-axis)	Lfy					[mm]
Offset additional force (Z-axis)	Lfz					[mm]
Possible distance between the carriages	Dz		Dy		Dx	[mm]
Transmission performance	η =					
Assembly: vertical= 90° - slope = 30°, 45°, 60° - horizontal	α=					
Stroke	Qz		Qy		Qx	
Speed	Vz		Vy		Vx	[m/s]
Acceleration	Az		Ay		Ax	[m/s^2]
Stroke time	Tz		Ty		Tx	[s]
Positioning accuracy and repeatability	+/-					[mm]
Work environment (temperature and cleanliness)						
Daily working cycles	n°					

Working cycle



Example working cycle



Notes:.....

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Preliminary selection table (1-2-3 axes)

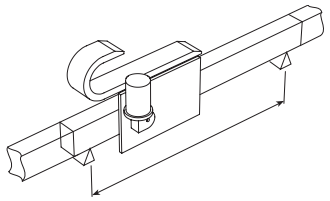
These tables are useful for making a preliminary selection with load applied in a central position with respect to the plate or profile axis. Z axis length is < 1600 mm. Deflection is computed assuming continuous beams having the same span and concentrated static loads.

In the following table, select the appropriate X axes according to the load

Max. Load capacity [kg.]	PA	2X	3X	4X	5X	6X	8X	10X	LC
		Deflection							
	50	1.4							5000
	100	1.8							5000
	200	2.7	1.8						5000
	300		2.3	2.7					5000
	400			3.3	2.4				5000
	500				2.8	1.8			5000
	600					2	2		6000
	800						2.5	1.8	6000
	1000							2.1	7000

NB: for vertical 8X and 10X portals, compensate the load

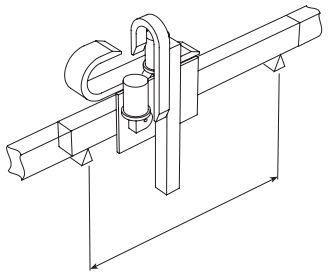
X-Axis



From the table below, select the most suitable combination of Y-Z axes depending on the load.

Max. Load capacity [kg.]	PA	2/1	3/1	4/1	5/2	6/2	8/3	6/4	8/6	10/6	10/8	LC
		Deflection										
	50	1.9										5000
	100	2.4	1.7	2	1.6							5000
	200				2.2	0.8	0.8					5000
	300					1.6	1.6	1.6				6000
	400							1.9	2	0.9		6000
	500								2.2	1		6000
	600								2.5	1.2	1.2	6000
	800										2.2	7000

Y-Z-Axis

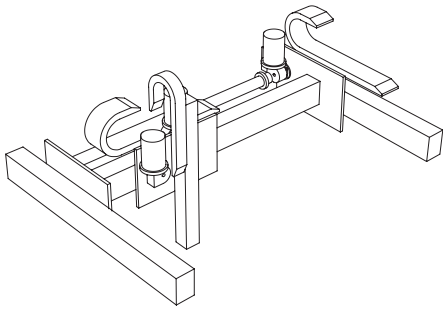


From the table below, select the most suitable combination of X-Y-Z axes depending on the load.

X-axis	Y-Z-axis PA	2/1	3/1	4/1	5/2	6/2	8/3	6/4	8/6	10/6	10/8
	PA Load [kg.]	100	100	100	200	200	300	400	600	600	700
	2X										
	3X										
	4X										
	5X										
	6X										
	8X										
	10X										

NB : the choice of X axis is based upon the actual load, the supporting points, max. deflection and the total weight of the Y-Z axes

X-Y-Z-Axis



EXAMPLE: selection of 3-axis portal with roller slides

(Please see page 7 and the portal pages for the nomenclature)

DATA: Total working load 300 kg, X axis stroke: 5,000 mm, Y axis stroke: 4,000 mm, Z axis stroke: 2,000 mm, support points: 2

By analysing the table of Y-Z axes based on the working load (Pc), profile length (Ly) and deflection, the selection falls on one PA 8/3 (load 300 kg.) portal

Check: $P_{eff} = P_{max}$- (Lz - 1,600)/1,000•q_z = 300-(2,900-1,600)/1,000•35 = 254.5 kg. < di 300 kg. Therefore select the larger size PA 6/4 (max. load capacity 400 kg.)

M_{tot} PA 6/4 (Y+Z) = M_{base}+(q_y•stroke$_y$+q_z• stroke$_z$)/1,000+Pc = 244+(66•4,000+48•2,000)/1,000+300 = 904 kg.

Ptx = M_{tot} PA 6/4 (Y+Z)•0.66 = 596.6 kg.

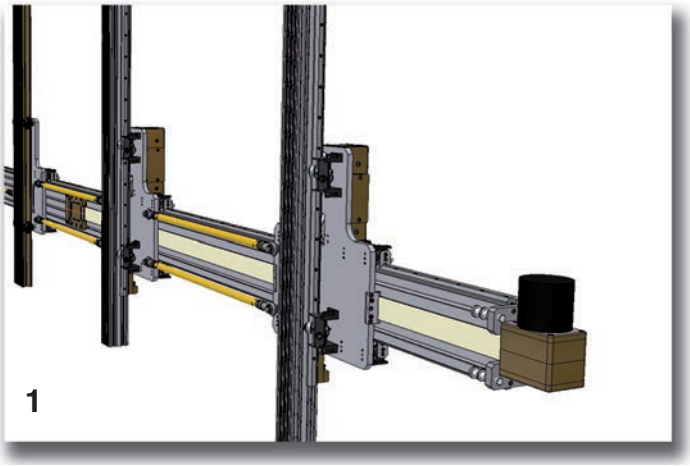
Lx = stroke$_x$ + 1,200 approx = 5,000+1,200 = 6,200 mm

By analysing the table of X axes based on the load (Ptx) profile length (Lx) and deflection, it is possible to select two PA 6X linear axes

Chosen composition: n°1 PA 6/4 + n° 2 PA 6X

Perform a final analysis by computing the deflection based on the actual size of the spans. Our technical dept. is at your complete disposal to help you examine the most suitable applications for your requirements.

Special applications with standard modules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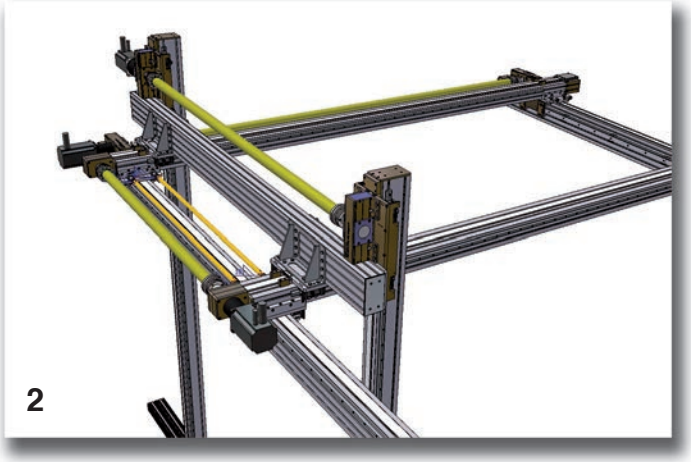
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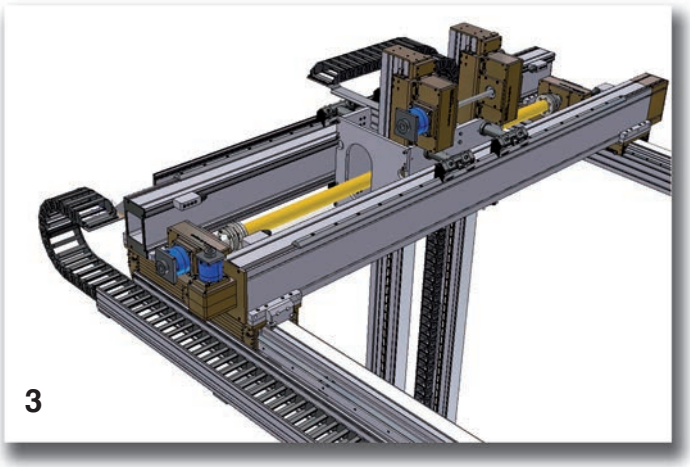
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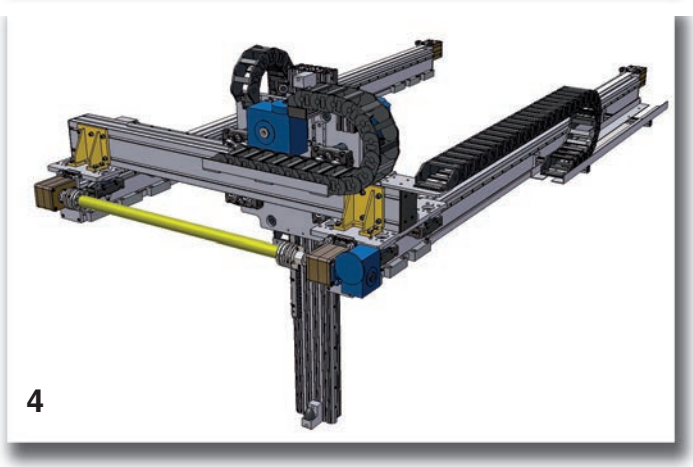
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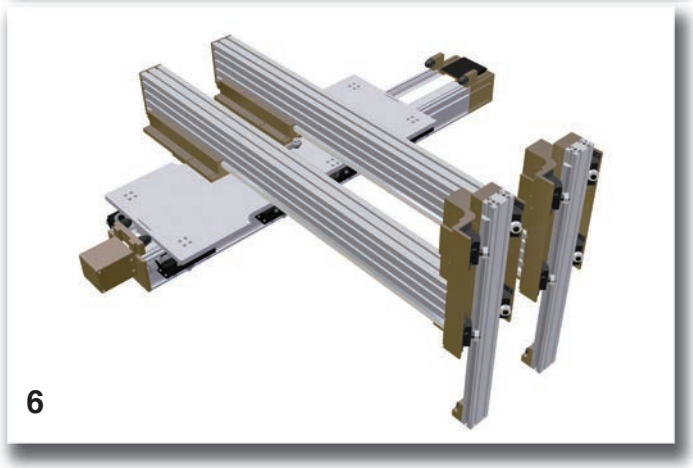
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7

1 Multi-gripper handling system with belt drive

2 Panel handling system, construction industry

3 Tool handling system in the iron and steel industry

4 Pick and place system for storage battery production plant

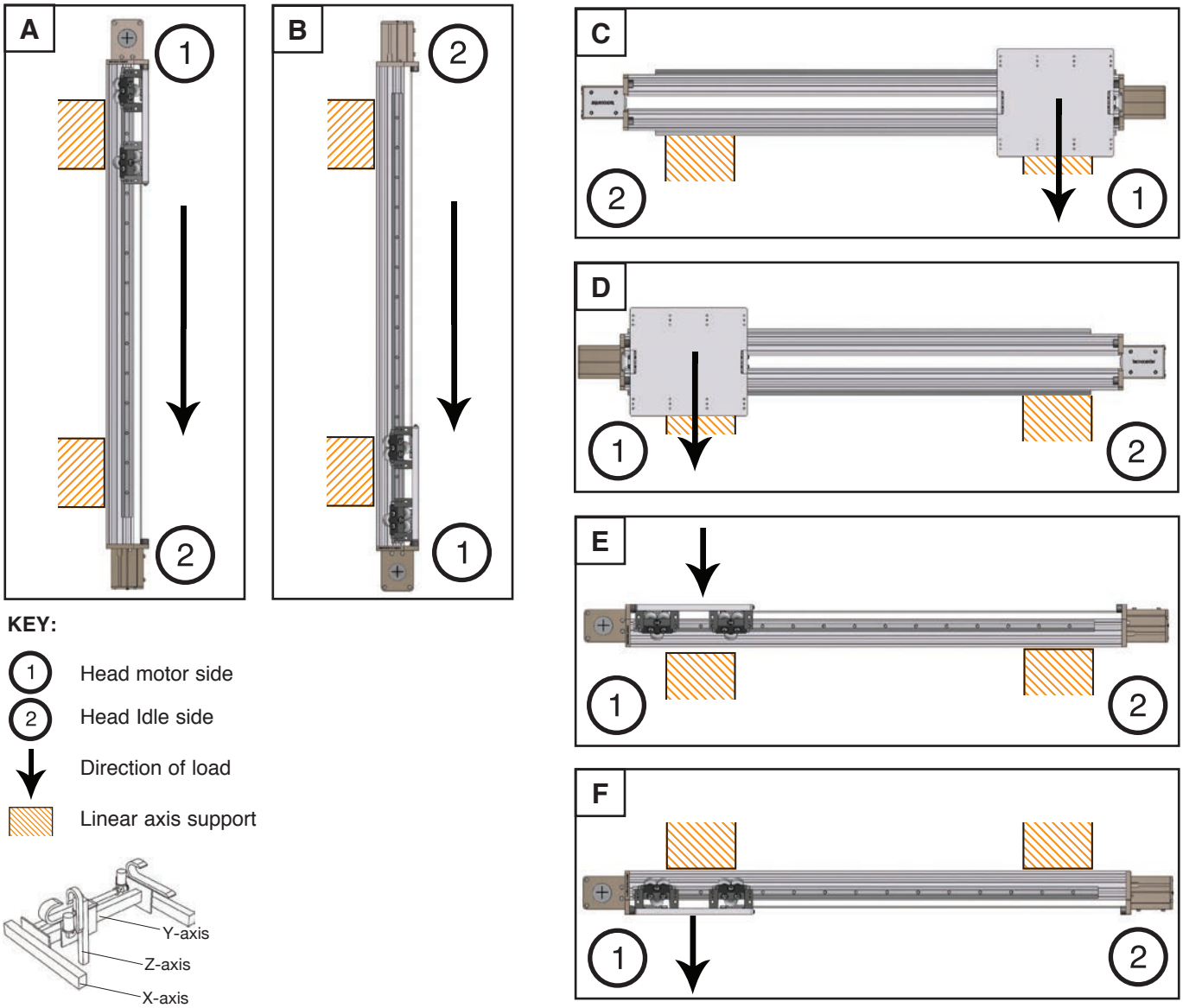
5 Pick and place system for packaging plant

6 Pick and place system for breadboards

7 Pick and place system for production plant

Assembly positions and load direction

For rollers profiles.



KEY:

1 Head motor side

2 Head Idle side

Direction of load

Linear axis support

Simplified code setting of the module

EXAMPLE		T	C	S	M	280	mm/mm/	...
SERIES	K= light M= compact closed section T= heavy Z= vertical omega belt							
HANDLING	C= belt CE= large belt V= ball screw T= trapezoidal screw N= idle L= linear motor							
SLIDE	RR / RQ /RP = guide rails for roller sl. Ø30 / Ø40 / Ø52 o Ø62 S= guide rails for caged balls roller slides H= guide rails for caged ball roller slides G= guide rails for cylindrical shaped rollers Y= guide rails for polyamide shaped rollers							
MACHINING PROFILE	M= profile with machined guide plane and rack plane							
PROFILE SIZE								
STROKE / LENGHT	"mm" = X-axis / Y-axis / Z-axis							
ACCESSORY CODES	Various accessory codes							

Order code setting

Required | **Complete for special versions** | Accessories

Order code																												
Example	Y	C	T	C	S	M	280	100	ATL	-	6000	8600	D	2	-	1200	FD 32	FX	K75	-	-	R	-	-	-	-	-	-	12, 40

Axis direction **Y**
X
Y
Z

See page 10 for assembly positions. Example C **C**

Unit type **T**
K
M
T
Z

Drive **C**
Belt **C**
Extra large belt **CE**
Ball screw **V**
Trapezoidal screw **T**
Not included **N**

Guide rails and roller slides **S**
Guide rails 28x11 **RR**
Guide rails 35x16 **RQ**
Guide rails 55x25 **RP**
Rectangular guide rails **RA**
Guide rails and caged ball roller slides **S**
Guide rails and compact caged ball roller slides **L**
Guide rails and ball roller slides without cage **H**
Round bar guide rails **G**
Sys guide rails **Y**

Profile machining **M**
Profile machined **M**
Profile not machined **-**

Profile size **280**
50
60
65
90
100H/50
100
180
170
200
220
280
360

Belt width or screw diameter **-**
Belt 10 ÷ 150 Ø Screw 16
20
25
32
40

Types of belt
Light belt **T**
Light belt normal series **AT**
Light belt: reinforced wobbler **ATL**

Type of screw: pitch / accuracy **-**
Pitch: 5 ÷ 10; 20 ÷ 25; 50
Accuracy class: T7; T5

Roller characteristic measurement **-**
Ø 63
Ø 75
Ø 30
Ø 40
Ø 52
Ø 62

Caged ball roller slides size 15 ÷ 35

Stroke **6000**

Total lenght **8600**

Standard carriage **-**
Drawing **D**
Short **C**
Long **L**
No plate (coupled unit) **X**
Not included **N**

Number of carriages **-**

Special carriage dimensions **-**

Carriage centre distance [mm] **-**

1° Flange gearbox entry side **FD32**
Right Ø **FDØ**
Left Ø **FSØ**
Drilled **FE**
Blind **FX**
Flange gearbox entry side **FSC - FDCØ**

FX 2° Opposite flange
FSØ Left Ø
FDØ Right Ø
FE Drilled
FX Blind

K50 - K75 - K100 - K150 - K200 Energy chain width **-**

M Micro-switch present **-**

P Cam-holder + cams **-**

R Gearbox assembly **-**

C Cylinder assembly **-**
C Ø32 ÷ Ø100

A/B Anti-drop brake device **-**
A Ø63 ÷ Ø125
B Ø63 ÷ Ø125

S Security lock-pin **-**
S Ø20
S Ø32

Connecting shaft **-**
A1/Centre distance length
A2/Centre distance length
A3/Centre distance length

Shaft torsional moment [Nm] **-**
20
35
70
100
190
300
420

Protection **-**
SF Bellows
LI Stainless steel band for MC series

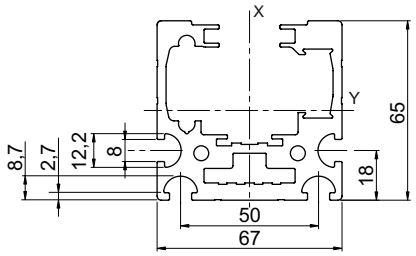
Additional accessories **-**

Additional accessories

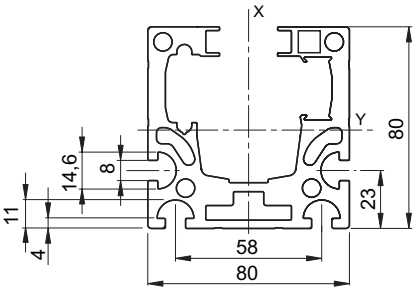
Available upon request

- Supply and assembly of cams and cam-holders for micro-switches, energy chains, etc.
- Assembly of optional accessories SUPPLIED BY THE CUSTOMER.
- Machining to specifications (drilling, milling) on the free surfaces of the plates or profile
- Customised applications (optional: structural inspections for special loads, Cartesian robots with three or more axes, linear units with several plates, etc.)
- Our technical dept. is at your complete disposal to examine the most suitable applications for your requirements.

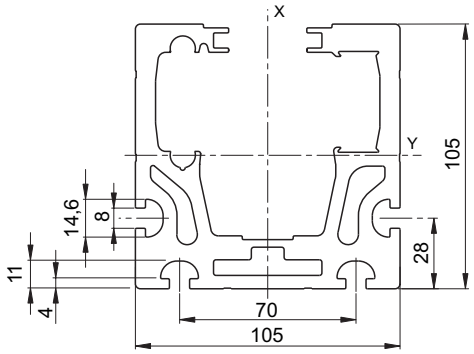
Profile specifications



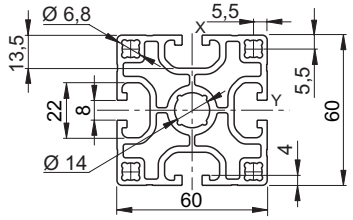
Profile	M 65x67	
Weight per metre	approx. 4.5	[kg/m]
Max. length	9	[m]
Moment of inertia IY	683,900	[mm4]
Moment of inertia IX	796,750	[mm4]
Module	MCR/L/H 65	



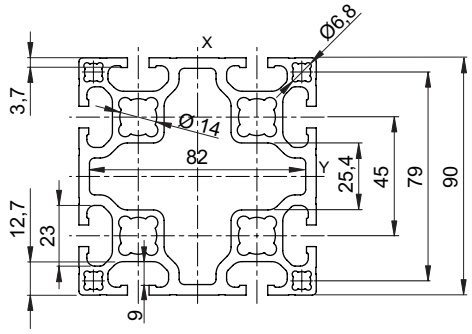
Profile	M 80x80	
Weight per metre	approx. 6.3	[kg/m]
Max. length	6	[m]
Moment of inertia IY	1,430,000	[mm4]
Moment of inertia IX	1,780,000	[mm4]
Module	MCR/S/H 80 - MVR/S/T 80	



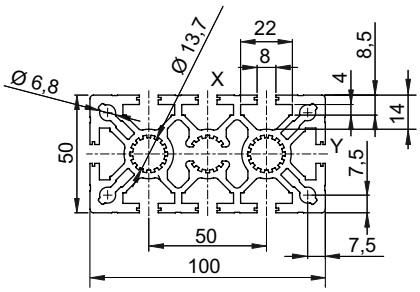
Profile	M 105x105	
Weight per metre	approx. 11	[kg/m]
Max. length	10.45	[m]
Moment of inertia IY	4,466,000	[mm4]
Moment of inertia IX	5,660,000	[mm4]
Module	MCR/S/H - MVR/S/T 105	

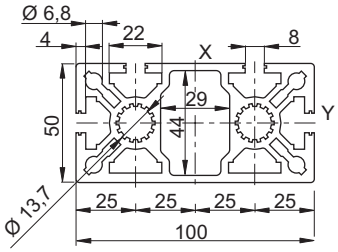


Profile (60x60)	F01-1	
Weight per metre	approx 3.6	[kg/m]
Max. length	6	[m]
Moment of inertia IY	466,600	[mm4]
Moment of inertia IX	466,600	[mm4]
Module	ZCG/L 60	

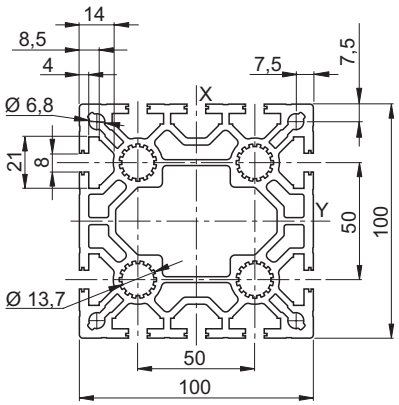


Profile (90x90)	E01-4	
Weight per metre	approx. 6	[kg/m]
Max. length	6	[m]
Moment of inertia IY	2,027,000	[mm4]
Moment of inertia IX	2,027,000	[mm4]
Module	ZCG - ZCL - ZCRR 90	

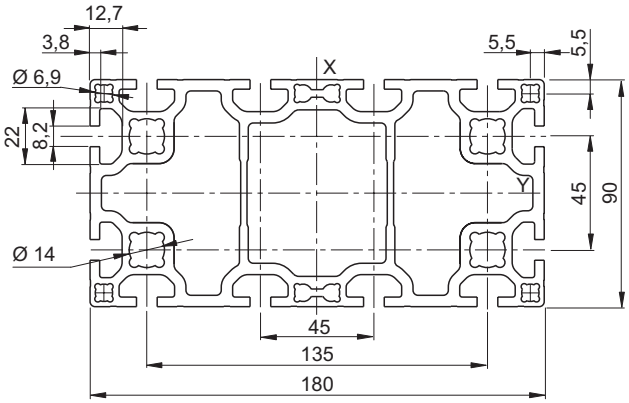




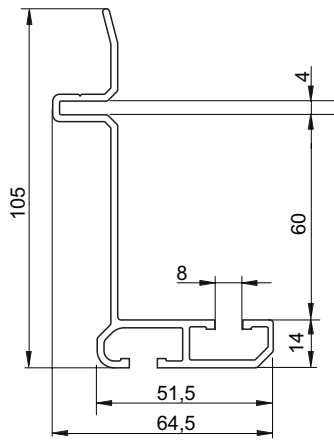
Profile (50x100)	MA 1-2	MA 1-4	
Weight per metre	approx. 5.3	5.2	[kg/m]
Max. length	6	6	[m]
Moment of inertia IY	502,800	543,100	[mm4]
Moment of inertia IX	1,986,600	2,036,700	[mm4]
Module	ZCR/L 100H	TCG/TCS/H 100	



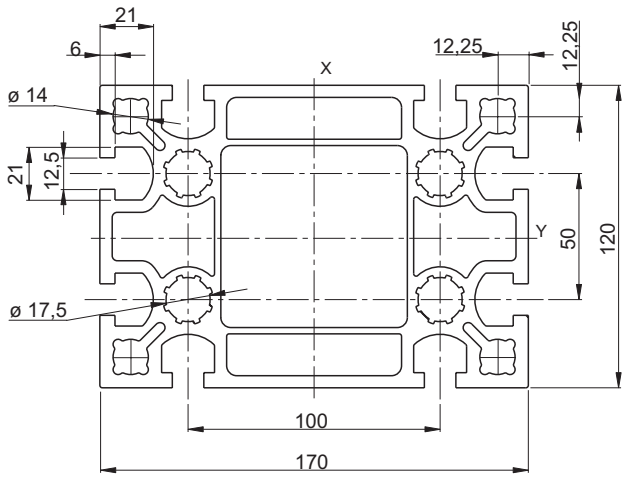
Profile (100x100)	MA 1-5	
Weight per metre	approx. 9.5	[kg/m]
Max. length	6	[m]
Moment of inertia IY	3,650,000	[mm4]
Moment of inertia IX	3,800,000	[mm4]
Module	ZCR/L 100	



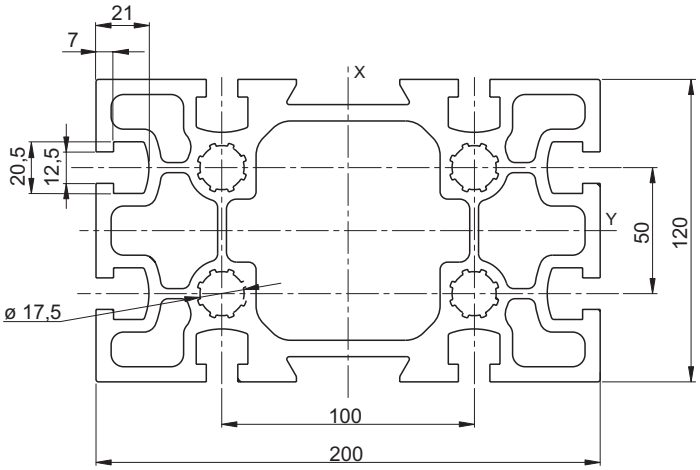
Profile (90x180)	E01-5	
Weight per metre	approx. 12.4	[kg/m]
Max. length	8	[m]
Moment of inertia IY	4,420,000	[mm4]
Moment of inertia IX	15,180,000	[mm4]
Module	TCR/G/S/H/ 180	



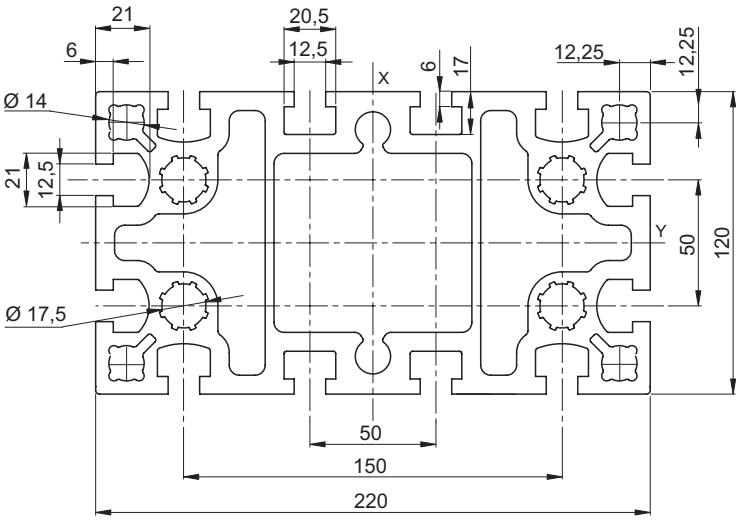
7400568 energy chain support profile		
Weight	1.5	kg/m
Available lenght	6	m



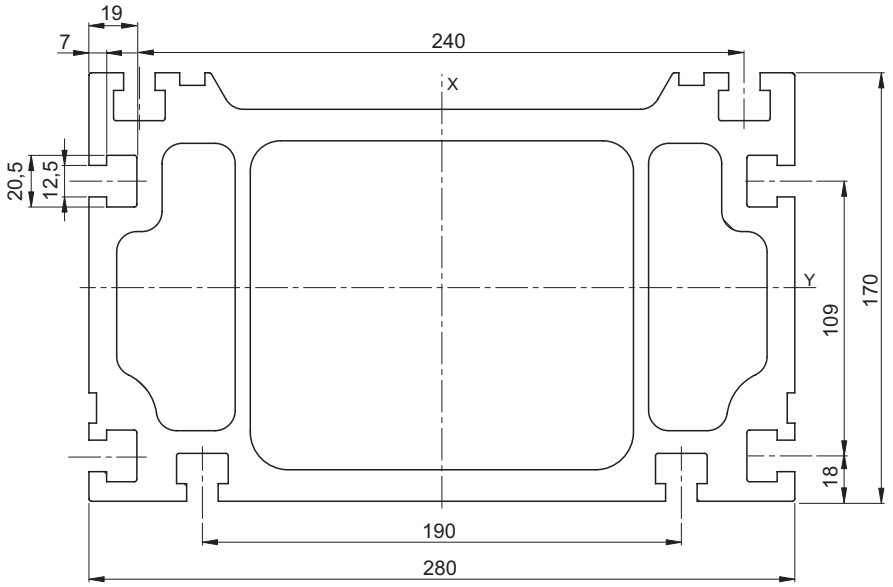
Statyca (120x170)	**Code 202.1753**	
Weight per metre	approx. 17	[kg/m]
Max. length	6	[m]
Moment of inertia IY	10,200,000	[mm^4]
Moment of inertia IX	20,360,000	[mm^4]
Module	TCR/S/H 170 - ZCR/L 170	



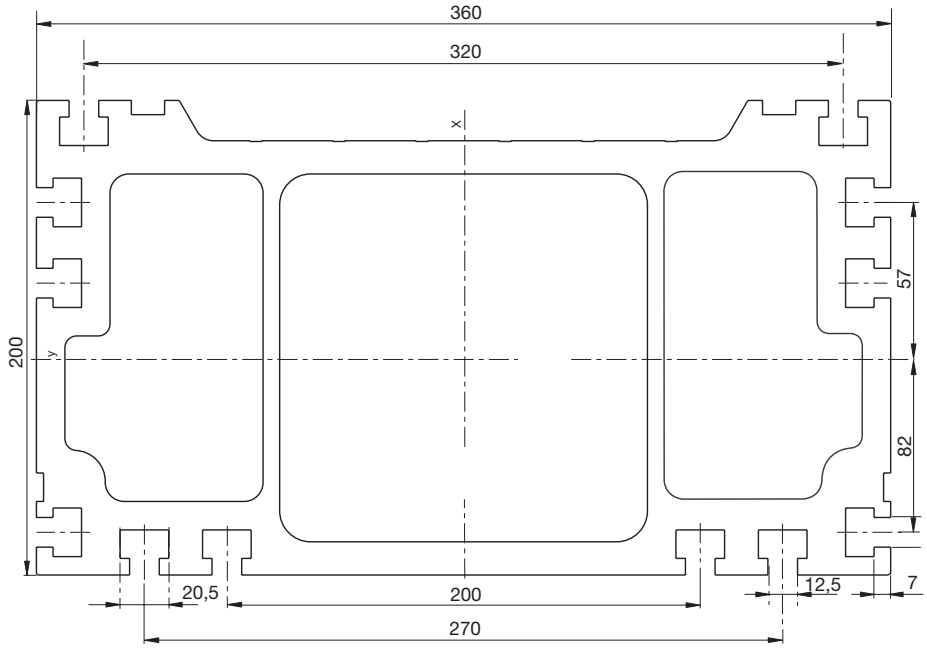
Valyda (120x200)	**Code 202.1146**	
Weight per metre	approx. 21	[kg/m]
Max. length	12	[m]
Moment of inertia IY	12,900,000	[mm^4]
Moment of inertia IX	32,900,000	[mm^4]
Module	TCR/S/H 200	
Anodised up to	9	[m]



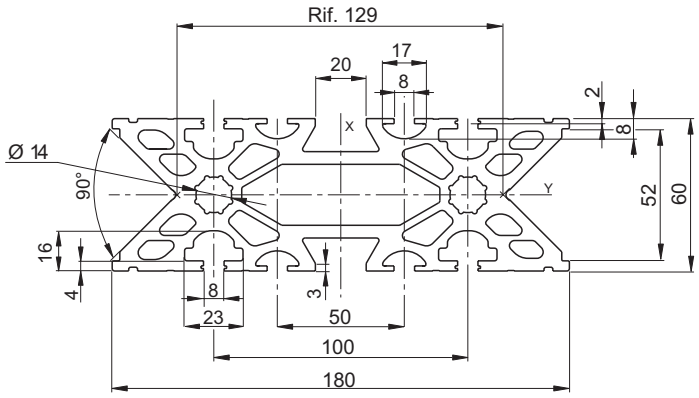
Logyca (120x220)	**Code 202.2184**	
Weight per metre	approx. 25	[kg/m]
Max. lenght	12	[m]
Moment of inertia IY	15,650,000	[mm^4]
Moment of inertia IX	46,550,000	[mm^4]
Module	TCR/S/H 220-ZCR/L/ 220	
Anodizzato fino a	lungh. 9	[m]



Pratyca (170x280)	Code 202.1147	
Weight per metre	approx. 40	[kg/m]
Max. length	12	[m]
Moment of inertia IY	50,288,000	[mm⁴]
Moment of inertia IX	134,103,000	[mm⁴]
Module	TCR/RP/S/H 280	
Usually not anodised		



Solyda (200x360)	Code 202.0342	
Weight per metre	approx. 60	[kg/m]
Max. length	12	[m]
Moment of inertia IY	318,687,000	[mm⁴]
Moment of inertia IX	105,533,000	[mm⁴]
Module	TCRP/S/H 360	
Usually not anodised		



SYS 1-G	Code 302.0001	
Weight per metre	approx. 12	[kg/m]
Max. lenght	7.5	[m]
Moment of inertia IY	1,600,000	[mm⁴]
Moment of inertia IX	12,350,000	[mm⁴]
Module	ZCY180	
*Holes for M16 thread and for PVS connecting elements		

Series M Modules with belt drive

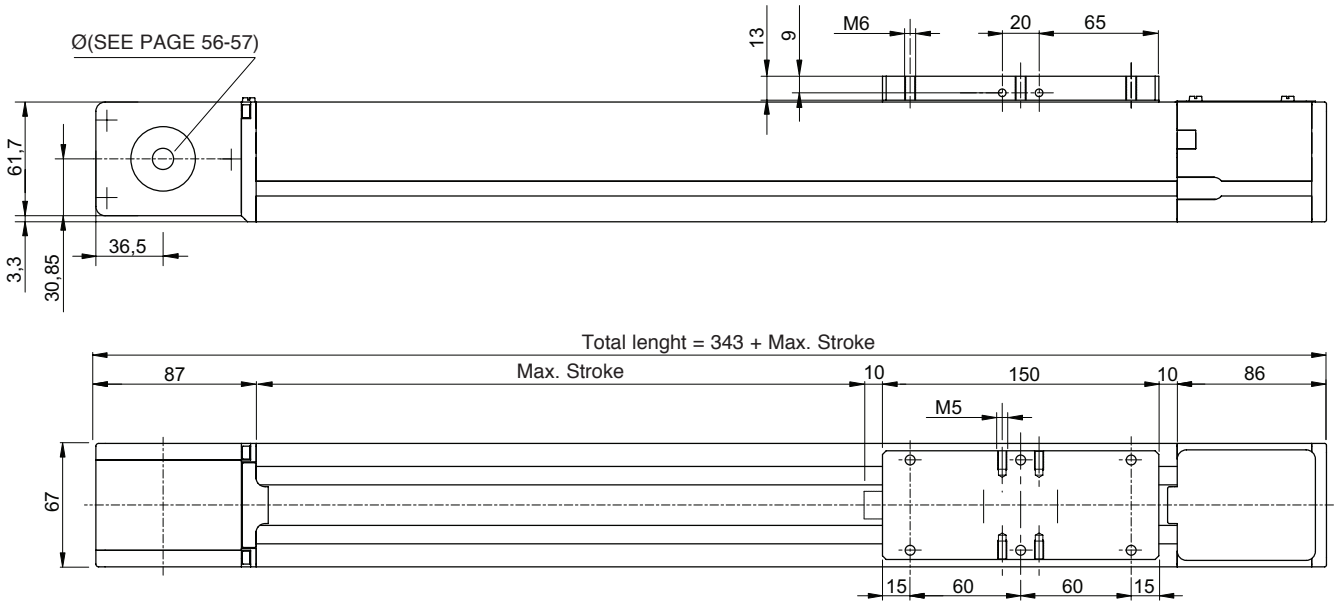
MCR 65

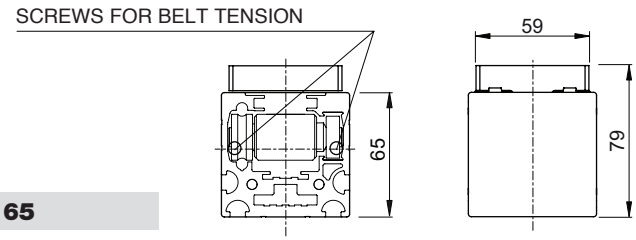
HARDENED GUIDE RAILS AND SHAPED ROLLERS

Registered model

Option: lighter version with pulley seats integrated within the profile

Accessories: see page 11



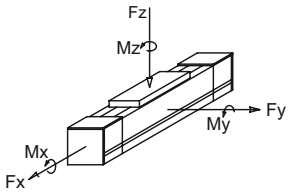


Performances	MCR 65	
Max. stroke	5,830	[mm]
Max. speed	4	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0,1	[mm]
Loadless torque	-	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCR 65	45	94	34	1,180	670	1,000

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data		
Belt	32AT05	
Slide	Rollers: 4 Ø 24 - 4 Ø 22	[mm]
Load bearing profile	65x67	(see page 12)
Pulley Ø	50.93	[mm]
Linear displacement per revolution	160	[mm]

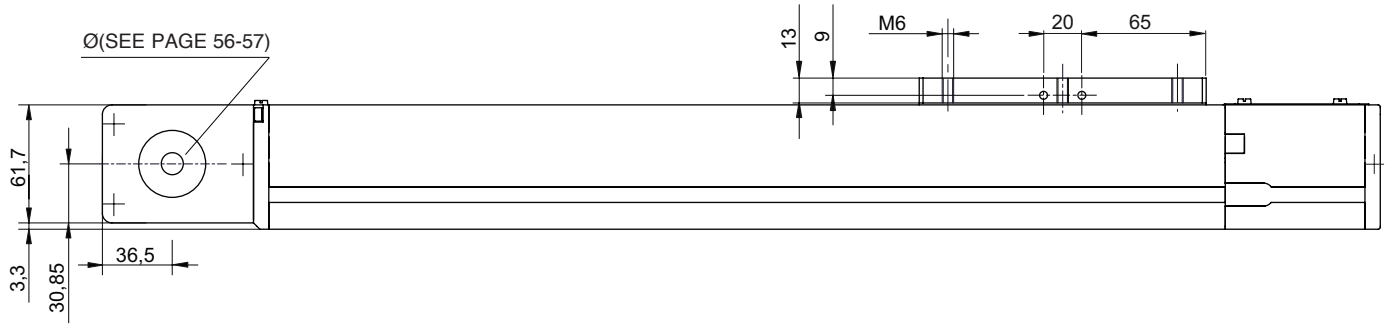
Weights		
Inertia of the pulley	-	[kgm^2]
Belt weight	0.22	[kg/m]
Carriage weight	1	[kg]
Base module (stroke=0)	M_{base}=4.4	[kg]
1,000 mm profile	q=5.4	[kg]

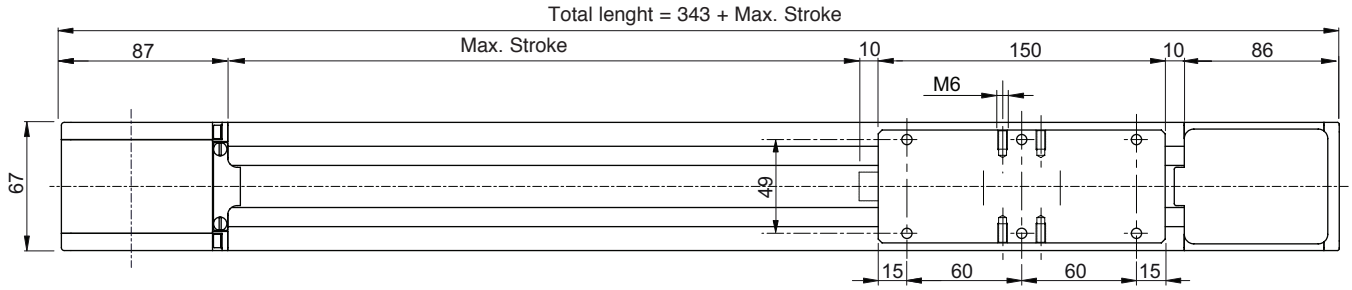
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

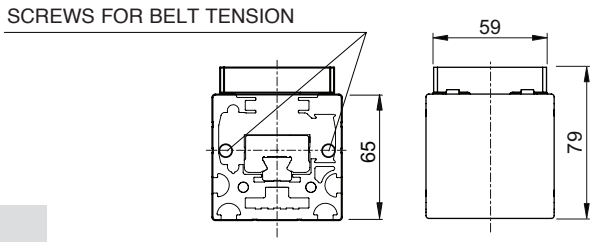
MCS 65 - MCH 65

Registered model

Option: lighter version with pulley seats integrated within the profile
Accessories: see page 11





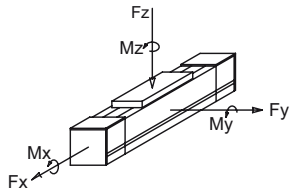


Performances	MCS 65	MCH 65	
Max. stroke	7,830	7,830	[mm]
Max. speed	5	3	[m/s]
Max. acceleration	50	30	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	-	-	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]	F_{zB}[N]
MCH 65	19	120	120	1,180	1,960	1,960	1,960
MCS 65	16	140	103	1,180	2,094	3,740	2,320

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data		
Belt	32AT05	
Slide	2 caged balls roller slides	15[mm]
Load bearing profile	65x67	(see page 12)
Pulley Ø	50.93	[mm]
Linear displacement per revolution	160	[mm]

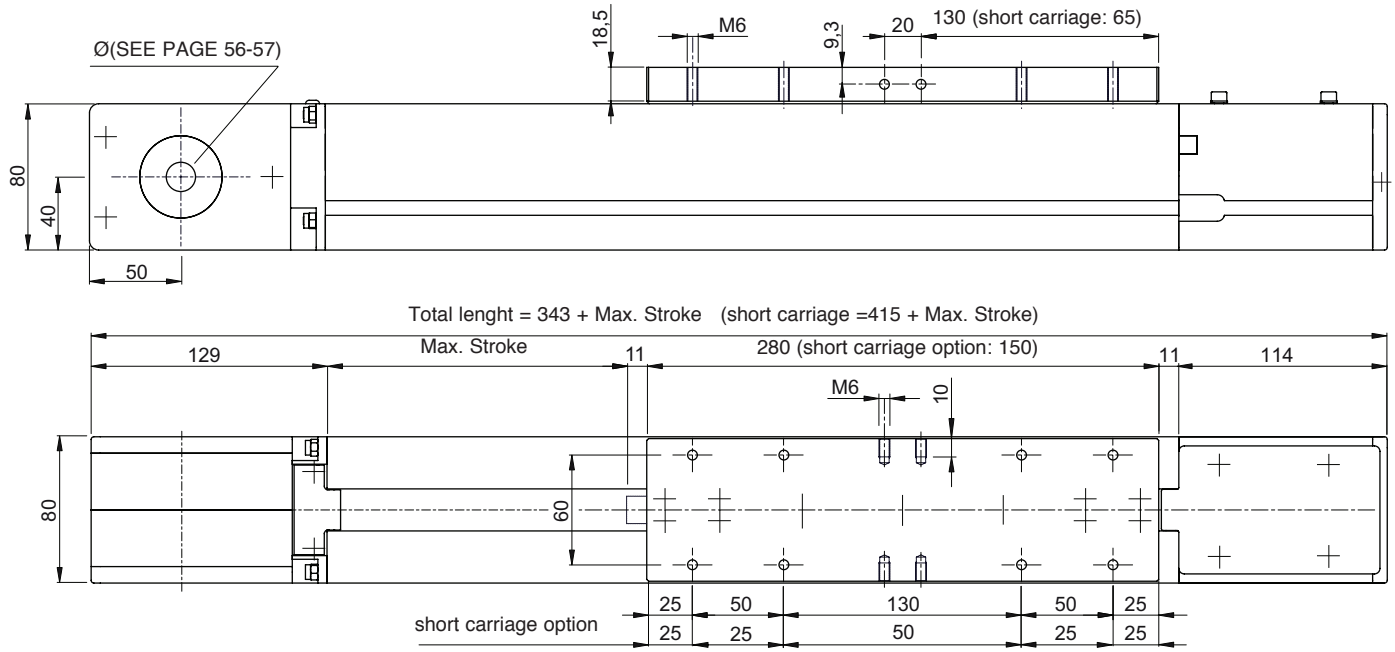
Weights		
Inertia of the pulley	-	[kgm^2]
Belt weight	0.22	[kg/m]
Carriage weight	1,1	[kg]
Base module (stroke=0)	M_{base}=4.2	[kg]
1,000 mm profile	q=6.2	[kg]

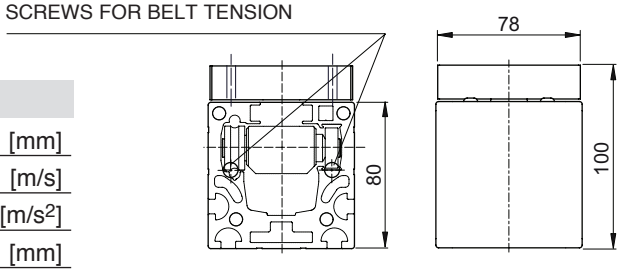
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

MCR 80

Registered model

Option: version with additional belt protection (see page 66)
Option: short carriage version - code C
Accessories: see page 11





Performances	MCR 80	
Max. stroke	5,700	[mm]
Max. speed	5	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	0.7	[Nm]

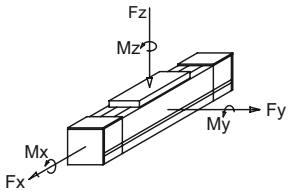
Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCR 80	51	200	80	2,150	850	1,400

Suggested working load conditions short carriage option

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCR 80...C	51	100	40	2,150	850	1,400

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data		
Belt	32AT10	
Slide	Rollers: 4 Ø 24 - 4 Ø 22 [mm]	
Load bearing profile	80x80	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per revolution	220	[mm]

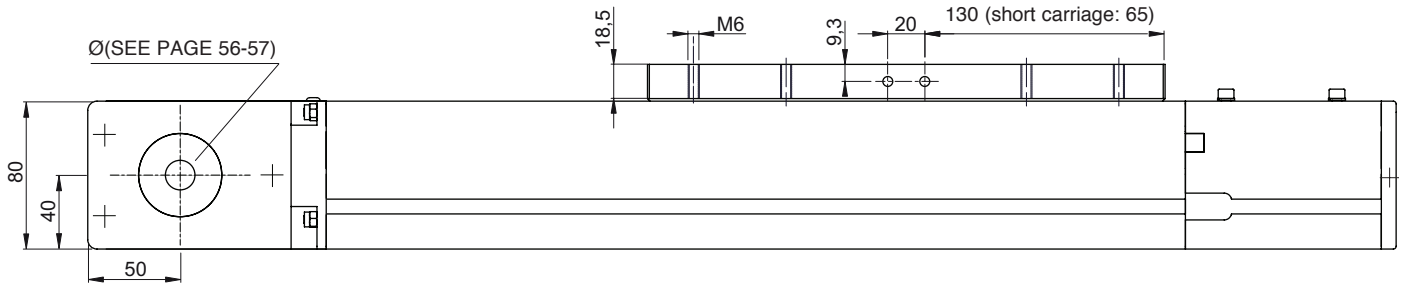
Weights		
Inertia of the pulley	0.0010	[kgm^2]
Belt weight	0.38	[kg/m]
Carriage weight	2	[kg]
Base module (stroke=0)	M_{base}=8	[kg]
1,000 mm profile	q=7	[kg]

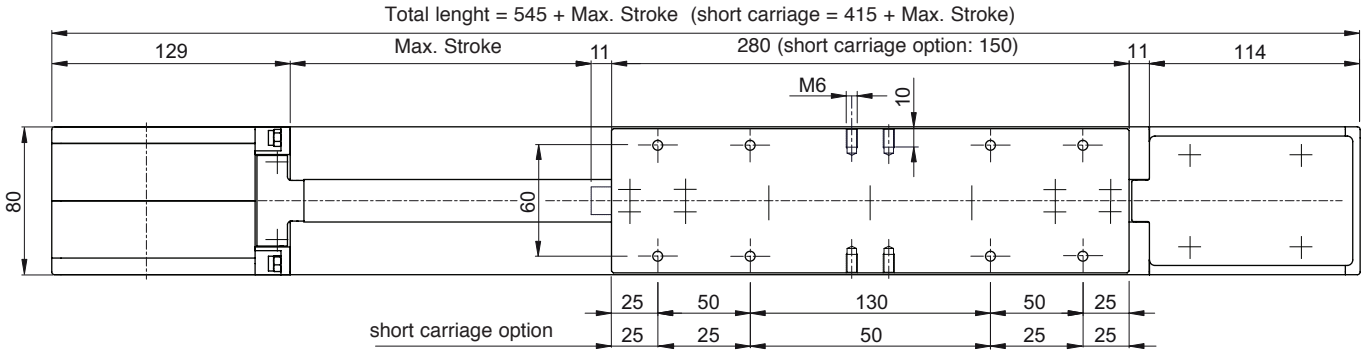
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

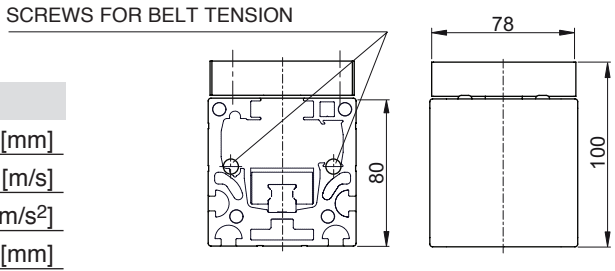
MCS 80 e MCH 80

Registered model

Option: version with additional belt protection (see page 66)
Option: short carriage version - code C
Accessories: see page 11







Performances	MCS 80	MCH 80	
Max. stroke	5,700	5,700	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	40	40	[m/s^2]
Repositioning accuracy	± 0,1	± 0,1	[mm]
Loadless torque	0.9	0.9	[Nm]

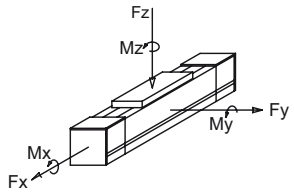
Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCS 80	52	400	400	2,150	4,200	4,200
MCH 80	30	290	290	2,150	2,900	2,900

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCS 80...C	16.5	15	15	2,150	2,100	2,100
MCH 80...C	14	15	12	2,150	1,450	1,450

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data	MCS80 - MCH80	
Belt	32AT10	
Slide	2 caged ball roller slides size 15*	
Load bearing profile	80x80	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per revolution	220	[mm]
* Short carriage option	1 pad	

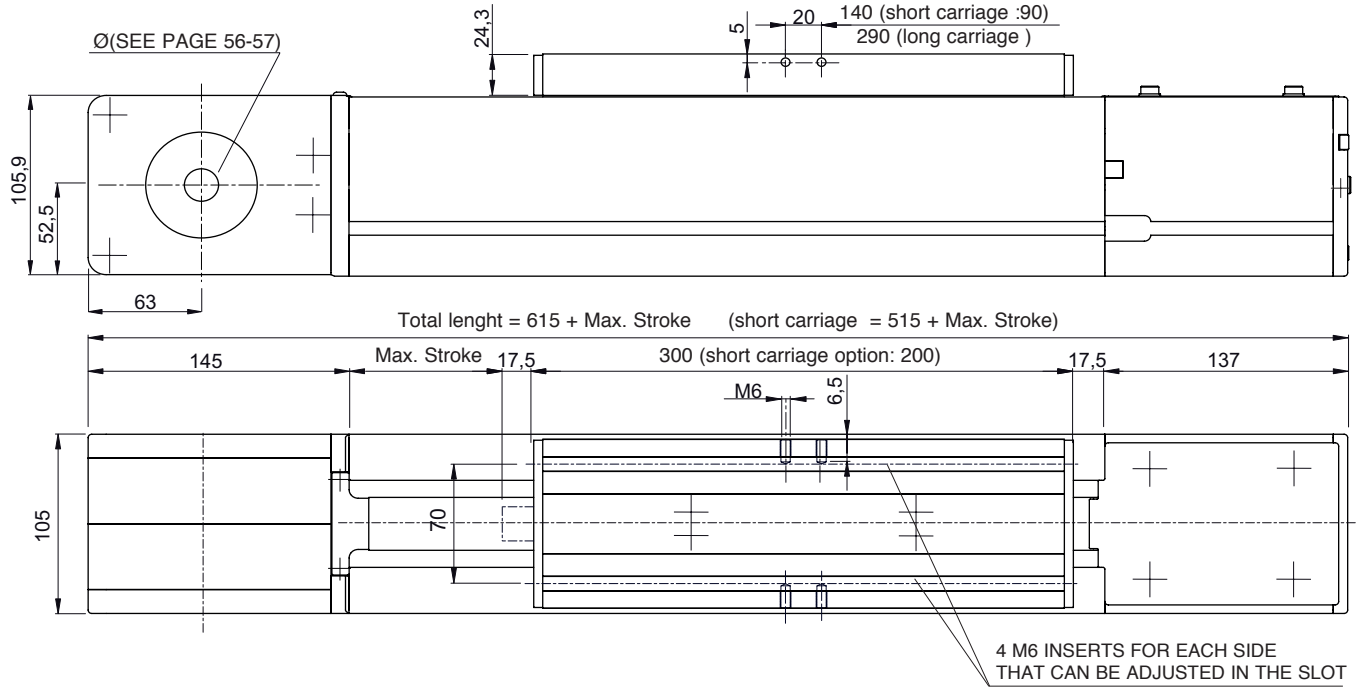
Weights	MCS80 - MCH80	
Inertia of the pulley	0.0010	[kgm^2]
Belt weight	0.38	[kg/m]
Carriage weight	2.6	[kg]
Base module (stroke=0)	M_{base}=9	[kg]
1,000 mm profile	q=8.2	[kg]

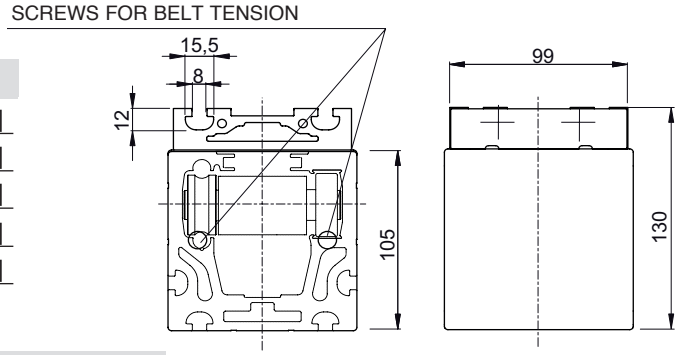
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

MCR 105

Registered model

Option: version with additional belt protection (see page 66)
*Option: short carriage version - (code C) or long carriage (code L)
Accessories: see page 11





Performances	MCR 105	
Max. stroke	10,100	[mm]
Max. speed	5	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	1.2	[Nm]

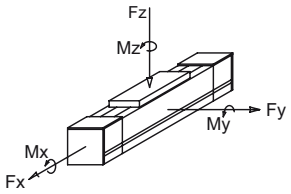
Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCR 105	185	580	220	3,300	1,500	2,950

Suggested working load conditions short carriage option

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCR 105...C	185	330	130	3,300	1,450	2,950

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data		
Belt	40AT10	
Slide	Rollers: 4 Ø 37 - 4 Ø 35	[mm]
Load bearing profile	105x105	(see page 12)
Pulley Ø	92.31	[mm]
Linear displacement per revolution	290	[mm]

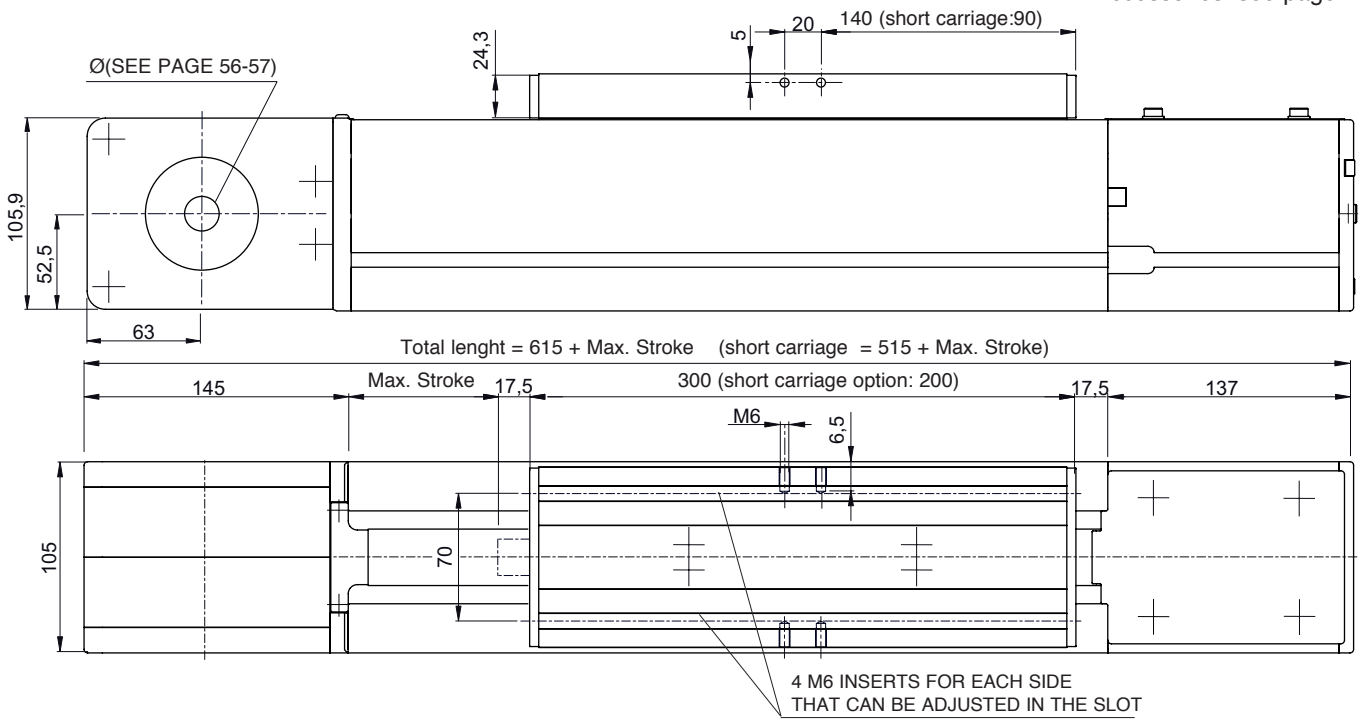
Weights		
Inertia of the pulley	0.0037	[kgm^2]
Belt weight	0.47	[kg/m]
Carriage weight	3.5	[kg]
Base module (stroke=0)	M_{base}=16.5	[kg]
1,000 mm profile	q=13	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

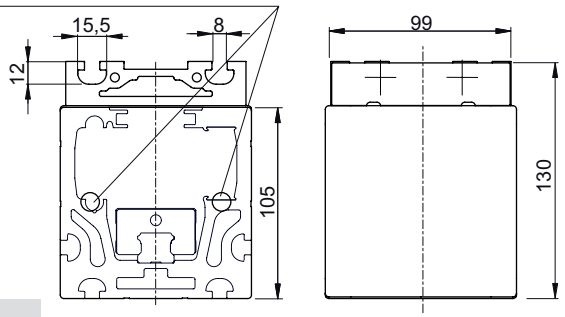
MCS 105 e MCH 105

Registered model

Option: version with additional belt protection (see page 66)
*Option: short carriage version - (code C)
Accessories: see page 11



SCREWS FOR BELT TENSION



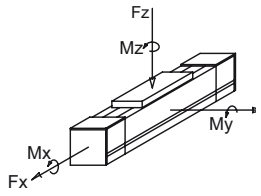
Performances	MCS 105	MCH 105	
Max. stroke	10,100	10,100	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	1.5	1.5	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCS 105	156	800	800	3,300	9,550	9,550
MCH 105	116	600	600	3,300	6,030	6,030

Suggested working load conditions short carriage option

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCS 105...C	51	52	52	3,300	4,777	4,777
MCH 105...C	36	30	30	3,300	3,018	3,018



Fx= Max belt strength

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Constuctive data		
Belt	40AT10	
Slide	2 caged ball roller slides size 20*	
Load bearing profile	105x105 (see page 12)	
Pulley Ø	92.31	[mm]
Linear displacement per revolution	290	[mm]
* Short carriage option	1 pad	

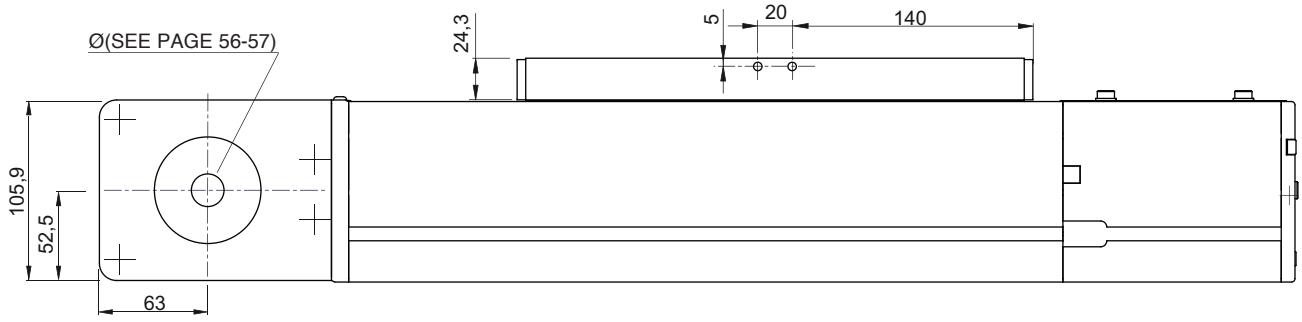
Weights		
Inertia of the pulley	0.0037	[kgm^2]
Belt weight	0.47	[kg/m]
Carriage weight	4.5	[kg]
Base module (stroke=0)	M_{base}=18	[kg]
1,000 mm profile	q=14.3	[kg]

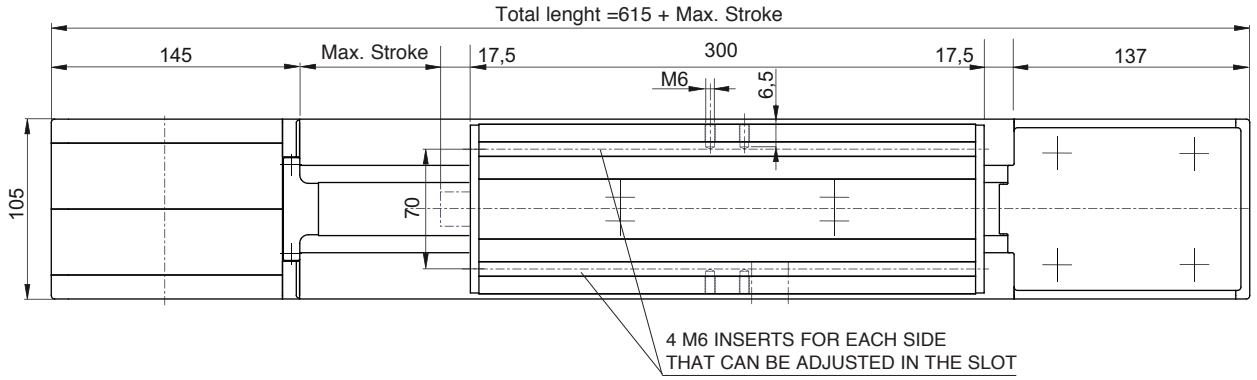
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

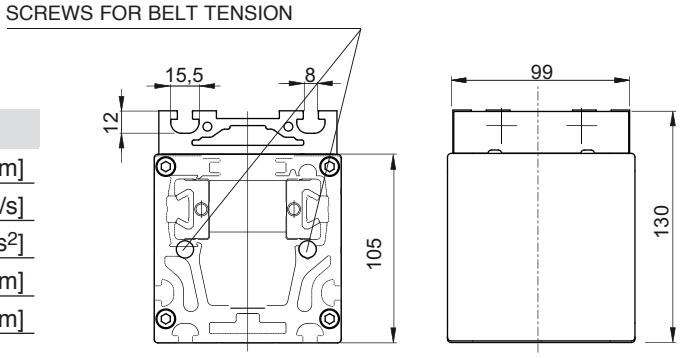
MCHH 105

Registered model

Accessories: see page 11



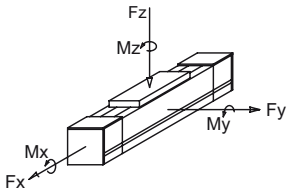




Performances	MCHH 105	
Max. stroke	7,400	[mm]
Max. speed	5	[m/s]
Max. acceleration	50	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	2.2	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MCHH 105	210	1.033	700	3,300	7,200	6,210



The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Fx= Max belt strength

Constructive data		
Belt	40ATL10	
Slide	4 caged ball roller slides size 15	
Load bearing profile	105x105	(see page 12)
Pulley Ø	92.31	[mm]
Linear displacement per revolution	290	[mm]

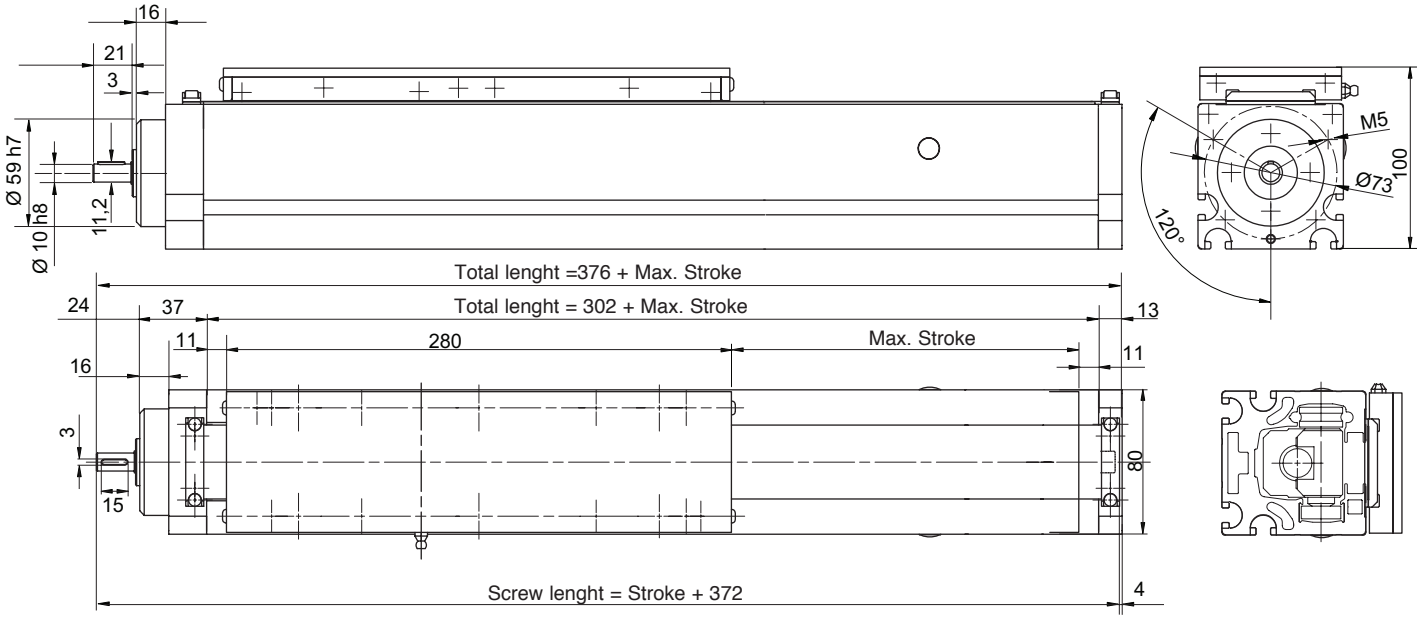
Weights		
Inertia of the pulley	0.0037	[kgm^2]
Belt weight	0.47	[kg/m]
Carriage weight	4.5	[kg]
Base module (stroke=0)	M_{base}=18	[kg]
1,000 mm di profile	q=14	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

Modules with screw drive

MVR 80 - MTR 80

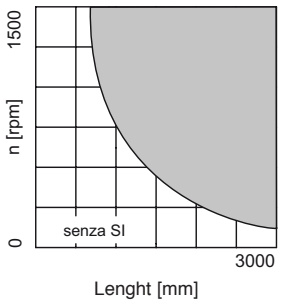
HARDENED GUIDES
WITH CYLINDRICAL SHAPED ROLLERS - TRAPEZOIDAL BALL SCREW



Code

M	T	R					

V = Ball screw
T = Trapezoidal screw
R = Rollers
Max. Stroke [mm]
Module total lenght [mm]
Type of carriage N/D
Screw pitch 5-10
Pedestal bearings SI



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked inside the broken line is not recommended.

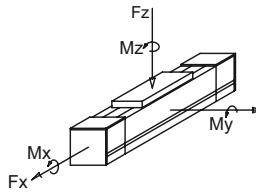
Performances	**MVR 80**		**MTR 80**	
Max. stroke	2,500		3,000	[mm]
Max. speed Pitch 5	0.15	Pitch 4	0.10	[m/s]
Pitch 10	0.30	Pitch 8	0.20	[m/s]
Pitch 16	0.50			[m/s]
Max. acceleration	5		2	[m/s^2]
Repositioning accuracy	± 0,05		± 0,20	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MVR 80	51	200	80	*1,600	850	1,400
MTR 80	51	200	80	*2,000	850	1,400

The values shown refer to maximum performance with each force acting individually. The dynamic data shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.

(*) With a pitch of 5 mm



Fx= Max belt strength

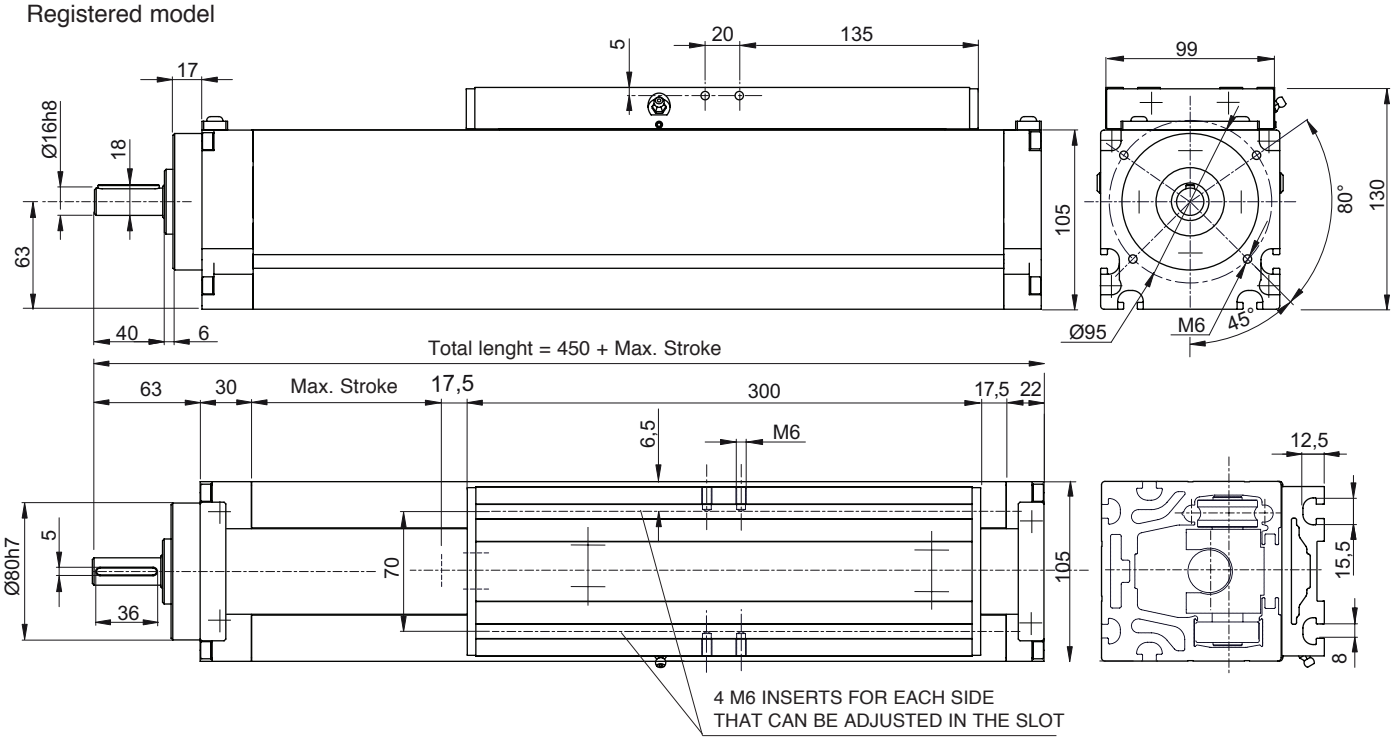
Constructive data		
Slide	Rollers: 4 Ø24 - 4 Ø22	[mm]
Beam	80x80 (see page 12)	
Ø screw	16	[mm]
Lenght of the screw	367+$_{max}$stroke	[mm]

Weights		
Inertia of the worm	0.0003 • L. screw(m)	[kgm^2]
Carriage weight	2.5 c.a.	[kg]
Base module (stroke=0)	M_{base}= 5.5 approx.	[kg]
1,000 mm profile	q=8 approx.	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** (stroke$_{max}$ in mm)

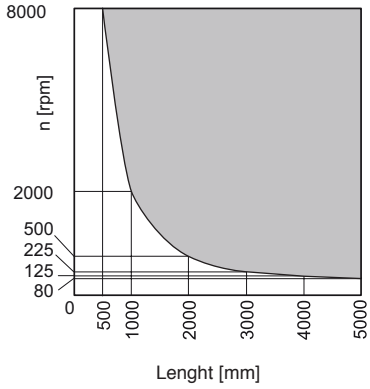
MVR 105 e MTR 105

Registered model



Code	M	T	R					
V = Ball screw T = Trapezoidal screw								
R = Rollers								
Max. stroke				[mm]				
Module total lenght					[mm]			
Type of carriage						N/D		
Screw pitch							5-10-25-50	
Pedestal bearings								SI

ball screw



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked inside the broken line is not recommended.

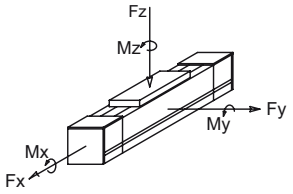
Performances			**MVR 105**	**MTR 105**	
Max. stroke	Pitch 5 -10 = 4550		Pitch 25 = 5,150		[mm]
Max. speed	Pitch 5	[mm]	0.15	0.075	[m/s]
	Pitch 10	[mm]	0.30	0.15	[m/s]
	Pitch 25	[mm]	0.75	0.37	[m/s]
Max. acceleration			5	2	[m/s^2]
Repositioning accuracy			± 0.05	± 0.2	[mm]

Suggested working load conditions

Module	**M_x[Nm]**	**M_y[Nm]**	**M_z[Nm]**	**F_x[N]**	**F_y[N]**	**F_z[N]**
MVR 105	185	580	220	*2,000	1,500	2,950
MTR 105	185	580	220	*3,000	1,500	2,950

The values shown refer to maximum performance with each force acting individually. The dynamic data shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.

(*) With a pitch of 5 mm

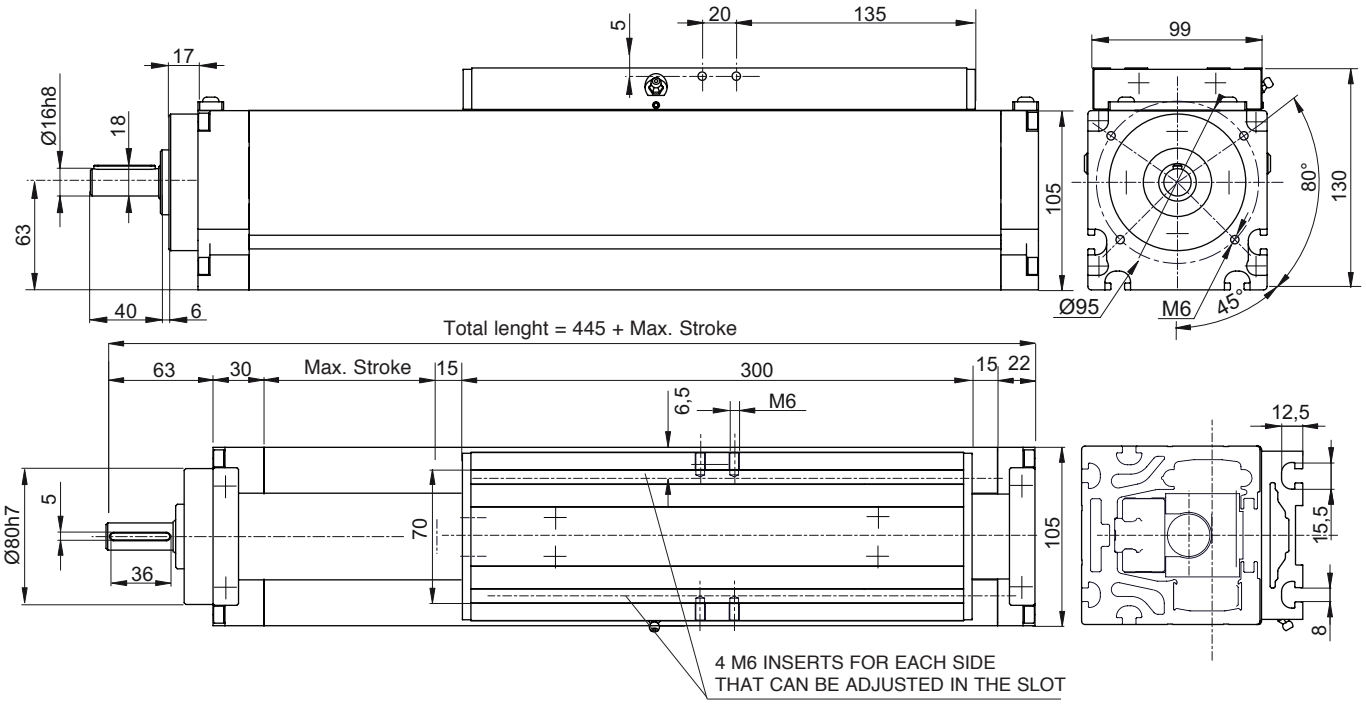


Fx= Max belt strength

Constructive data		
Slide	Rollers: 4 Ø 37 - 4 Ø 35	[mm]
Beam	105x105	(see page 12)
Ø screw	25	[mm]
Lenght of the screw	440+$_{max}$stroke	[mm]

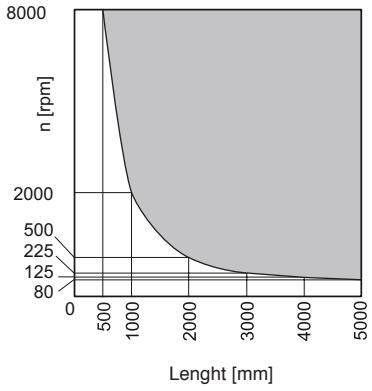
Weights		
Inertia of the worm	0.0003 • L. screw(m)	[kgm^2]
Carriage weight	4 approx.	[kg]
Base module (stroke=0)	M_{base}=11	[kg]
1,000 mm profile	q=17.2 approx.	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** (stroke$_{max}$ in mm)



Code	M	V	L					
V = Ball screw								
S = Caged ball roller slides H = Ball roller slides								
Max. stroke				[mm]				
Module total lenght					[mm]			
Type of carriage						N/D		
Screw pitch							5-10-25-50	
Pedestal bearings								SI

ball screw



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked inside the broken line is not recommended.

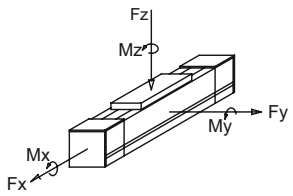
Performances			**MVS 105**	**MVH 105**	
Max. stroke	Pitch 5 -10 = 4,550		Pitch 25 = 5,150		[mm]
Max. speed	Pitch 5	[mm]	0.15	0.15	[m/s]
	Pitch 10	[mm]	0.30	0.30	[m/s]
	Pitch 25	[mm]	0.75	0.75	[m/s]
Max. acceleration			5	5	[m/s^2]
Repositioning accuracy			± 0.05	± 0.05	[mm]

Suggested working load conditions

Module	**M_x[Nm]**	**M_y[Nm]**	**M_z[Nm]**	**F_x[N]**	**F_y[N]**	**F_z[N]**
MVS 105	156	800	800	3,000(*)	9,550	9,550
MVH 105	116	600	600	3,000(*)	6,030	6,030

The values shown refer to maximum performance with each force acting individually. The dynamic data shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.

(*) With a pitch of 5 mm



Fx= Max belt strength

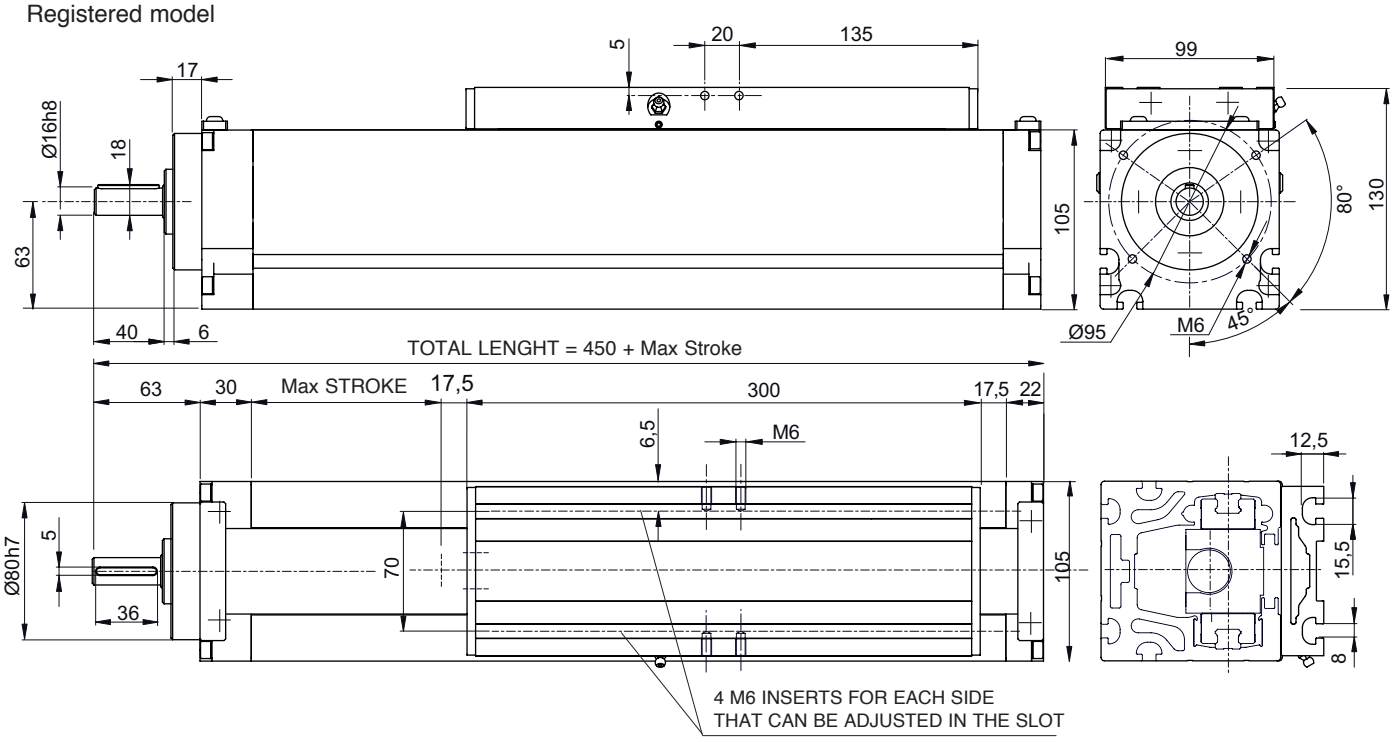
Constructive data		
Slide	2 caged ball roller slides size 20	
Beam	105x105 (see page 12)	
Ø screw	25	[mm]
Lenght of the screw	440+$_{max}$stroke	[mm]

Weights		
Inertia of the worm	0.0003 • L. screw(m)	[kgm^2]
Carriage weight	4 approx.	[kg]
Base module (stroke=0)	M_{base}=12	[kg]
1,000 mm profile	q=17.2 approx.	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** (stroke$_{max}$ in mm)

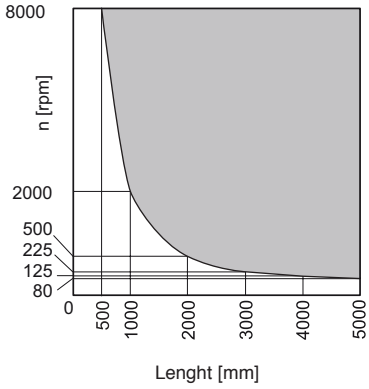
MVHH 105

Registered model



Code	M	V	HH					
V=ball screw								
H=ball roller slides								
Max Stroke				[mm]				
Module total lenght					[mm]			
Type of carriage						N/D		
Screw pitch							5-10-25	
Pedestal bearings								SI

ball screw



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked inside the broken line is not recommended.

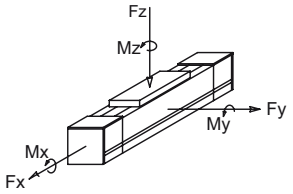
Performances		**MVHH 105**	
Max Stroke	Pitch 5 -10 = 4550 Pitch 25 = 5150		[mm]
Max Speed	Pitch 5 [mm]	0,15	[m/s]
	Pitch 10 [mm]	0,30	[m/s]
	Pitch 25 [mm]	0,75	[m/s]
Max acceleration		5	[m/s^2]
Repositioning accuracy		± 0,05	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
MVHH 105	185	500	500	*3.000	6.000	6.000

The values shown refer to maximum performance with each force acting individually. The dynamic data shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.

(*) With a pitch of 5 mm

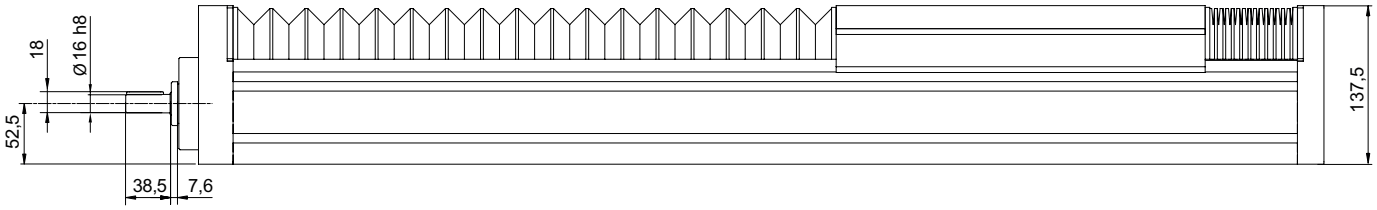


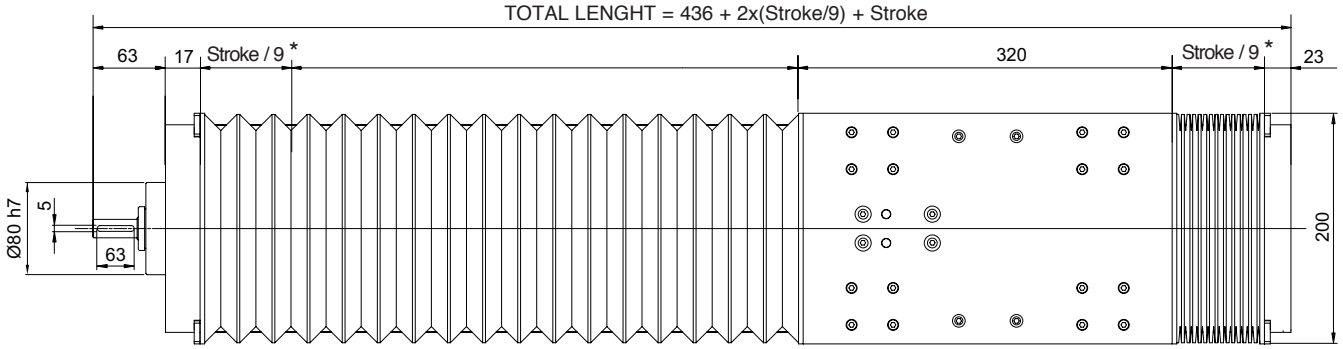
Fx= Max belt strength

Constructive data		
Slide	4 caged ball roller slides size 15	
Beam	105x105 (see page 12)	
Ø screw	25	[mm]
Lenght of the screw	440+stroke$_{max}$	[mm]

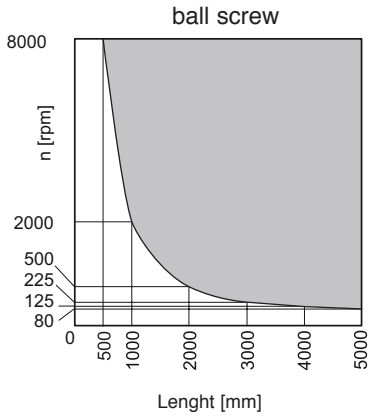
Weights		
Inertia of the worm	0,0003 • L. screw(m)	[kgm^2]
Carriage weight	4 c.a.	[kg]
Base module (stroke=0)	M_{base}=13	[kg]
1,000 mm profile	q=17,5 approx.	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** (stroke$_{max}$ in mm)

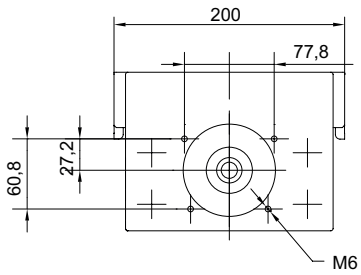


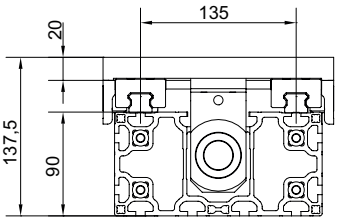


*valore indicativo



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked insidethe broken line is not recommended.





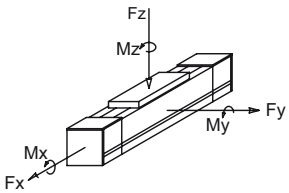
Performances			**TVH 180**	
Max Stroke	Pitch 5 -10 = 4550	Pitch 25 = 5150		[mm]
Max Speed	Pitch 5 [mm]		0,15	[m/s]
	Pitch 10 [mm]		0,30	[m/s]
	Pitch 25 [mm]		0,75	[m/s]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TVH 180	600	850	850	*3.000	9.200	9.200

The values shown refer to maximum performance with each force acting individually. The dynamic data shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.

(*) With a pitch of 5 mm

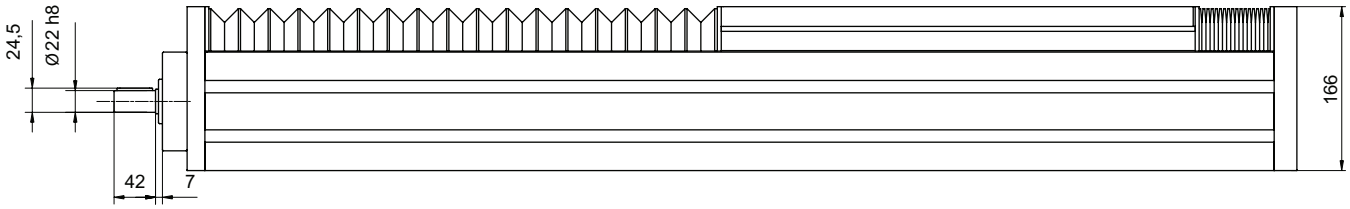


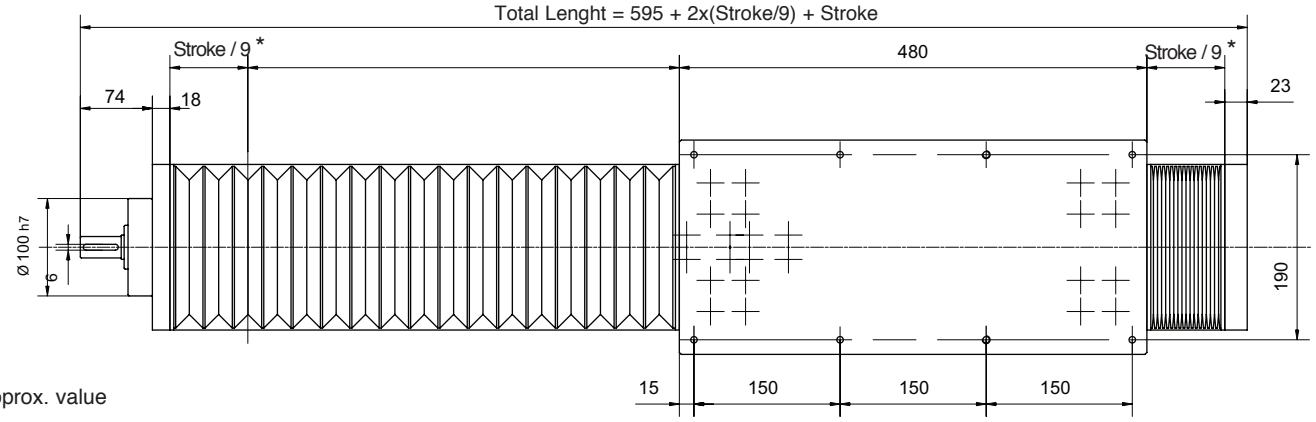
Fx= Max belt strength

Constructive data		
Slide	4 caged ball roller slides size 20	
Beam	E01-5	(see page 13)
Ø screw	25	[mm]
Bellow	heat-sealed, plastic	

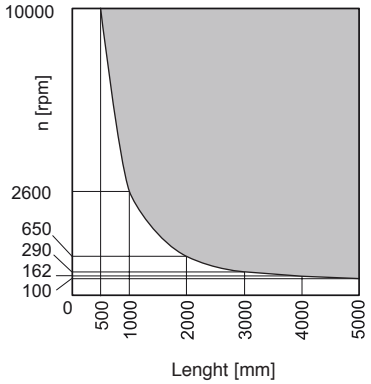
Weights		
Inertia of the worm	0,0003 • L. screw(m)	[kgm^2]
Carriage weight	7	[kg]
Base module (stroke=0)	M_{base}= 20	[kg]
1,000 mm profile	q= 20	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

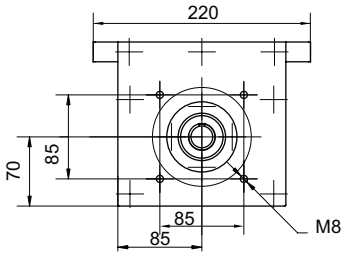


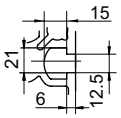


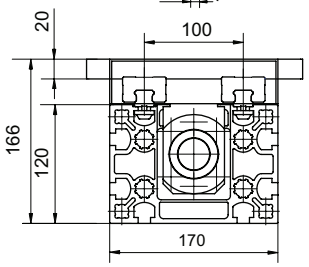
*approx. value



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked inside
the broken line is not recommended.





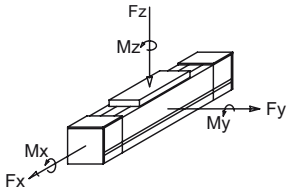


Performances			**TVS 170**	
Max. stroke			4,000	[mm]
Max. speed	Pitch 5	[mm]	0.15	[m/s]
	Pitch 10	[mm]	0.30	[m/s]
	Pitch 20	[mm]	0.75	[m/s]
	Pitch 32	[mm]	1.00	[m/s]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TVS 170	720	2,050	2,050	*6,000	11,950	11,950

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept.
(*) With a pitch of 10 mm



Fx= Max belt strength

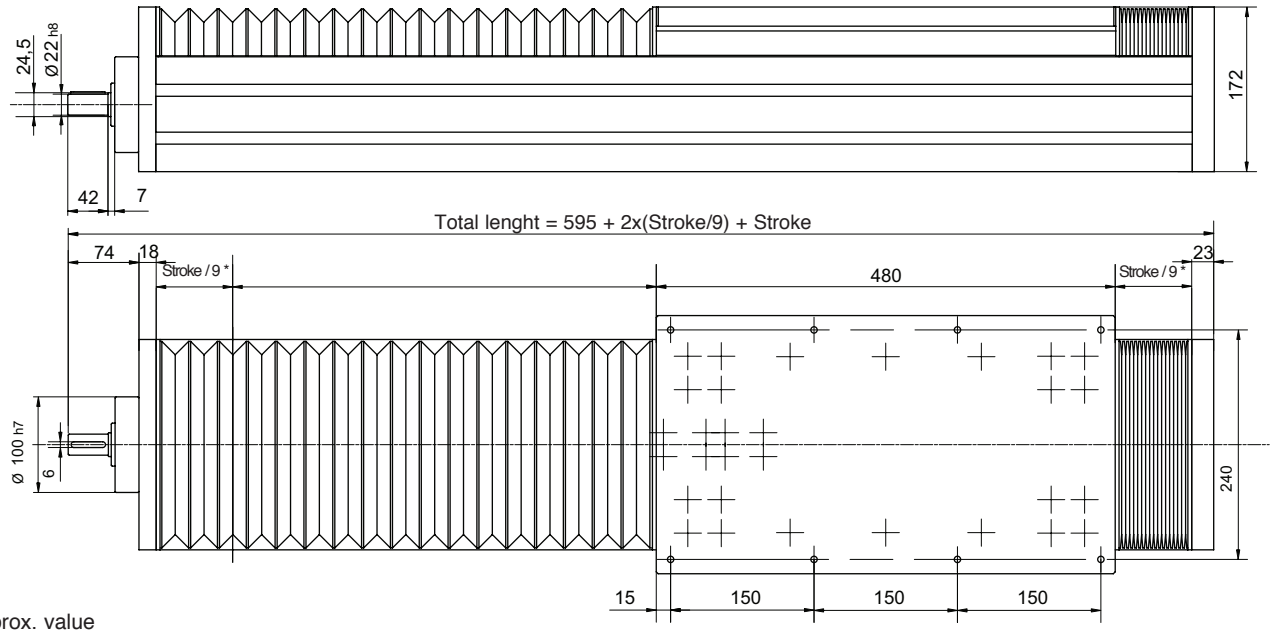
Constructive data

Slide	4 caged ball roller slides size 20	
Beam	Statyca	(see page 14)
Ø screw	32	[mm]
Bellow	heat-sealed, plastic	

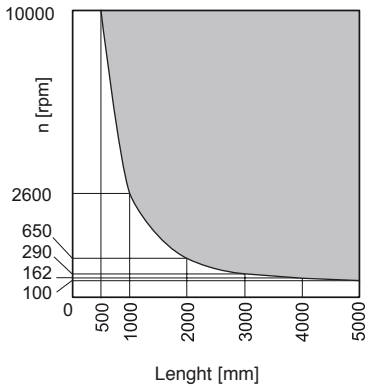
Weights

Inertia of the worm	0,0006 • L. screw(m)	[kgm^2]
Carriage weight	11	[kg]
Base module (stroke=0)	M_{base}= 36	[kg]
1,000 mm profile	q= 28	[kg]

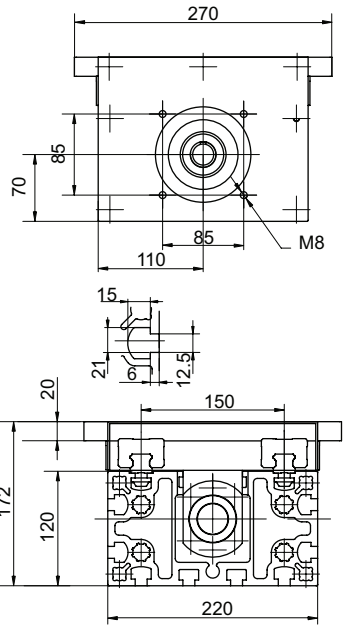
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)



*approx. value



Max. stroke-speed limit over which some pedestal bearings are required (SI) to avoid an excessive screw oscillation. The working point marked inside
the broken line is not recommended.



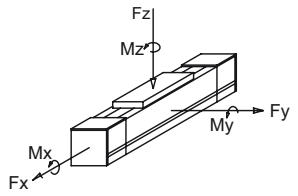
Performances			**TVS 220**	
Max. stroke			4,000	[mm]
Max. speed	Pitch 5	[mm]	0.15	[m/s]
	Pitch 10	[mm]	0.30	[m/s]
	Pitch 20	[mm]	0.75	[m/s]
	Pitch 32	[mm]	1.00	[m/s]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TVS 220	1,300	3,200	3,200	*6,000	18,300	18,300

The dynamic values shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept.

(*) With a pitch of 10 mm



Fx= Max belt strength

Constructive data		
Slide	4 caged ball roller slides size 25	
Beam	Logyca	(see page 14)
Ø screw	32	[mm]
Bellow	heat-sealed, plastic	

Weights		
Inertia of the worm	0.0006 • L. screw(m)	[kgm^2]
Carriage weight	13	[kg]
Base module (stroke=0)	M_{base}= 44	[kg]
1,000 mm profile	q= 37	[kg]

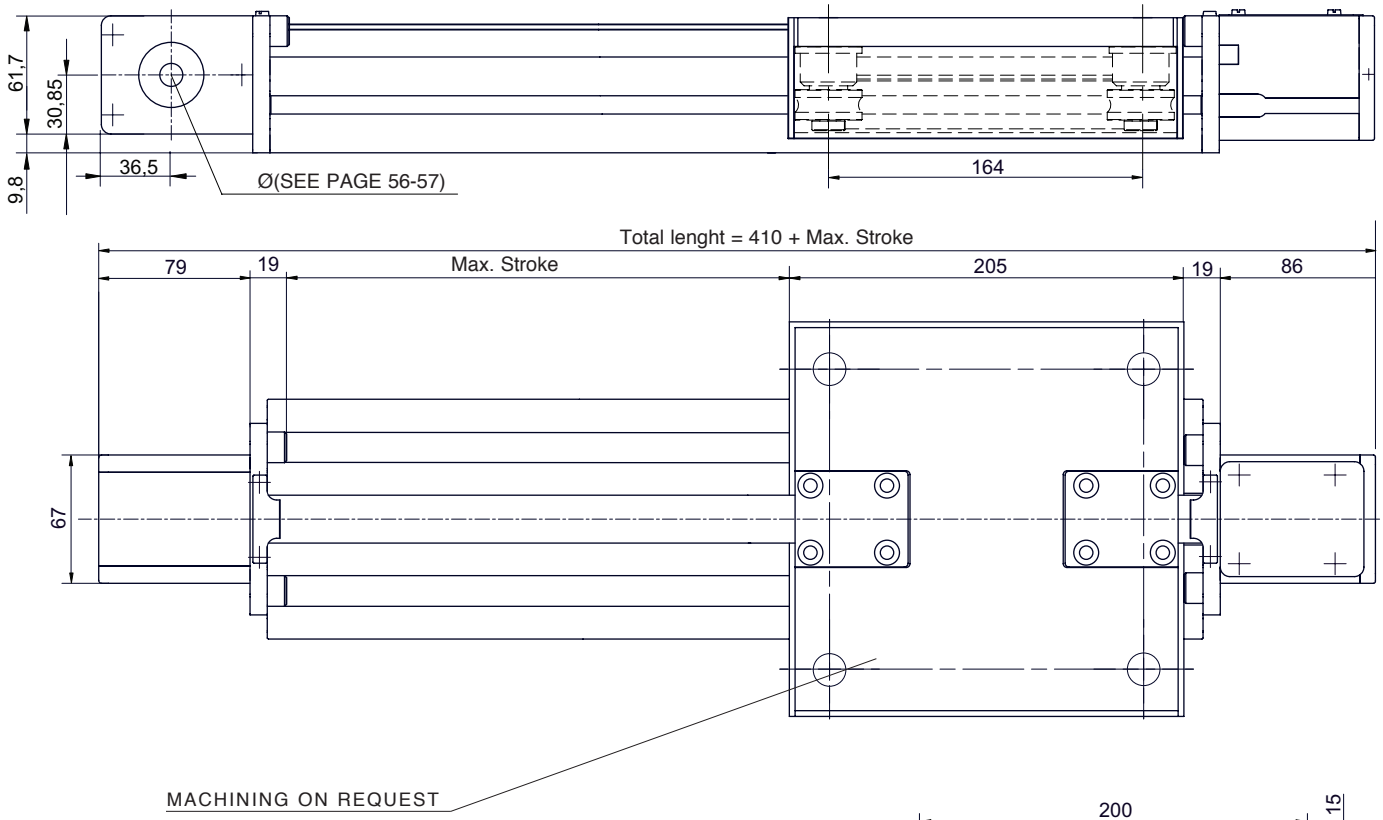
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

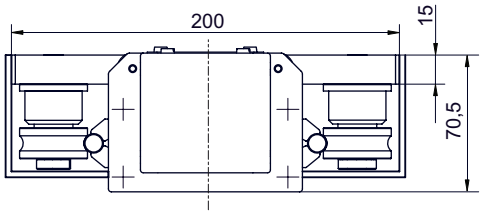
Series T modules with belt drive

TCG 100

HARDENED GUIDE RAILS AND CYLINDRICAL SHAPED ROLLERS

Registered model



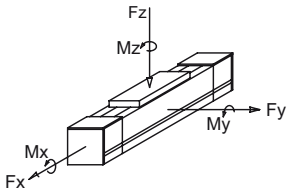


Performances	TCG 100	
Max. stroke	5,490	[mm]
Max. speed	5	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1*	[mm]
Loadless torque	2	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCG 100	40	120	200	1,100	1,700	1,200

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



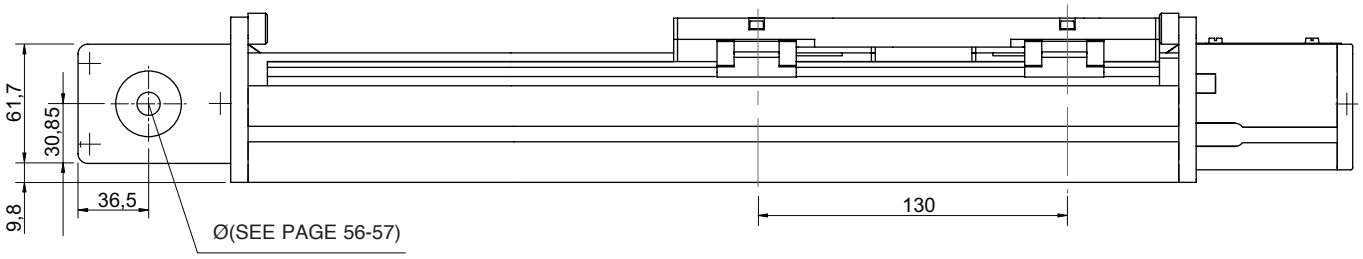
Fx= Max belt strength

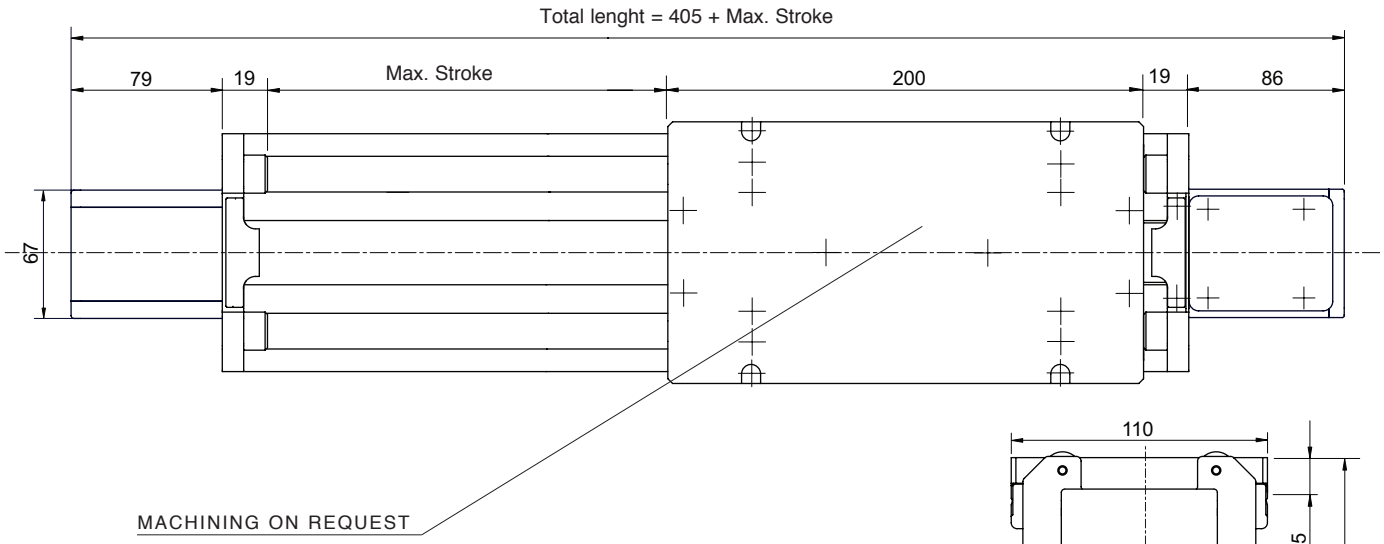
Assembly positions and load direction, see page 10

Constructive data		
Belt	32AT5	
Slide	4 shaped rollers Ø35[mm]	
Load bearing profile	MA 1-4 (see page 13)	
Pulley Ø	50.93	[mm]
Linear displacement per revolution	160	[mm]

Weights		
Inertia of the pulley	-	[kgm^2]
Belt weight	0.21	[kg/m]
Carriage weight	2.5	[kg]
Base module (stroke=0)	M_{base}=6.4	[kg]
1,000 mm profile	q=8.3	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)



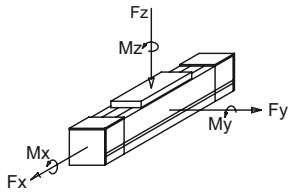


Performances	TCH 100	TCS 100	
Max. stroke	5,400	5,400	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	-	-	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 100	138	324	324	1,180	4,100	4,100
TCS 100	150	324	324	1,180	4,100	4,100

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data		
Belt	32AT5	
Sliding	4 caged ball roller slides size15	
Load bearing profile	MA 1-4	(see page 13)
Pulley Ø	50.93	[mm]
Linear displacement per revolution	160	[mm]

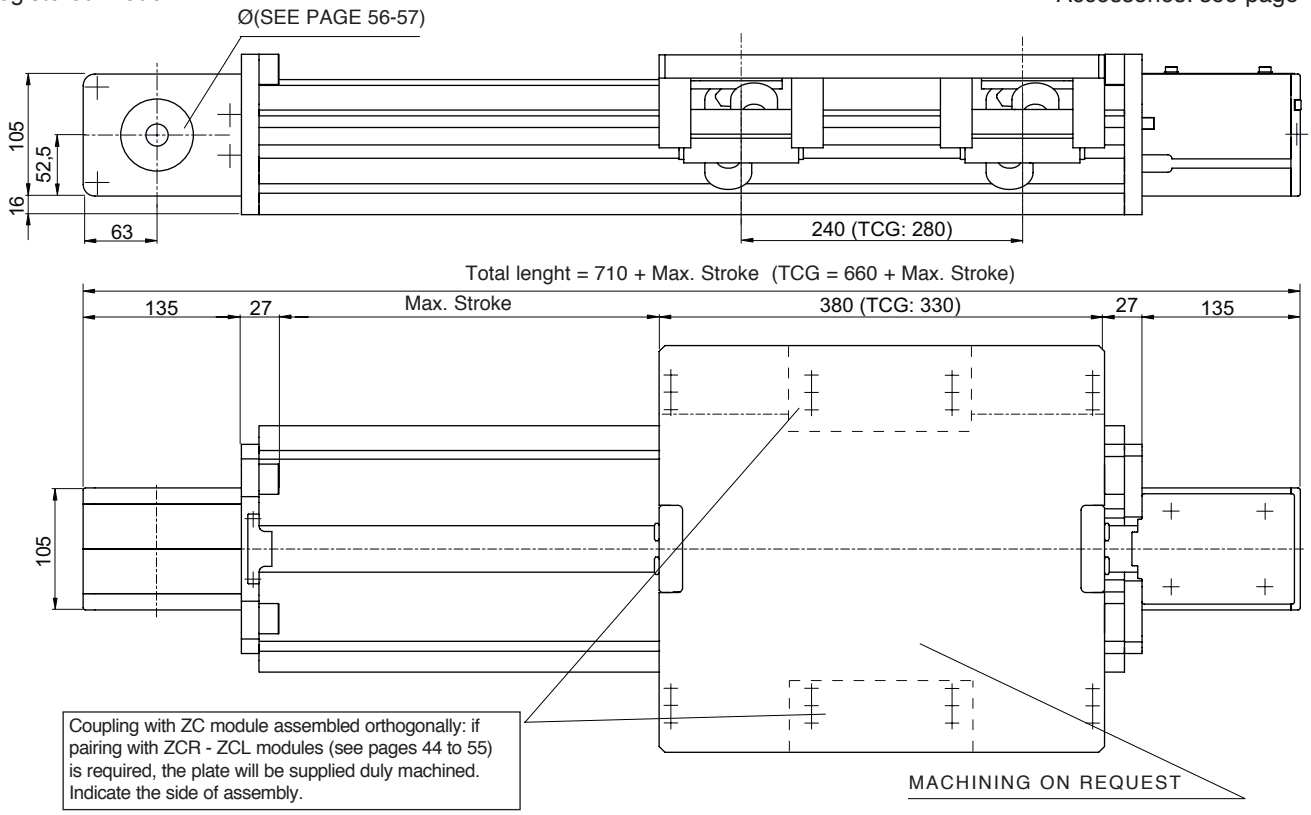
Weights		
Inertia of the pulley	-	[kgm^2]
Belt weight	0.21	[kg/m]
Carriage weight	2.6	[kg]
Base module (stroke=0)	M_{base}=6.5	[kg]
1,000 mm profile	q=9.2	[kg]

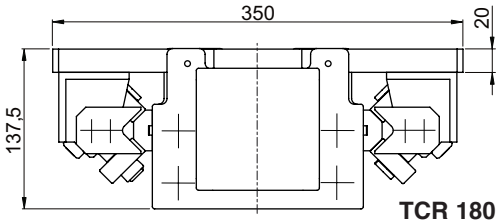
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

TCR 180 e TCG 180

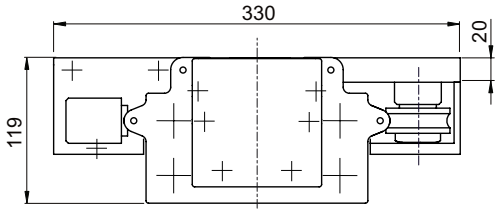
Registered model

Accessories: see page 11





TCR 180



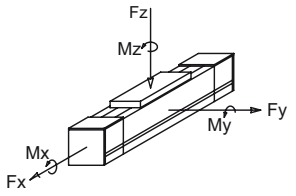
TCG 180

Performances	TCR 180	TCG 180	
Max. stroke	7,480	7,540	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	20	20	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	4.2	1.2	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCR 180	630	800	800	3,300	7,320	7,320
TCG 180	220	270	540	3,300	3,400	1,800

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



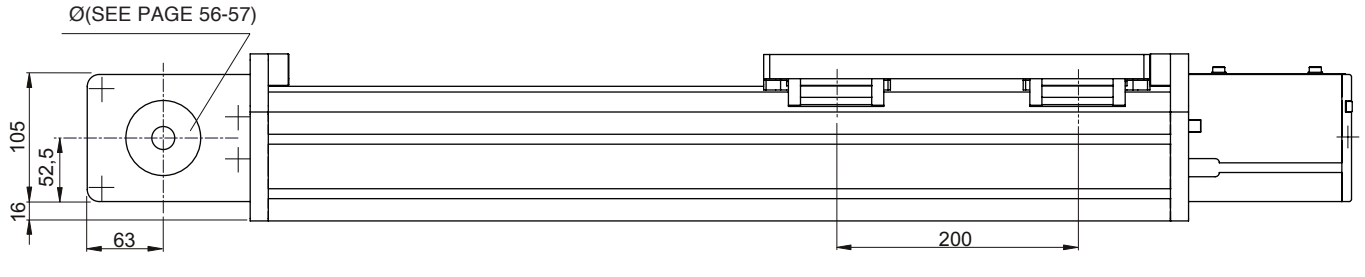
Fx= Max belt strength

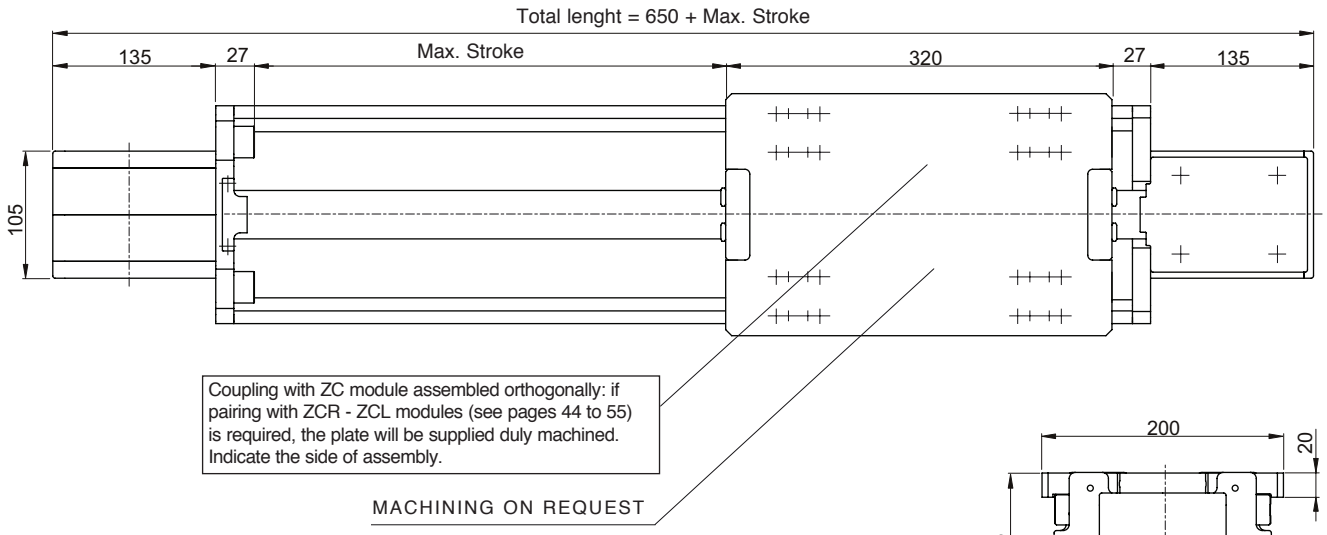
Assembly positions and load direction, see page 10

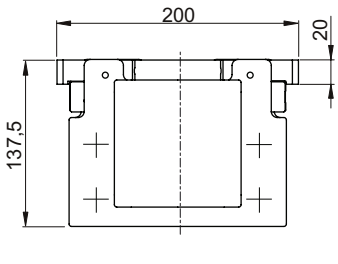
Constructive data	TCR 180	TCG 180	
Belt	40ATL10		
Slide	4 roller slides with 2 rollers 4 rollers Ø 52, guide Ø16		
Load bearing profile	E01-5		(see page 13)
Pulley Ø	92.31		[mm]
Linear displacement per rev.	290		[mm]

Weights	TCR 180	TCG 180	
Inertia of the pulley	0.0037		[kgm^2]
Belt weight	0.55		[kg/m]
Carriage weight	12.4	10.6	[kg]
Base module (stroke=0)	M_{base}=32	27.6	[kg]
1,000 mm profile	q=21	q=16.8	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)





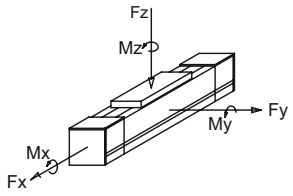


Performances	TCH 180	TCS 180	
Max. stroke	7,340	7,340	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	3.2	3.2	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 180	600	850	850	3,300	9,200	9,200
TCS 180	960	1,350	1,350	3,300	10,950	10,950

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data	TCH 180 - TCS 180	
Belt	40ATL10	
Slide	4 caged ball slides size 20	
Load bearing profile	E01-5	(see page 13)
Pulley Ø	92.31	[mm]
Linear displacement per rev.	290	[mm]

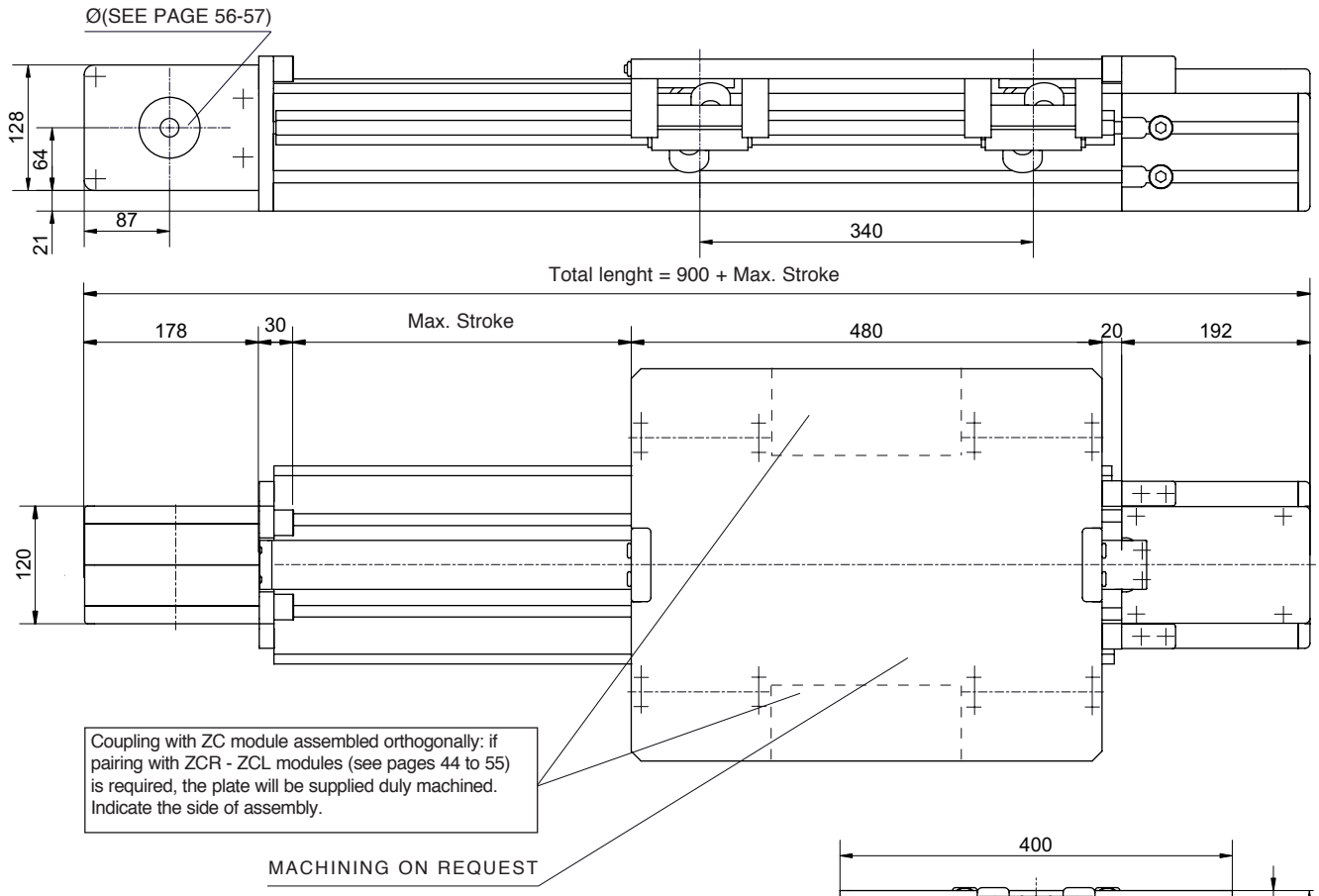
Weights	TCH 180 - TCS 180	
Inertia of the pulley	0.0037	[kgm^2]
Belt weight	0.55	[kg/m]
Carriage weight	6	[kg]
Base module (stroke=0)	M_{base}=23.6	[kg]
1,000 mm profile	q=19	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

TCRQ 170

Registered model

Accessories: see page 11

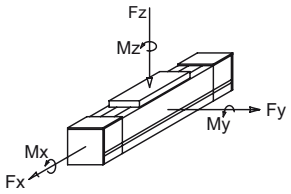


Performances	TCRQ 170	
Max. stroke	5,480	[mm]
Max. speed	7	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	4.2	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCRQ 170	620	1,100	1,100	4,000	7,620	7,620

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Assembly positions and load direction, see page 10

Constructive data		
Belt	50ATL10	
Slides	4 slides 2 rollers Ø40[mm]	
Load bearing profile	Statyca	(see page 14)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

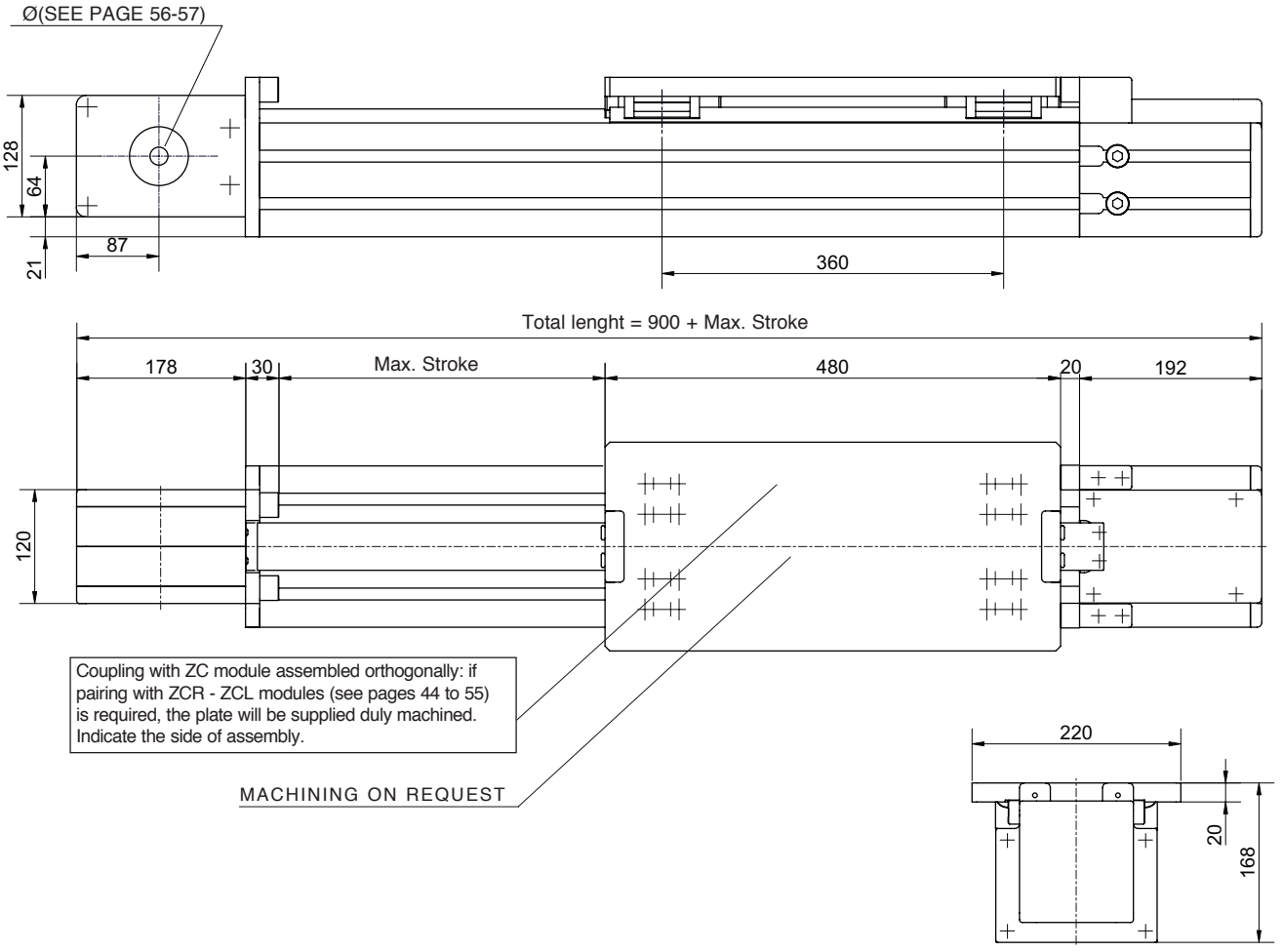
Weights		
Inertia of the pulley	0.0053	[kgm^2]
Belt weight	0.68	[kg/m]
Carriage weight	14.6	[kg]
Base module (stroke=0)	M_{base}=44.6	[kg]
1,000 mm profile	q=25	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

TCH 170 e TCS 170

Modello depositato

Accessories: see page 11

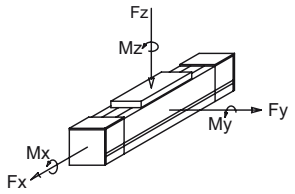


Performances	TCH 170	TCS 170	
Max. stroke	5,480	5,480	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	4.8	4.8	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 170	450	1,430	1,430	4,000	9,400	9,400
TCS 170	720	2,050	2,050	4,000	11,950	11,950

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data	TCH 170 - TCS 170	
Belt	50ATL10	
Slide	4 caged ball slides size 20	
Load bearing profile	Statyca (see page 14)	
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

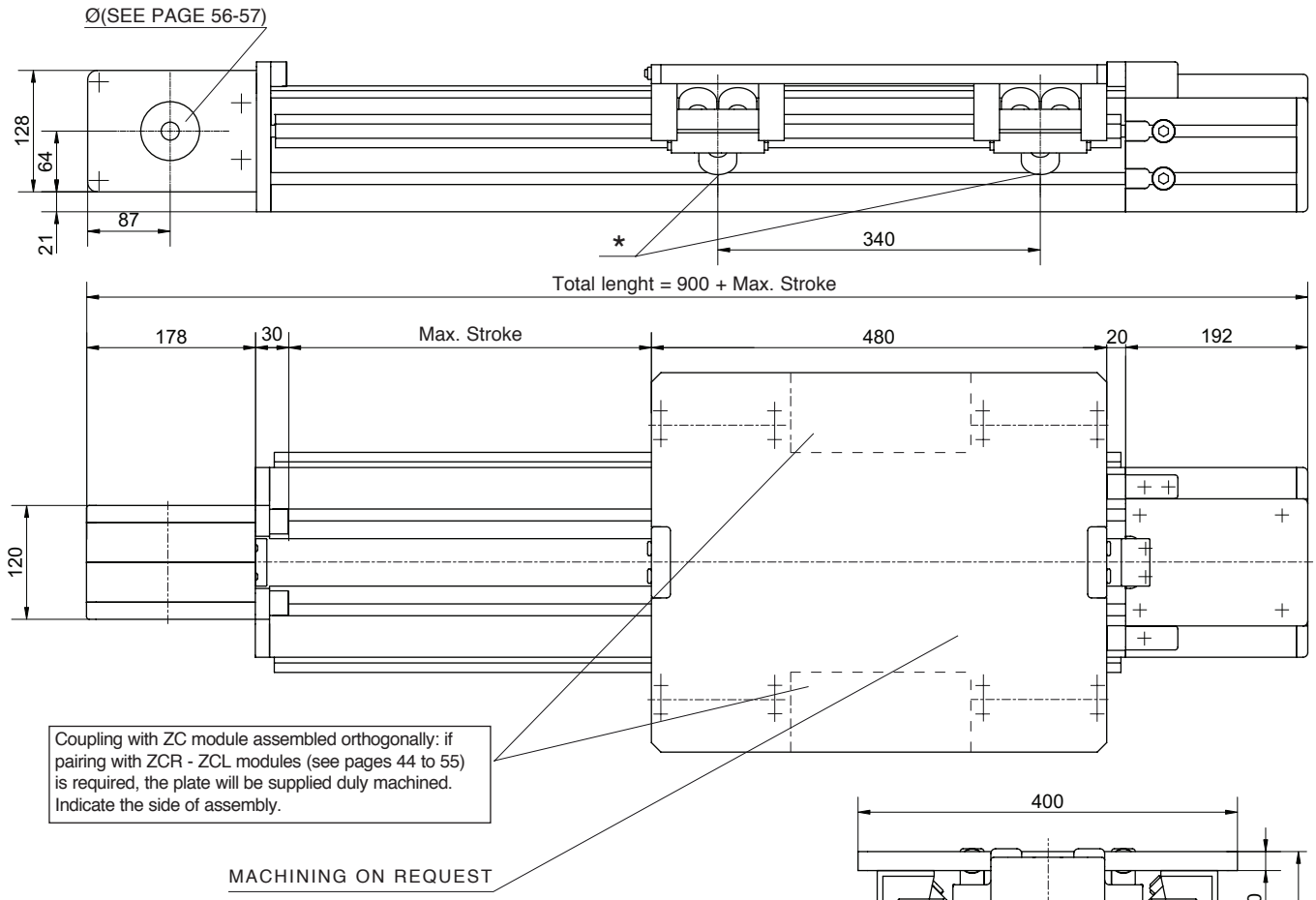
Weights	TCH 170 - TCS 170	
Inertia of the pulley	0.0053	[kgm^2]
Belt weight	0.68	[kg/m]
Carriage weight	8.6	[kg]
Base module (stroke=0)	M_{base}=38	[kg]
1,000 mm profile	q=23	[kg]

To calculate the module weight use the following formula: $\mathbf{M=M_{base}+q\cdot stroke_{max}/1{,}000}$ ($stroke_{max}$ in mm)

TCRQ 200

Registered model

Accessories: see page 11



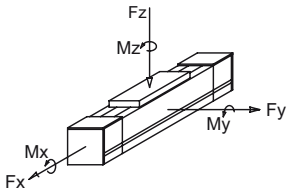
*: Please specify the roller orientation according to the barycentre of the applied load. Values corresponding to the most favourable load position.

Performances	TCRQ 200	
Max. stroke	8,480	[mm]
Max. speed	5	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	4.2	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCRQ 200	1,300(*)	1,600(*)	1,300	4,000	7,620	12,500 (*)

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Assembly positions and load direction, see page 10

Constructive data		
Belt	50ATL10	
Slide	4 slides 3 roll. Ø40	[mm]
Load bearing profile	Valyda	(see page 14)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

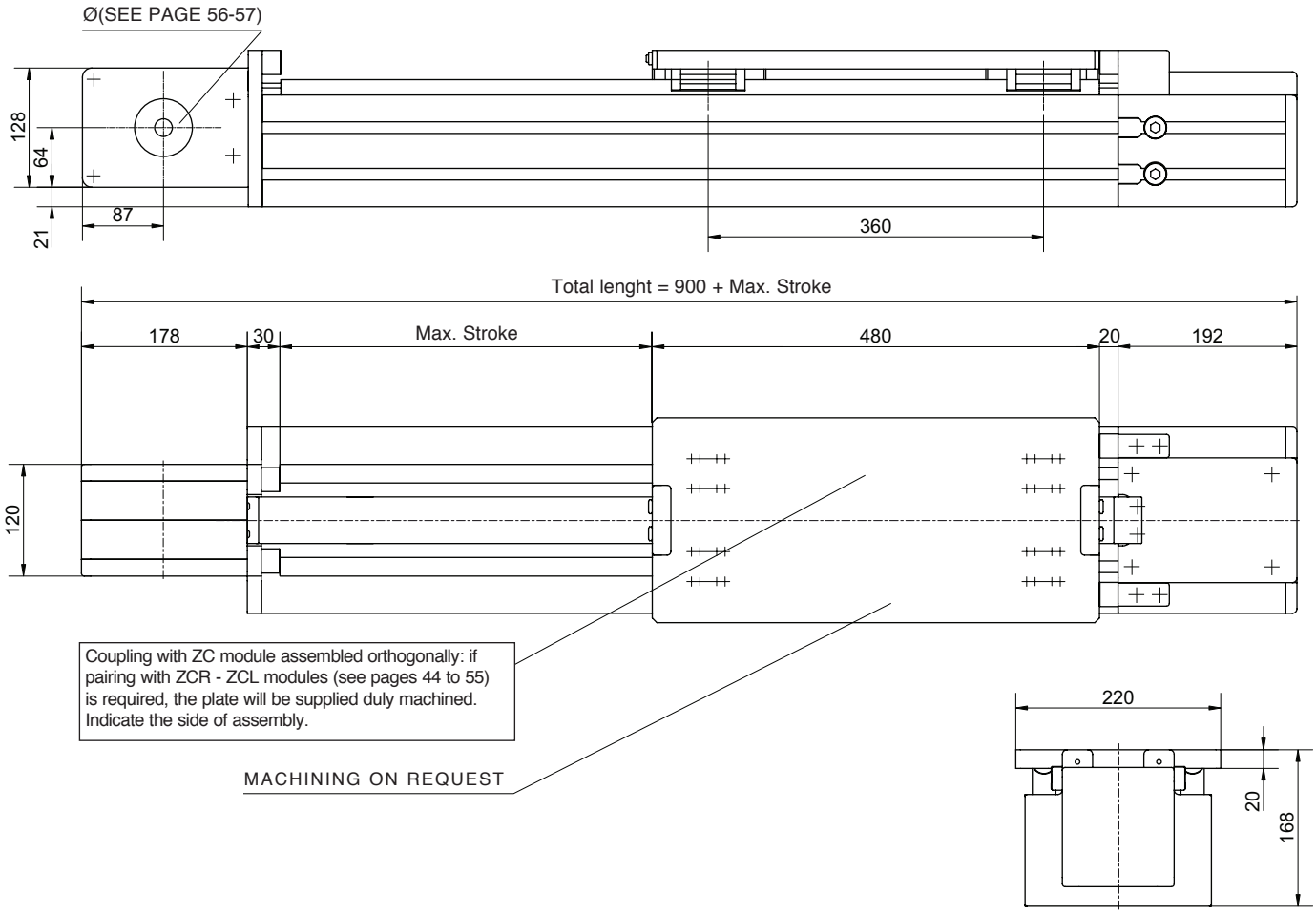
Weights		
Inertia of the pulley	0.0053	[kgm^2]
Belt weight	0.68	[kg/m]
Carriage weight	15	[kg]
Base module (stroke=0)	M_{base}=52	[kg]
1,000 mm profile	q=30	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

TCH 200 e TCS 200

Registered model

Accessories: see page 11



Performances	TCH 200	TCS 200	
Max. stroke	8,480	8,480	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	4.8	4.8	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 200	500	1,430	1,430	4,000	9,400	9,400
TCS 200	810	2,050	2,050	4,000	13,950	13,950

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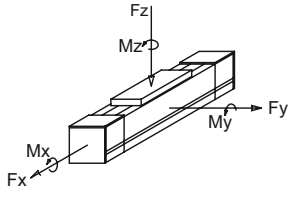


Fx= Max belt strength

Constructive data	TCH 200 - TCS 200	
Belt	50ATL10	
Slide	4 caged ball slides size 20	
Load bearing profile	Valyda	(see page 14)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

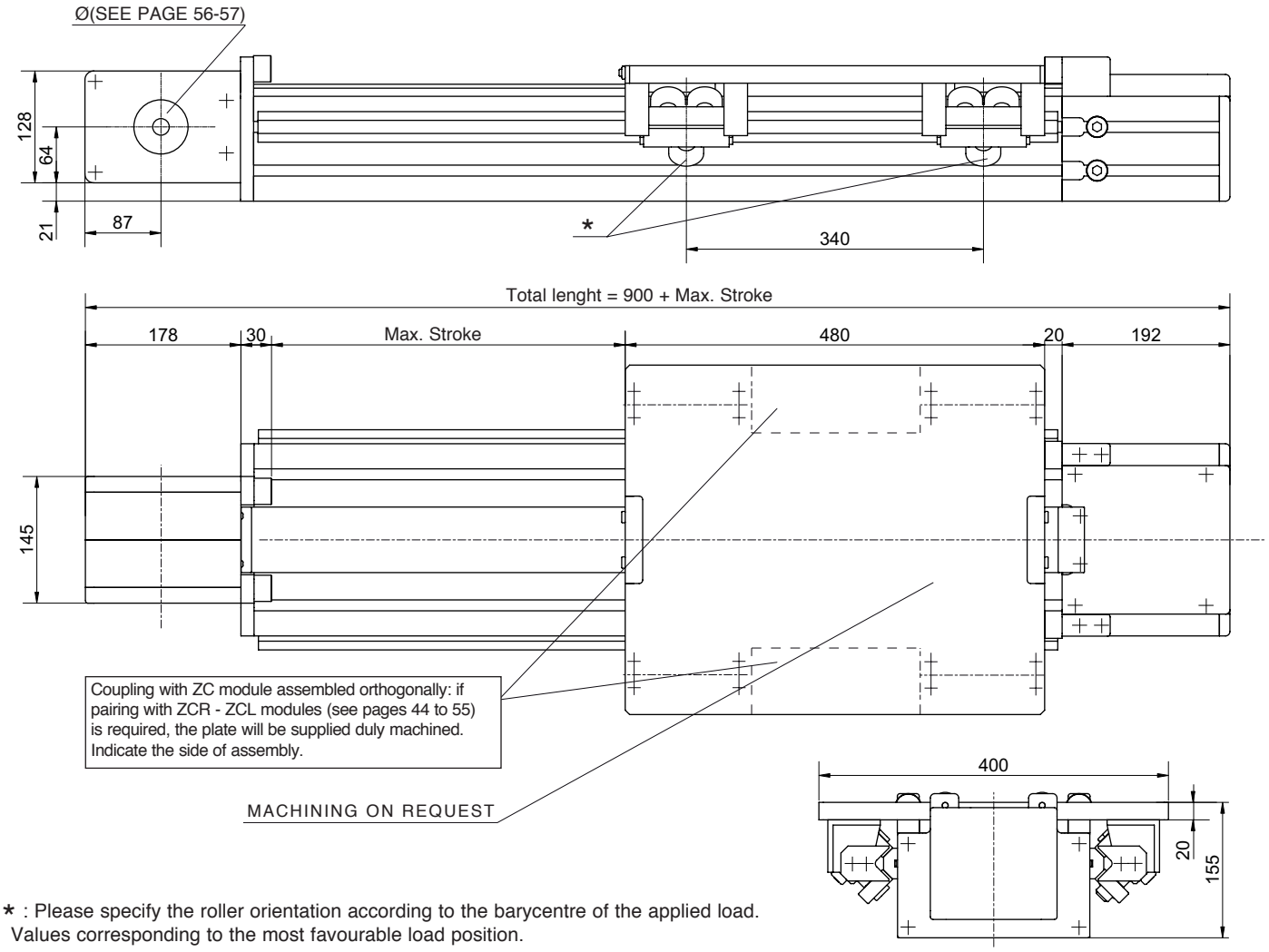
Weights	TCH 200 - TCS 200	
Inertia of the pulley	0.0053	[kgm^2]
Belt weight	0.68	[kg/m]
Carriage weight	8,8	[kg]
Base module (stroke=0)	M_{base}=42	[kg]
1,000 mm profile	q=27.5	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

TCRQ 220

Registered model

Accessories: see page 11



* : Please specify the roller orientation according to the barycentre of the applied load. Values corresponding to the most favourable load position.

Performances	TCRQ 220	
Max. stroke	11,480	[mm]
Max. speed	5	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	5.8	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCRQ220	1,400(*)	1,600(*)	1,300	6,000	7,620	12,500(*)

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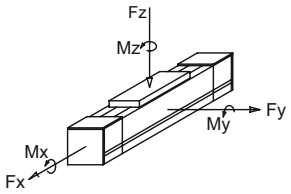


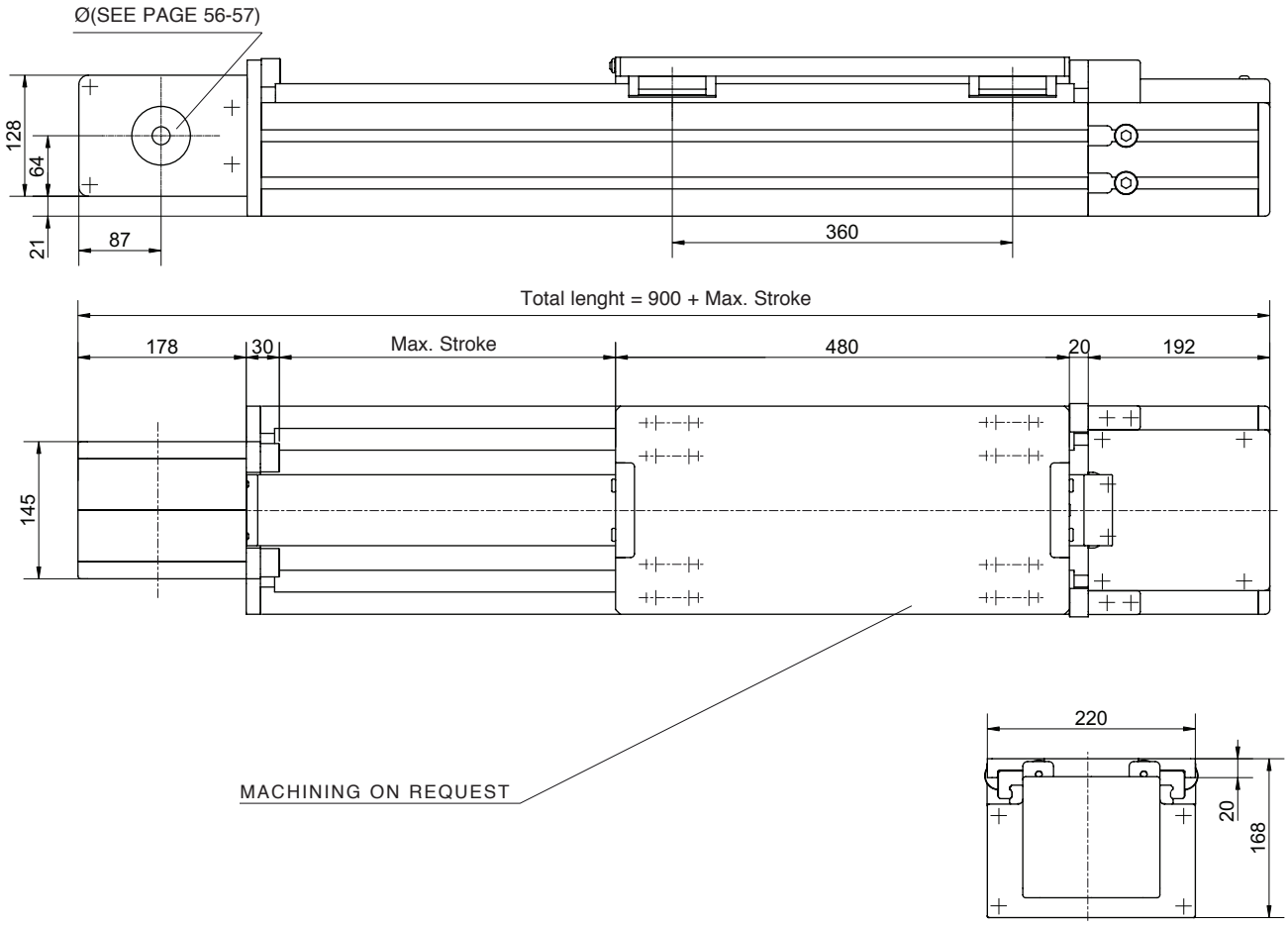
Fx= Max belt strength

Assembly positions and load direction, see page 10

Constructive data		
Belt	75ATL10	
Slide	4 slides 3 roll. Ø 40	[mm]
Load bearing profile	Logyca	(see page 14)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

Weights		
Inertia of the pulley	0,0082	[kgm^2]
Belt weight	1,02	[kg/m]
Carriage weight	16	[kg]
Base module (stroke=0)	M_{base}=54.6	[kg]
1,000 mm profile	q= 33.7	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)



Performances	TCH 220	TCS 220	
Max. stroke	11,480	11,480	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	6.9	6.9	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 220	950	2,200	2,200	6,000	13,000	13,000
TCS 220	1,300	3,200	3,200	6,000	18,300	18,300

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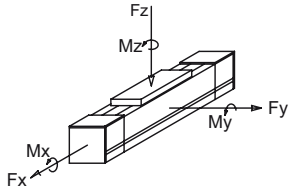


Fx= Max belt strength

Constructive data	TCH 220 - TCS 220	
Belt	75ATL10	
Slide	4 caged ball slides size 25	
Load bearing profile	Logyca	(see page 14)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

Weights	TCH 220 - TCS 220	
Inertia of the pulley	0.0082	[kgm^2]
Belt weight	1.02	[kg/m]
Carriage weight	9.5	[kg]
Base module (stroke=0)	M_{base}=47.4	[kg]
1,000 mm profile	q=33	[kg]

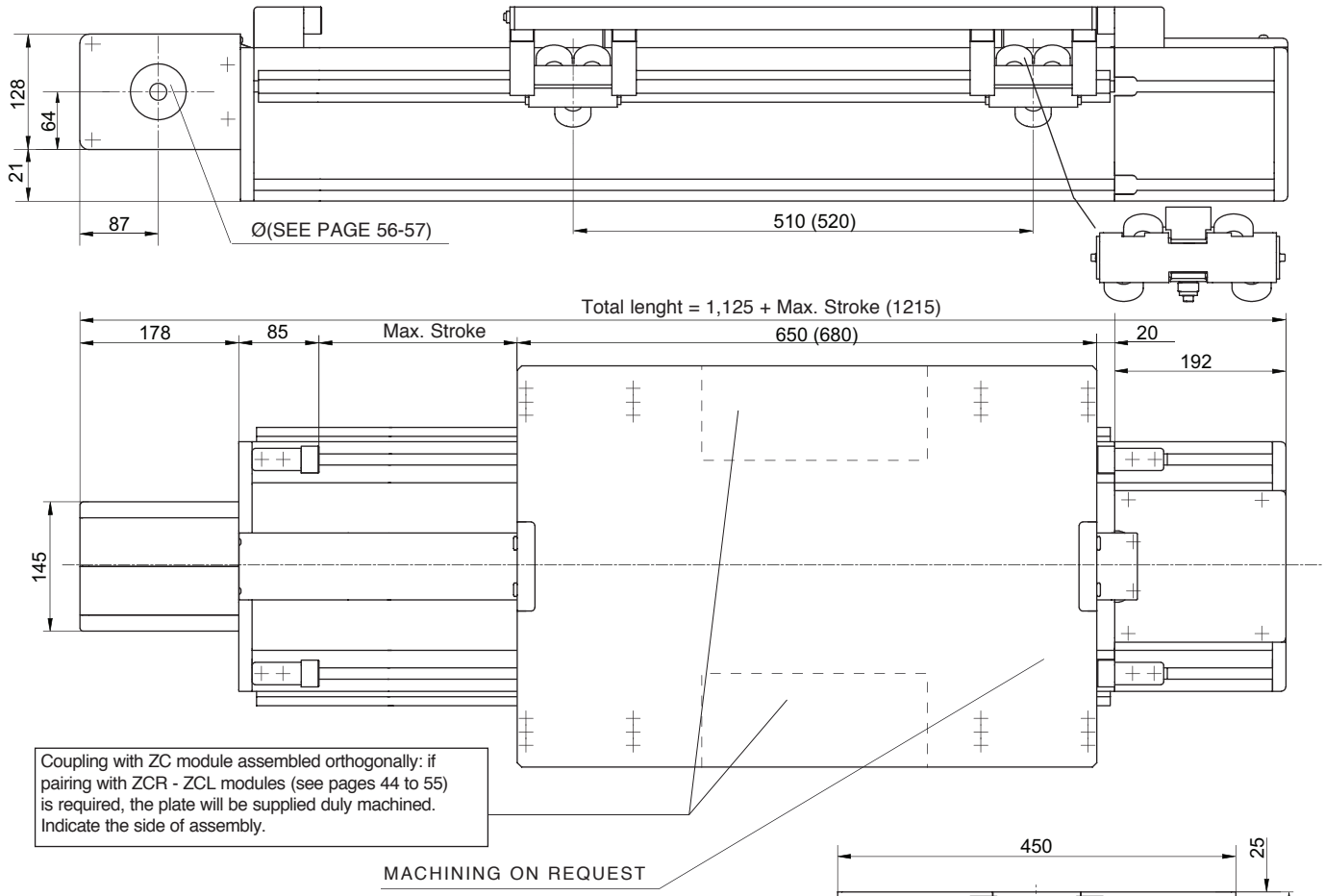
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

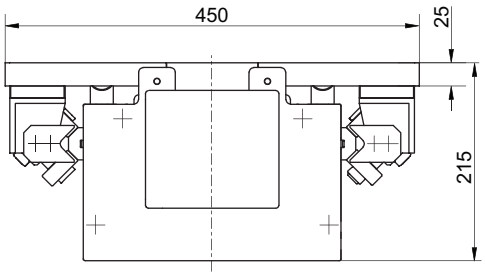
TCRQ 280 (TCRP 280)

Registered model*

RP= Heavy guide rails and roller slides - Ø52

Accessories: see page 11





* Versions with a 100 mm belt are also available. (TCRE/TCREP)

Performances	TCRQ 280 (TCRP280)		
Max. stroke	11,315	11,175	[mm]
Max. speed	7	5	[m/s]
Max. acceleration	20	10	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	7.6	8.5	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCRQ 280	1,950(*)	3,100(*)	1,950	6,000	7,620	13,500(*)
TCRP 280	3,100	4,150	4,150	6,000	20,100	20,100

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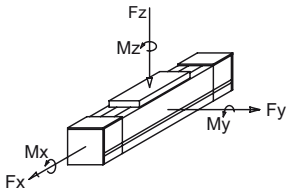
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Assembly positions and load direction, see page 10

Constructive data	TCRQ 280	(TCRP 280)	
Belt	75 ATL 10		
Slide	4 slides 3 rollers Ø40	4 slides 4 rollers Ø52	[mm]
Load bearing profile	Pratyca	(see page 15)	
Pulley Ø	95.49		[mm]
Linear displacement per rev.	300		[mm]

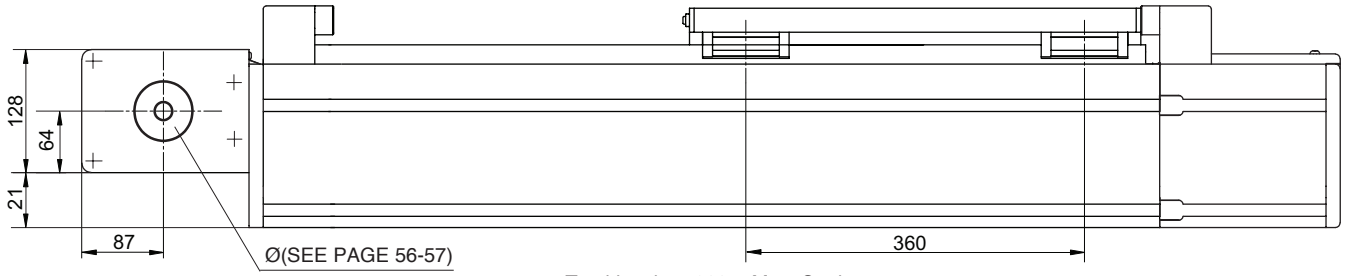
Weights	TCRQ 280	(TCRP 280)	
Inertia of the pulley	0.0082		[kgm^2]
Belt weight	1.02		[kg/m]
Carriage weight	27	55	[kg]
Base module	M_{base}=87	M_{base}=122	[kg]
1,000 mm profile	q=48	q=56	[kg]

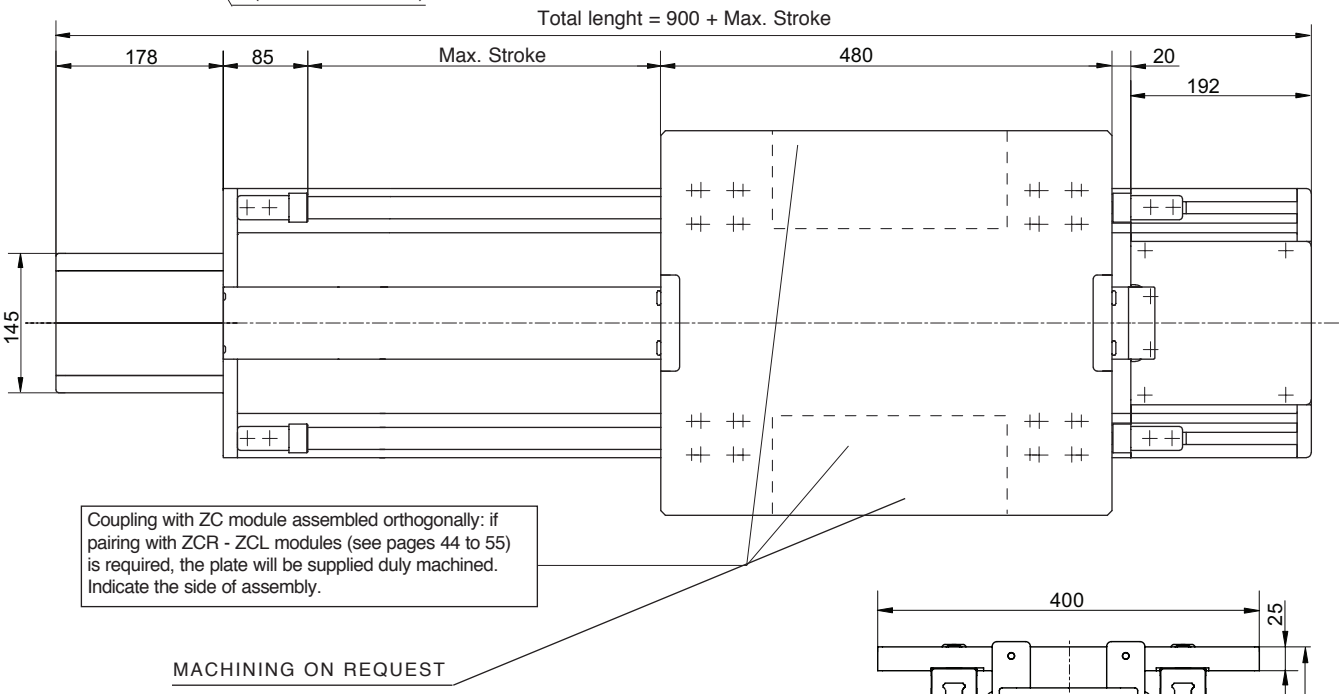
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

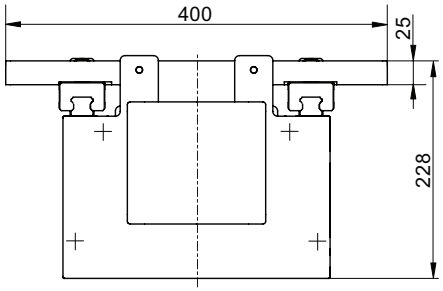
TCH 280 - TCS 280

Registered model

Accessories: see page 11







* Versions with a 100 mm belt are also available. (TCSE 280)

Performances	TCH 280	TCS 280	
Max. stroke	11,480	11,485	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	8.3	8.3	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 280	1,450	2,200	2,200	6,000	13,500	13,500
TCS 280	1,950	3,200	3,200	6,000	20,300	20,300

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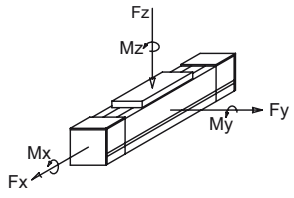
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Constructive data	TCH 280 - TCS 280	
Belt	75 ATL 10	
Slide	4 caged ball slides size 25	
Load bearing profile	Pratyca (see page 15)	
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

Weights	TCH 280 - TCS 280	
Inertia of the pulley	0.0082	[kgm^2]
Belt weight	1.02	[kg/m]
Carriage weight	18	[kg]
Base module (stroke=0)	M_{base}=69	[kg]
1,000 mm profile	q= 47	[kg]

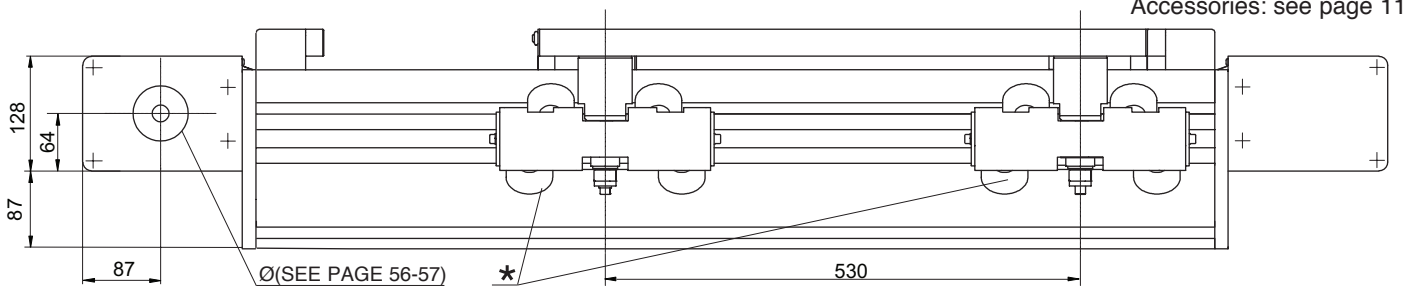
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

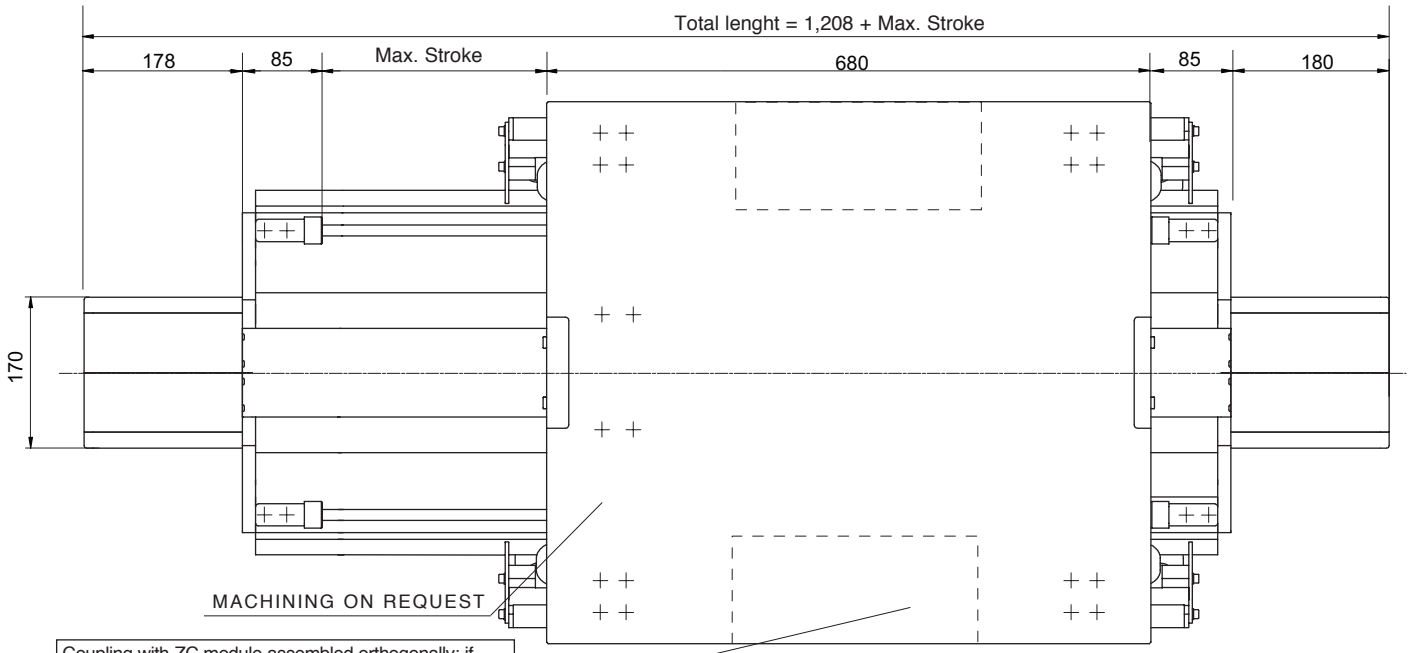
TCRP 360

Registered model

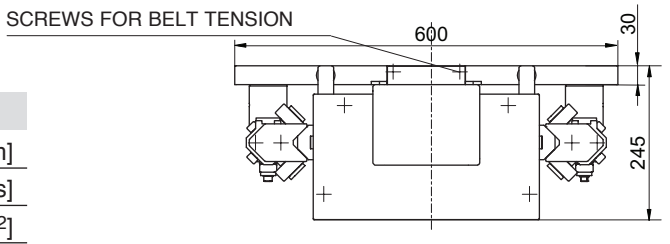
RP= Heavy guide rails and roller slides - Ø52

Accessories: see page 11





Coupling with ZC module assembled orthogonally: if pairing with ZCR - ZCL modules (see pages 42 to 53) is required, the plate will be supplied duly machined. Indicate the side of assembly.

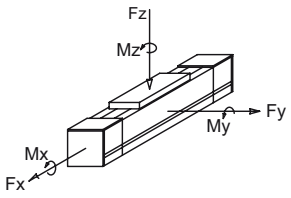


* Versions with a 150 mm belt are also available. (TCRPE360)

Performances	TCRP 360	
Max. stroke	11,175	[mm]
Max. speed	5	[m/s]
Max. acceleration	10	[m/s^2]
Repositioning accuracy	± 0.1	[mm]
Loadless torque	8.5	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCRP 360	4,900	5,300	5,300	8,000	25,400	25,400



Fx= Max belt strength

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They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Assembly positions and load direction, see page 10

Constructive data		
Belt	100 ATL 10	
Slide	4 slides 4 rollers Ø52	[mm]
Load bearing profile	Solyda	(see page 15)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

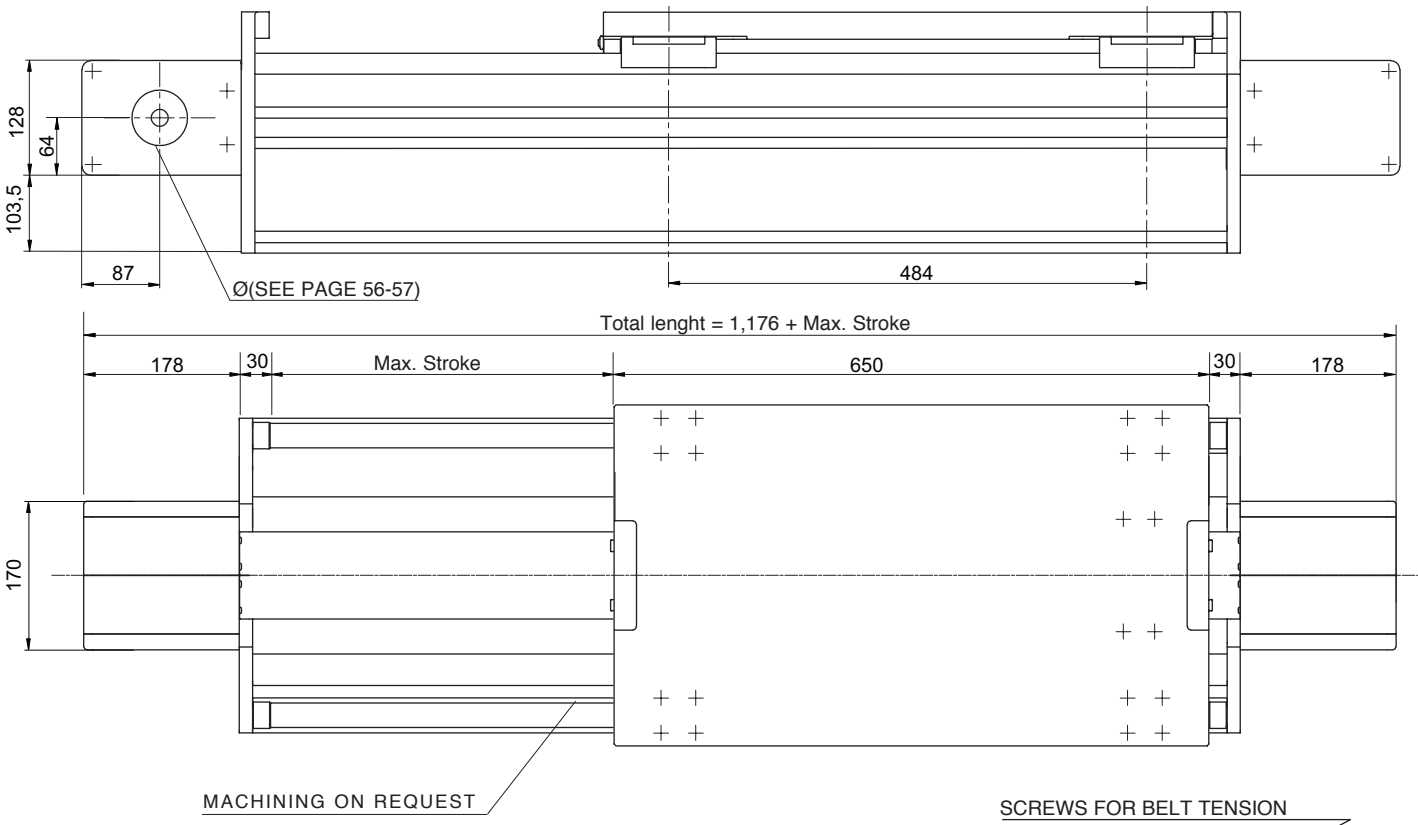
Weights		
Inertia of the pulley	0.0082	[kgm^2]
Belt weight	1.02	[kg/m]
Carriage weight	55	[kg]
Base module (stroke=0)	M_{base}=137	[kg]
1,000 mm profile	q=75	[kg]

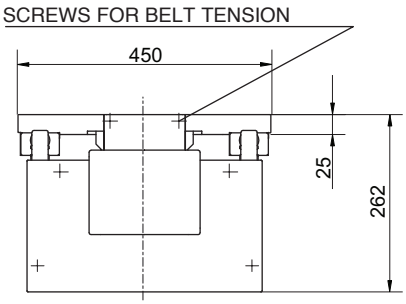
To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

TCH 360 - TCS 360

Registered model

Accessories: see page 11





* Versions with a 150 mm belt are also available. (TCSE360)

Performances	TCH 360	TCS 360	
Max. stroke	11,480	11,485	[mm]
Max. speed	5	5	[m/s]
Max. acceleration	50	50	[m/s^2]
Repositioning accuracy	± 0.1	± 0.1	[mm]
Loadless torque	8.3	8.3	[Nm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
TCH 360	2,600	3,710	3,710	8,000	19,050	19,050
TCS 360	4,000	5,500	5,500	8,000	28,600	28,600

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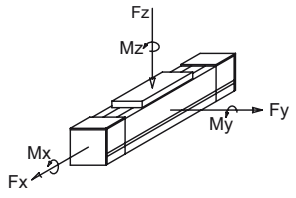


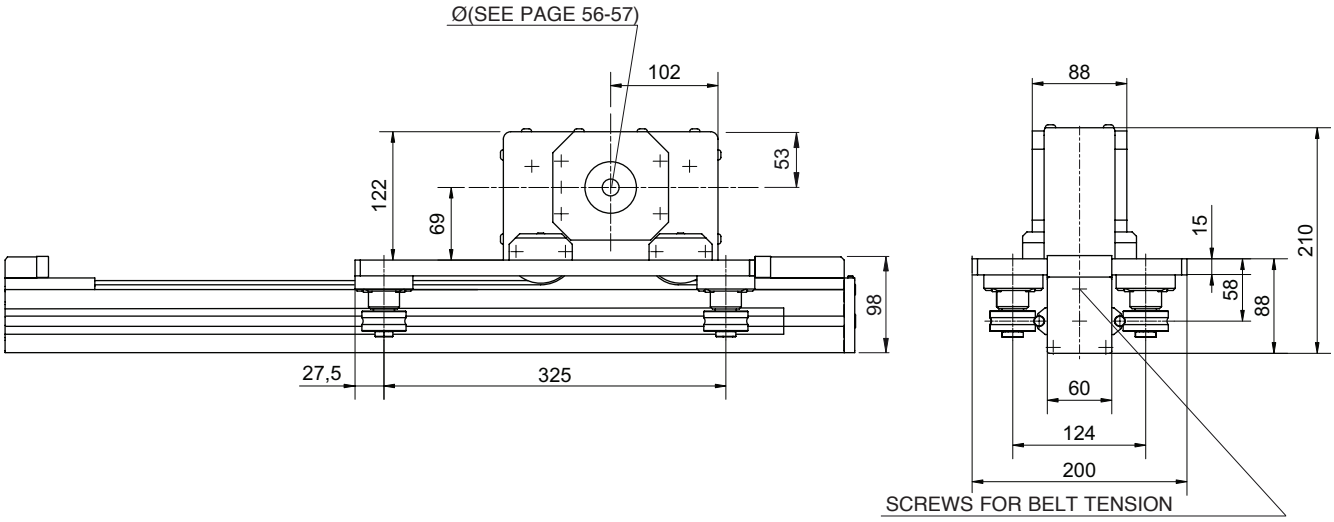
Fx= Max belt strength

Constructive data	TCH 360 - TCS 360	
Belt	100 ATL 10	
Slide	4 caged ball roller slides 30	
Load bearing profile	Solyda	(see page 15)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

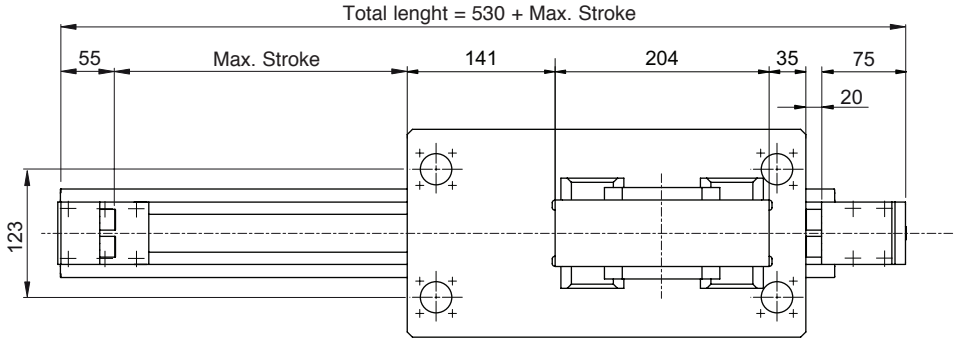
Weights	TCH 360 - TCS 360	
Inertia of the pulley	0.0082	[kgm^2]
Belt weight	1.02	[kg/m]
Carriage weight	28	[kg]
Base module (stroke=0)	M_{base}=105	[kg]
1,000 mm profile	q= 70	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

Accessories: see page 11



60x90 profile available



IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	**ZCG 60**	
Max. stroke	5,470	[mm]
Max. speed	4	[m/s]
Max. acceration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCG 60	60	200	340	2,000	2,100	1,500

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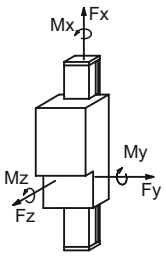


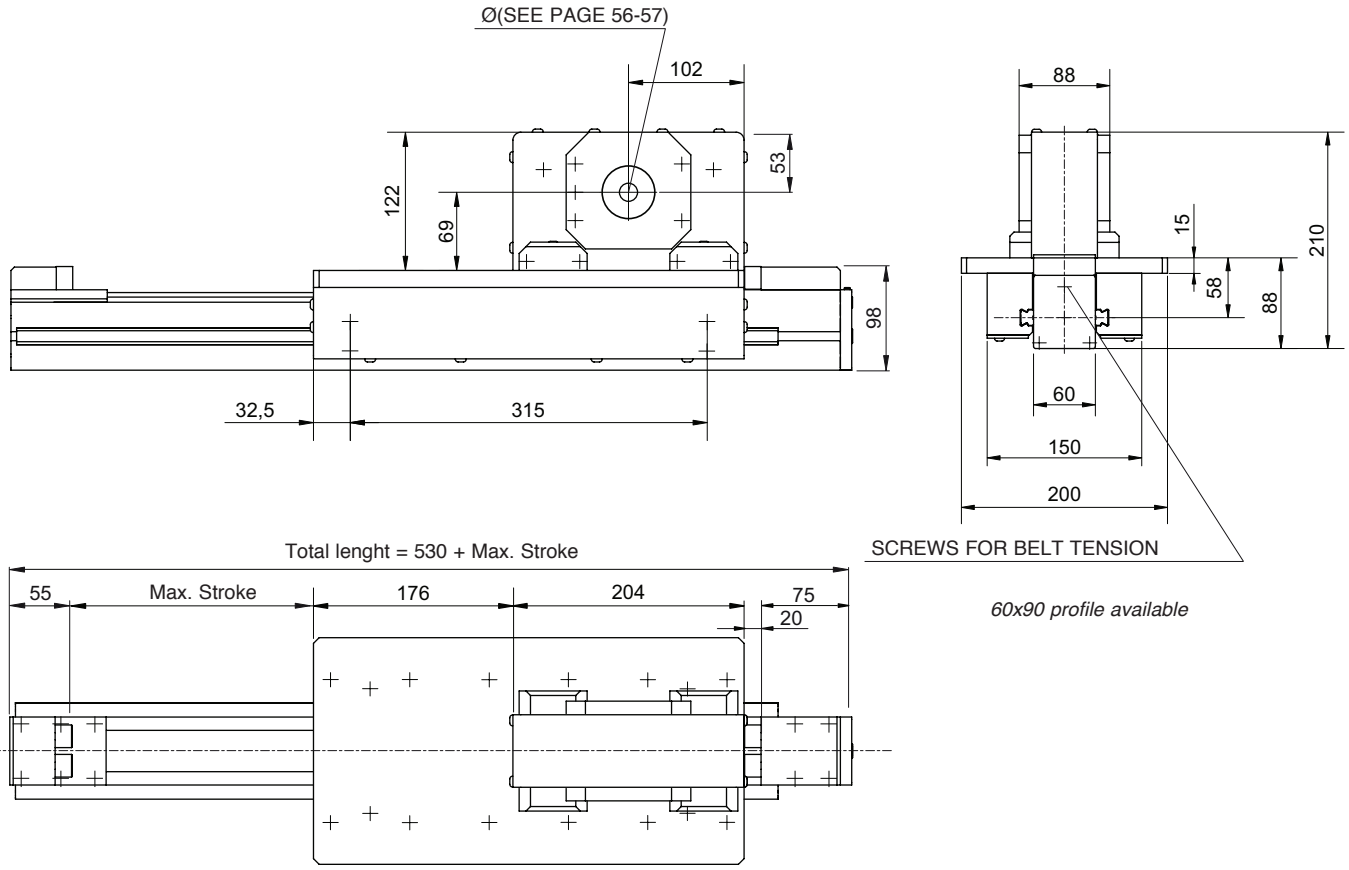
Fx= Max belt strength

Assembly positions and load direction, see page 10

Constructive data		
Belt	32AT10	
Slide	4 shaped roller slides Ø 42 [mm]	
Load bearing profile	F01-1	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per rev.	220	[mm]

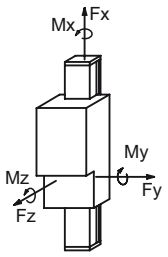
Weights		
Inertia of the pulley	0.0013	[kgm^2]
Belt weight	0.19	[kg/m]
Carriage weight	10	[kg]
Base module (stroke=0)	M_{base}=14	[kg]
1,000 mm profile	q=6	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)



60x90 profile available

IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.



Fx= Max belt strength

Performances	**ZCL 60**	
Max. stroke	5,470	[mm]
Max. speed	4	[m/s]
Max. acceleration	40	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCL 60	151	570	630	2,000	4,180	3,740

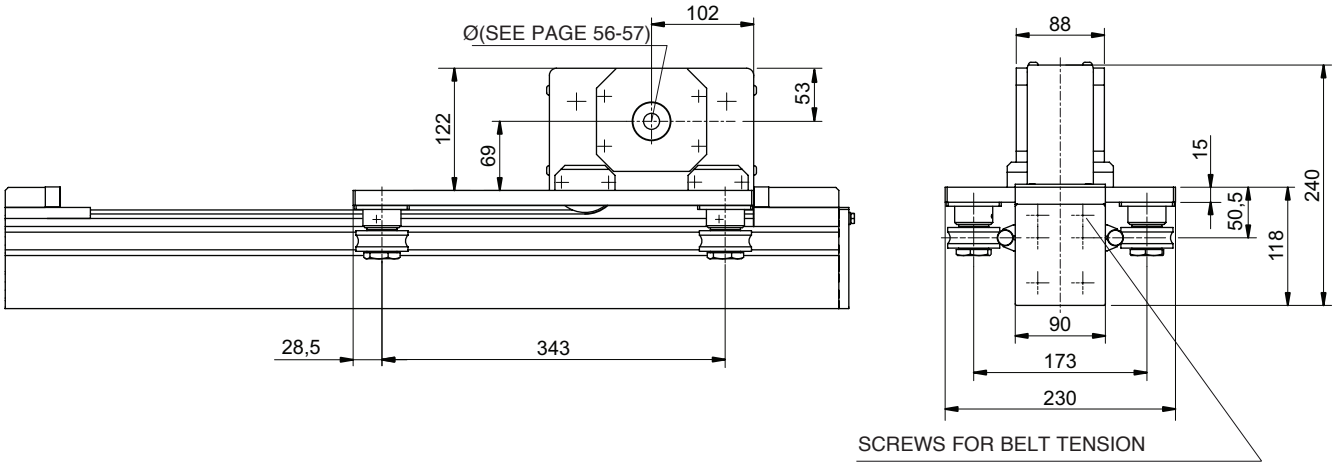
The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

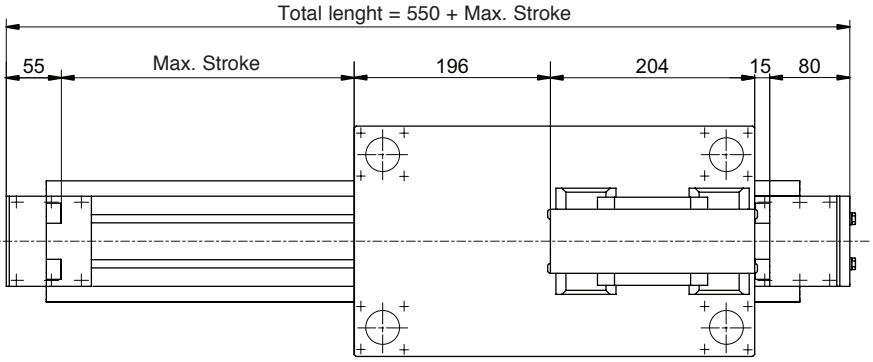
Constructive data		
Belt	32AT10	
Slide	4 caged ball roller slides 15	
Load bearing profile	F01-1	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per rev.	220	[mm]

Weights		
Inertia of the pulley	0.0013	[kgm^2]
Belt weight	0.19	[kg/m]
Carriage weight	11	[kg]
Base module (stroke=0)	M_{base}=16	[kg]
1,000 mm profile	q=7.2	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

Accessories: see page 11





90x180 profile available

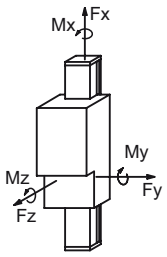
IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	**ZCG 90**	
Max. stroke	5,450	[mm]
Max. speed	4	[m/s]
Max. acceleration	15	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCG 90	120	400	540	2,000	3,400	1,800

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Assembly positions and load direction, see page 10

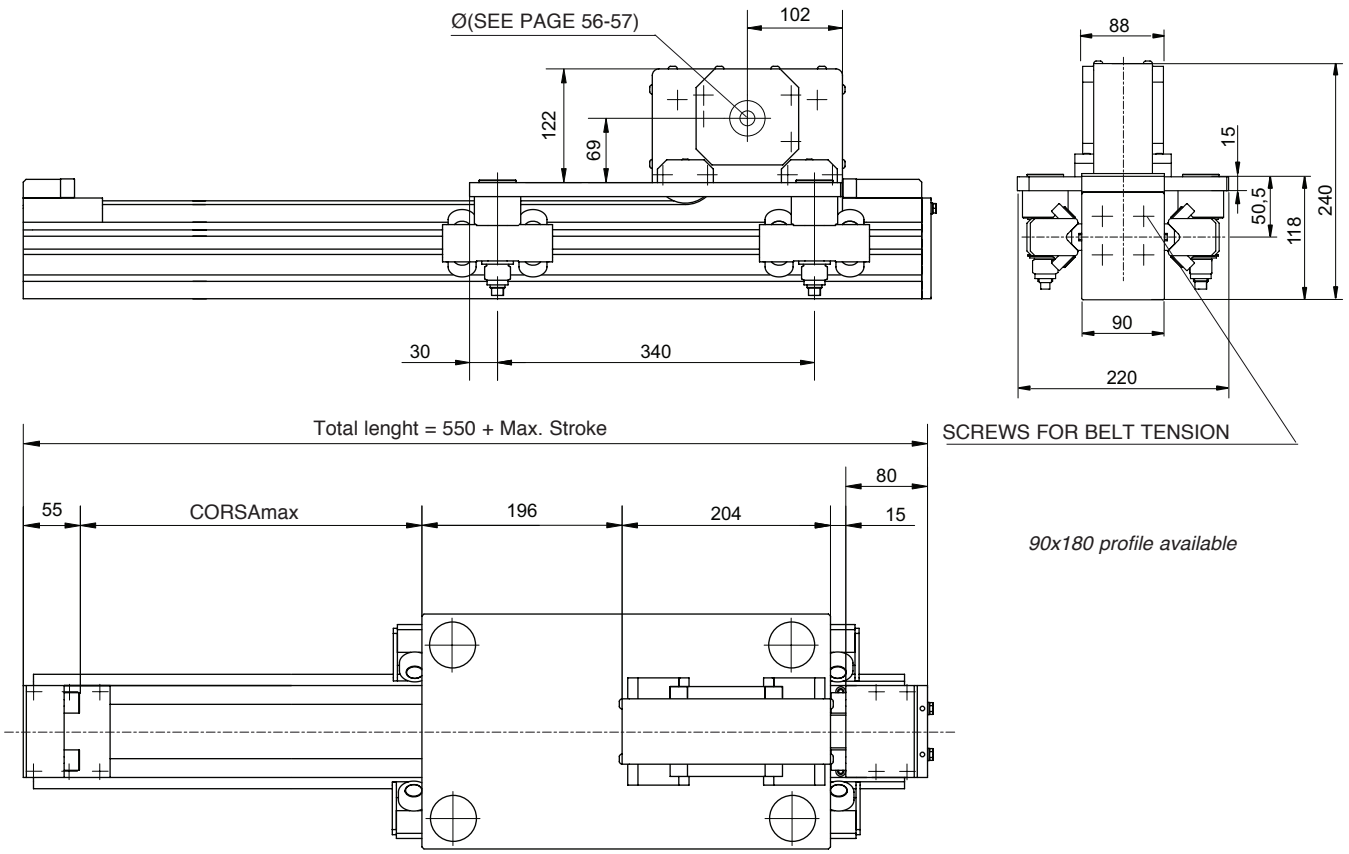
Constructive data		
Belt	32AT10	
Slide	4 shap. r. Ø52 - guide Ø16	
Load bearing profile	E01-4	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per rev.	220	[mm]

Weights		
Inertia of the pulley	0.0013	[kgm^2]
Belt weight	0.19	[kg/m]
Carriage weight	10.5	[kg]
Base module (stroke=0)	M_{base}=16	[kg]
1.000 mm profile	q=8.5	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

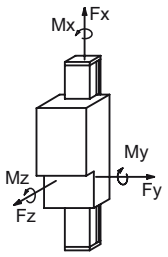
ZCRR 90

Accessories: see page 11



90x180 profile available

IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.



Fx= Max belt strength

Performances	ZCRR 90	
Max. stroke	5,450	[mm]
Max. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCRR 90	300	1,000	1,000	2,000	6,700	6,700

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

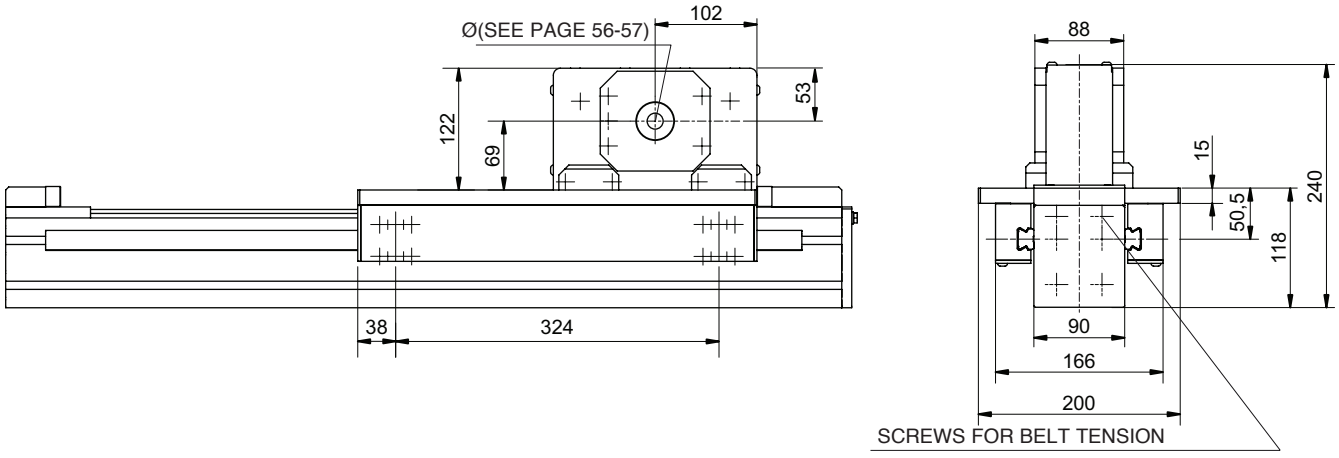
Assembly positions and load direction, see page 10

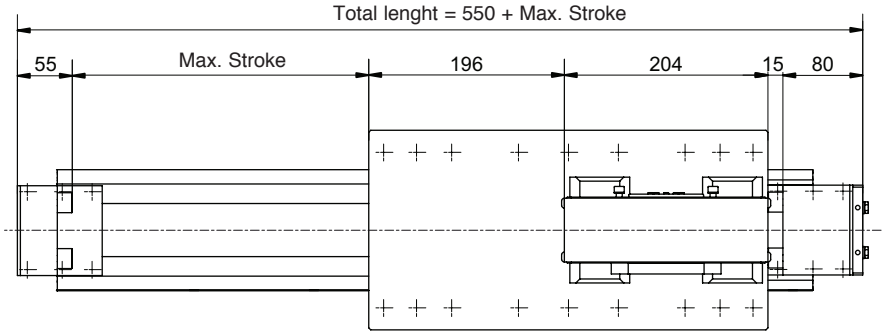
Constructive data		
Belt	32 AT 10	
Slide	4 slides 4 roll. Ø30	[mm]
Load bearing profile	E01-4	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per rev.	220	[mm]

Weights		
Inertia of the pulley	0.0013	[kgm^2]
Belt weight	0.21	[kg/m]
Carriage weight	13	[kg]
Base module (stroke=0)	M_{base}= 20	[kg]
1,000 mm profile	q=11.2	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

Accessories: see page 11

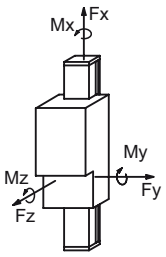




90x180 profile available

IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	**ZCL 90**	
Max. stroke	5,450	[mm]
Max. speed	4	[m/s]
Max. acceleration	20	[m/s^2]
Repositioning accuracy	± 0.1	[mm]



Fx= Max belt strength

Suggested working load conditions						
Module	**M_x[Nm]**	**M_y[Nm]**	**M_z[Nm]**	**F_x[N]**	**F_y[N]**	**F_z[N]**
ZCL 90	260	730	1,000	2,000	5,500	5,000

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Constructive data		
Belt	32AT10	
Slide	4 caged ball roller slides 20	
Load bearing profile	E01-4	(see page 12)
Pulley Ø	70.03	[mm]
Linear displacement per rev.	220	[mm]

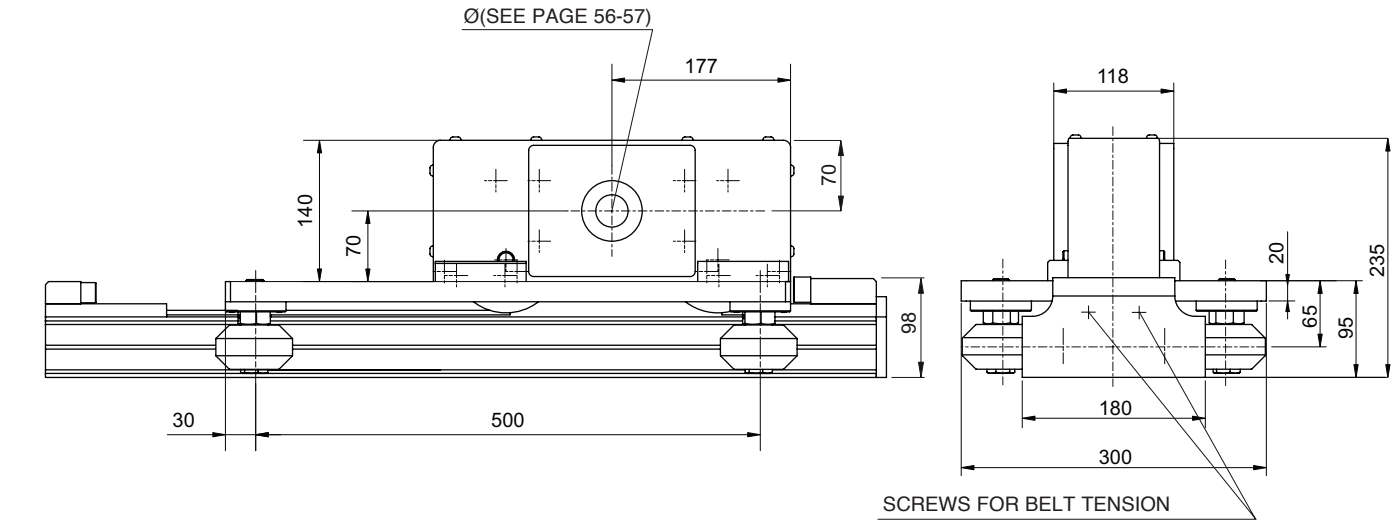
Weights		
Inertia of the pulley	0.0013	[kgm^2]
Belt weight	0.19	[kg/m]
Carriage weight	11.5	[kg]
Base module (stroke=0)	M_{base}=18.5	[kg]
1,000 mm profile	q=11.5	[kg]

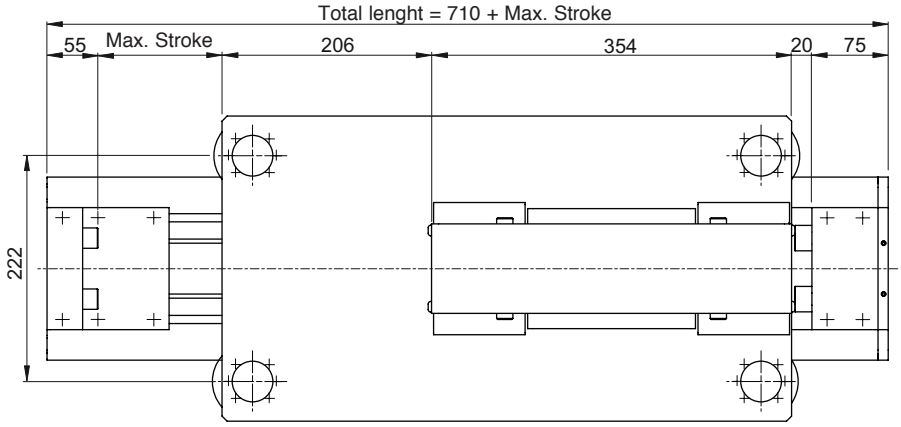
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

ZCY 180

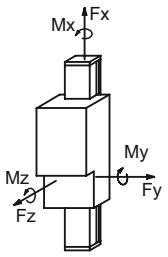
Registered model

Accessories: see page 11





IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.



Fx= Max belt strength

Performances	ZCY 180	
Max. stroke	6,750	[mm]
Max. speed	4	[m/s]
Max. acceleration	15	[m/s^2]
Repositioning accuracy	± 0.6	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCY 180	220	350	280	3,000	2,400	1,800

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Assembly positions and load direction, see page 10

Constructive data		
Belt	50ATL10	
Slide	4 Rollers Ø 76	[mm]
Load bearing profile	Sys -1G (see page 15)	
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

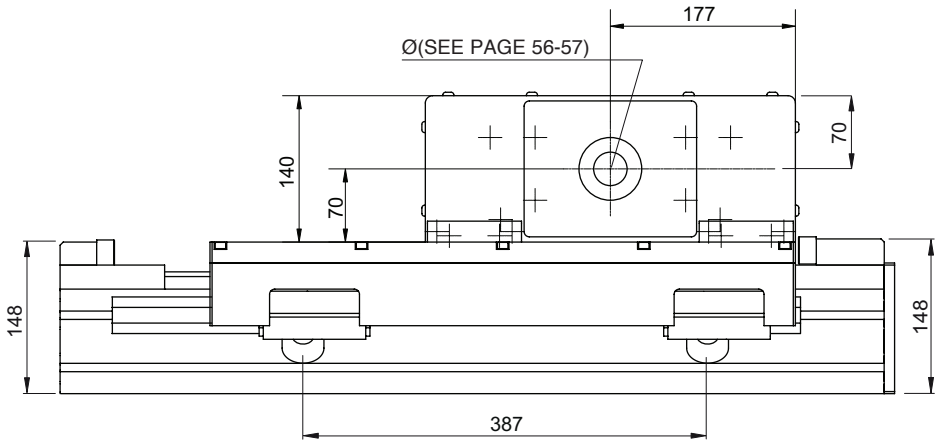
Weights		
Inertia of the pulley	0.0067	[kgm^2]
Belt weight	0.34	[kg/m]
Carriage weight	23.2	[kg]
Base module (stroke=0)	M_{base}=33.5	[kg]
1,000 mm profile	q=12.5	[kg]

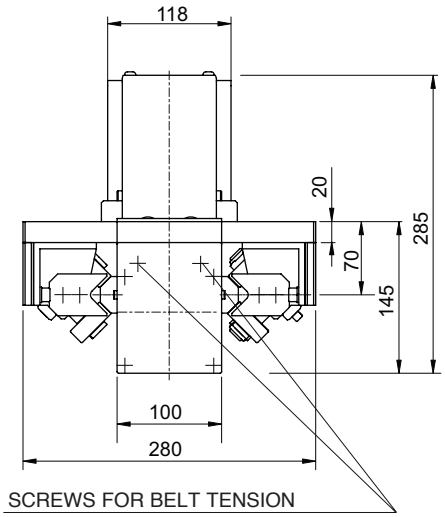
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

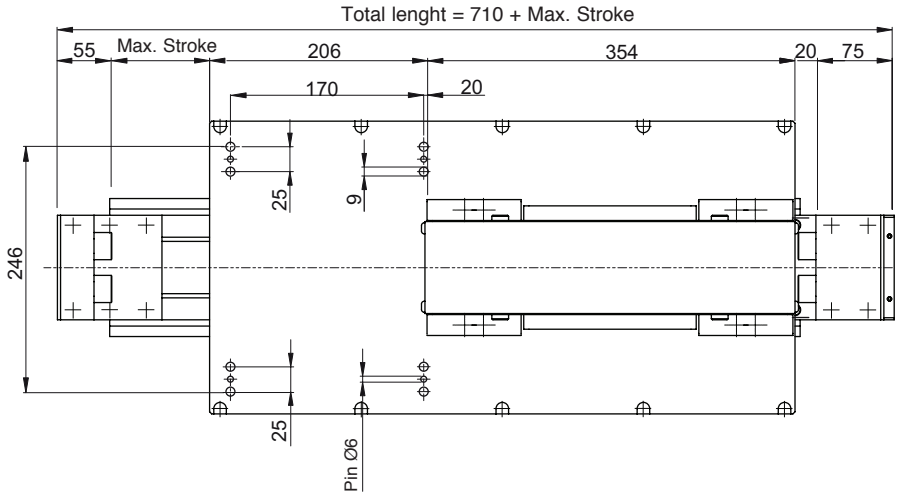
ZCRQ 100

SUITABLE FOR VERTICAL AND HORIZONTAL ASSEMBLY

Accessories: see page 11







IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	**ZCRQ 100**	
Max. stroke	5,300	[mm]
Max. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCRQ 100	360	1,200	1,200	4,000	7,320	7,320

The dynamic values shown do not refer to the max. theoretical load capacity.
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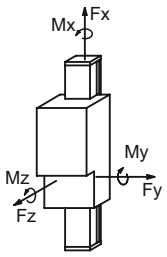
In case of peak forces acting together please ask the technical dept



Fx= Max belt strength

Assembly positions and load direction, see page 10

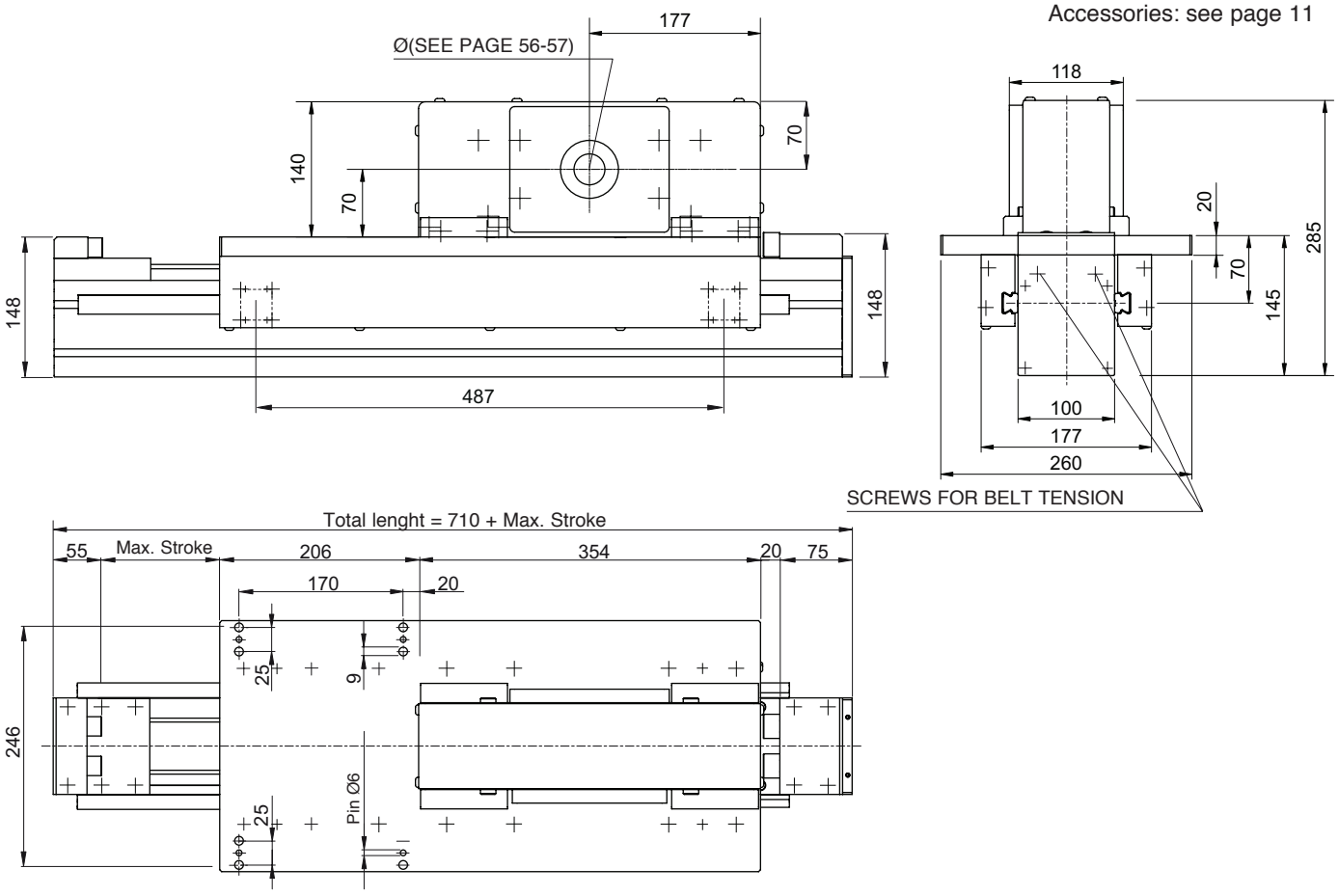
Constructive data		
Belt	50 ATL 10	
Slide	4 slides 2 roll. Ø 40	[mm]
Load bearing profile	MA 1-5	(see page 13)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

Weights		
Inertia of the pulley	0.0067	[kgm^2]
Belt weight	0.34	[kg/m]
Carriage weight	25	[kg]
Base module (stroke=0)	M_{base}=36.5	[kg]
1,000 mm di profile	q=16.5	[kg]

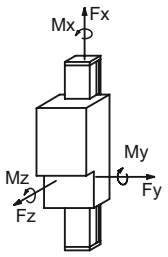
To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

ZCL 100

Accessories: see page 11



IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.



Fx= Max belt strength

Performances	ZCL 100	
Max. stroke	5,300	[mm]
Max. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCL 100	480	1,630	1,840	4,000	7,360	8,260

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Constructive data		
Belt	50 ATL 10	
Slide	4 caged ball roller slides 20	
Load bearing profile	MA 1-5	(see page 13)
Pulley Ø	95.49	[mm]
Linear displacement per rev.	300	[mm]

Weights		
Inertia of the pulley	0.0067	[kgm^2]
Belt weight	0.34	[kg/m]
Carriage weight	24.4	[kg]
Base module (stroke=0)	M_{base}=36.6	[kg]
1,000 mm profile	q=15.2	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

ZCRQ 170 - ZCERQ 170

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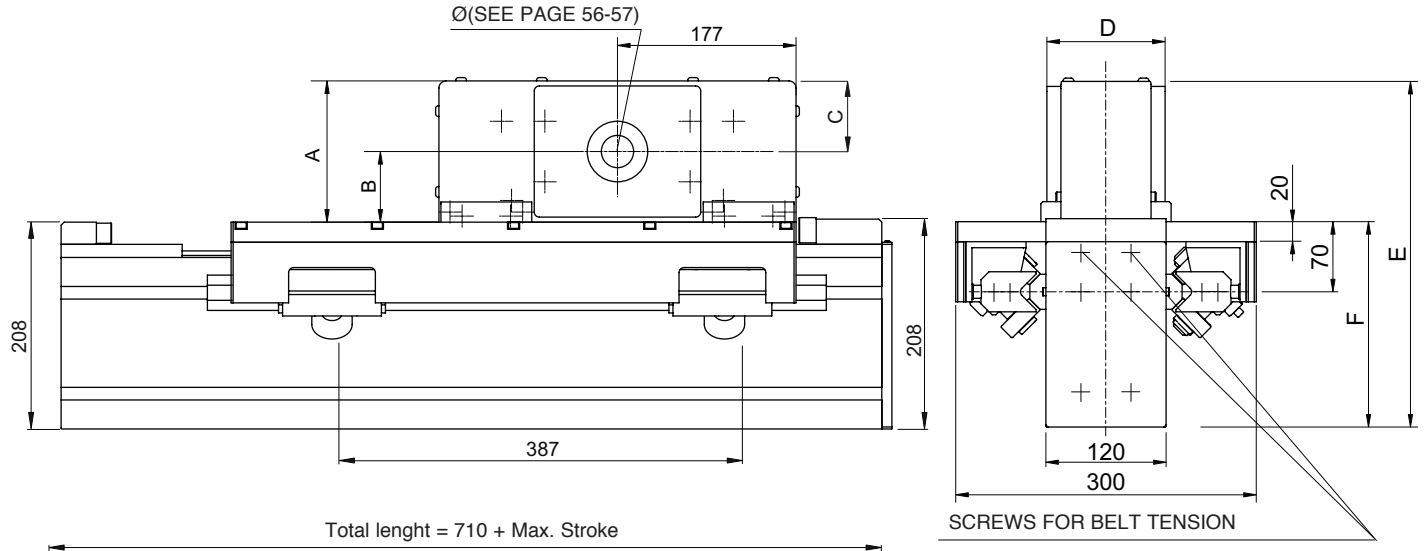
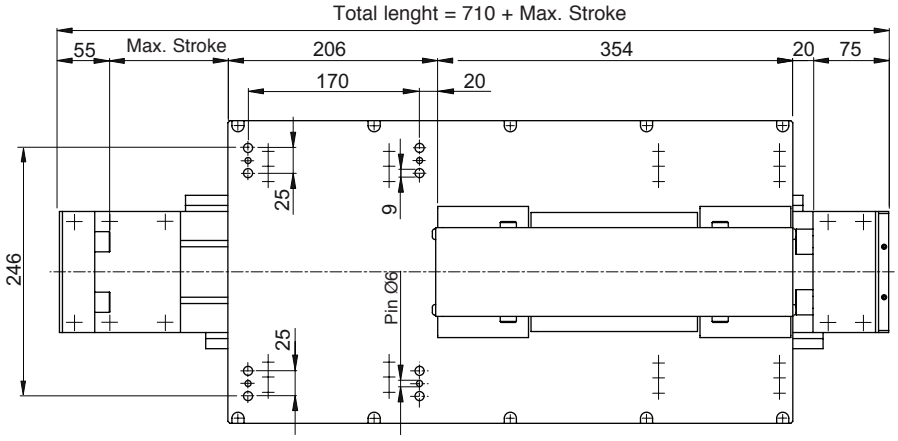


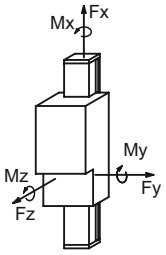


IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	ZCRQ 170 - ZCERQ 170	
Max. stroke	5,300	[mm]
Max. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCRQ 170	440	1,485	1,485	4,000	7,620	7,620
ZCERQ 170	440	1,485	1,485	6,000	7,620	7,620



Fx= Max belt strength

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Assembly positions and load direction, see page 10

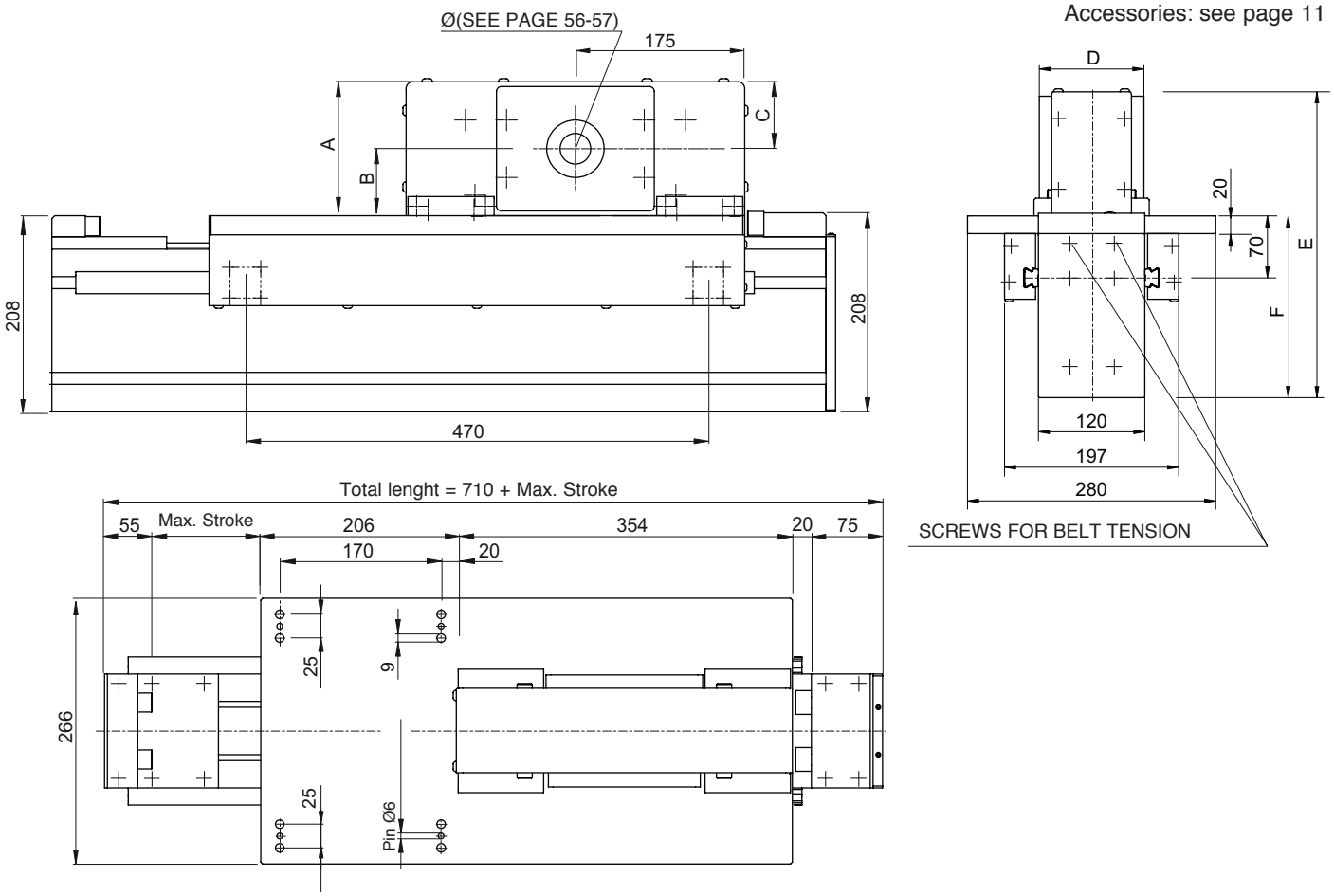
Belt	A	B	C	D	E	F
50	140	70	70	118	345	205
75	164	82	82	143	379	215

Constructive data	ZCRQ 170	ZCERQ 170	
Belt	50 ATL 10	75 ATL 10	
Slide	4 slides 2 roll. Ø 40		[mm]
Load bearing profile	Statyca	(see page 14)	
Pulley Ø	95.49		[mm]
Linear displacement per rev.	300		[mm]

Weights	ZCRQ 170	ZCERQ 170	
Inertia of the pulley	0.0067	0.010	[kgm^2]
Belt weight	0.34	0.51	[kg/m]
Carriage weight	27.6	32	[kg]
Base module (stroke=0)	M_{base}=47	M_{base}=51.4	[kg]
1,000 mm profile	q=25	q=25	[kg]

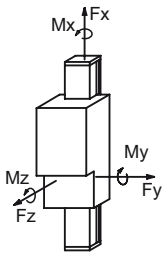
To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

Accessories: see page 11



IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	ZCL 170 - ZCEL 170	
Max. stroke	5,300	[mm]
Max. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]



Fx= Max belt strength

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCL 170	810	2,940	4,560	4,000	10,400	12,000
ZCEL 170	810	2,940	4,560	6,000	10,400	12,000

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Belt	A	B	C	D	E	F
50	140	70	70	118	345	205
75	164	82	82	143	379	215

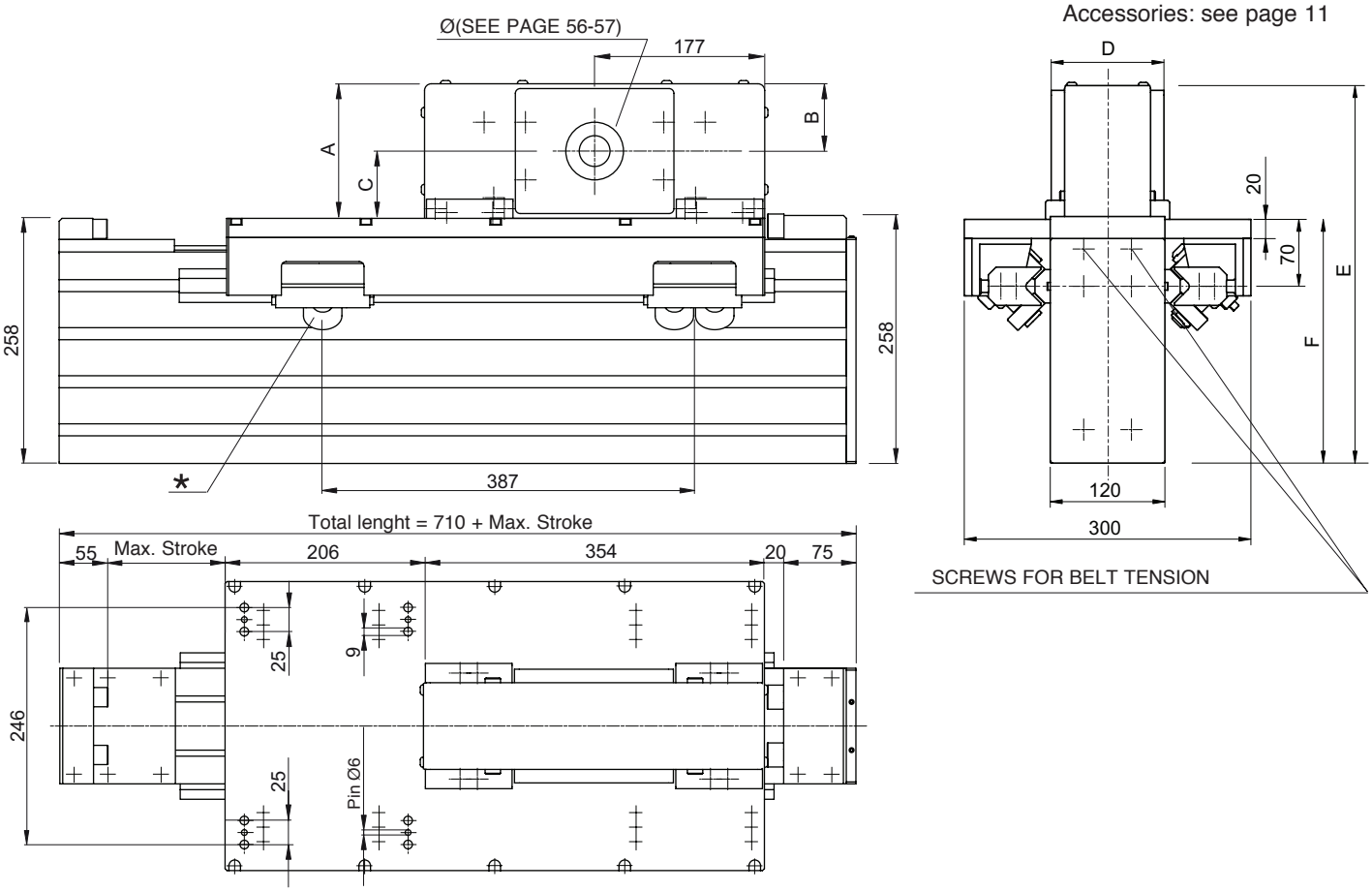
Constructive data	ZCL 170	ZCEL 170	
Belt	50 ATL 10	75 ATL 10	
Slide	4 caged ball roller slides 25		
Load bearing profile	Statyca	(see page 14)	
Pulley Ø	95.49		[mm]
Linear displacement per rev. 300			[mm]

Weights	ZCL 170	ZCEL 170	
Inertia of the pulley	0.0067	0.010	[kgm^2]
Belt weight	0.34	0.51	[kg/m]
Carriage weight	27.6	31.6	[kg]
Base module (stroke=0)	M_{base}=46.2	M_{base}=50.2	[kg]
1,000 mm profile	q=24	q=24	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

ZCRQ 220 - ZCERQ 220

SUITABLE FOR VERTICAL AND HORIZONTAL ASSEMBLY
Accessories: see page 11



IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

*: Please specify the roller orientation according to the barycentre of the applied load. Values corresponding to the most favourable load position.

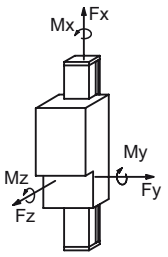
Performances	ZCRQ 220 - ZCERQ 220	
Max. stroke	11,300	[mm]
Mas. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCRQ 220	440	1,900(*)	1,485	4,000	7,620	9,500(*)
ZCERQ 220	440	1,900(*)	1,485	6,000	7,620	9,500(*)

The dynamic values shown do not refer to the max. theoretical load capacity. They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Assembly positions and load direction, see page 10



Fx= Max belt strength

Belt	A	B	C	D	E	F
50	140	70	70	118	395	255
75	164	82	82	143	429	265

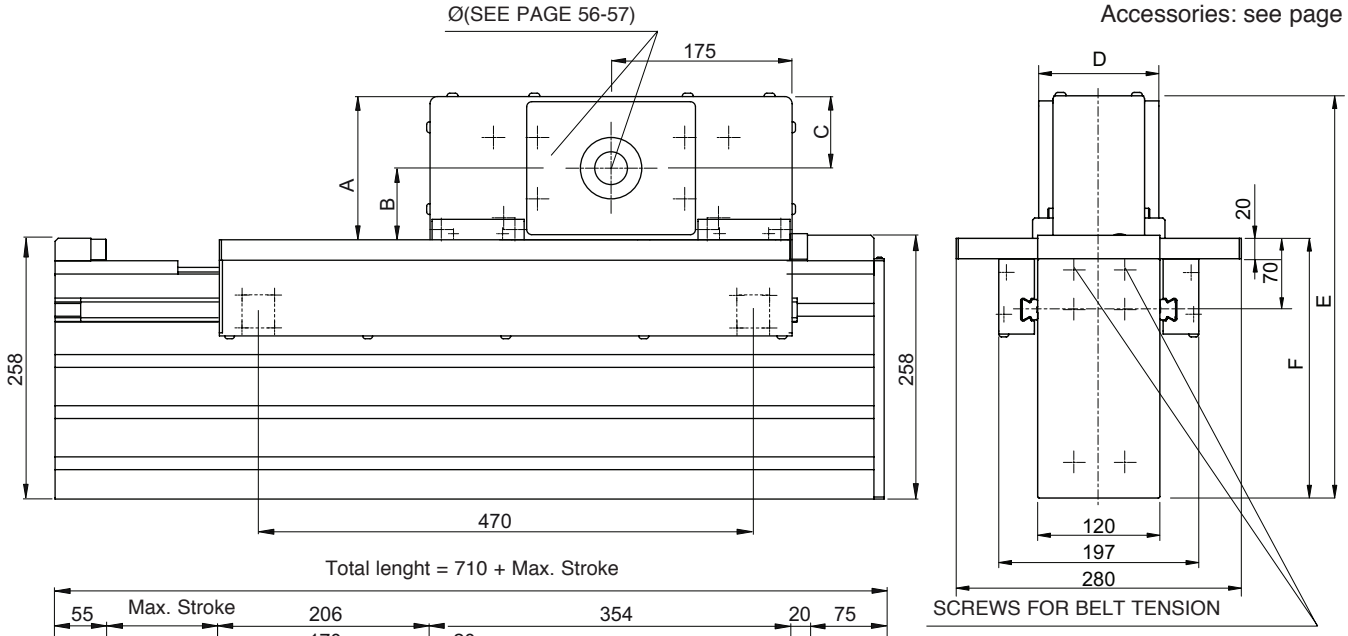
Constructive data	ZCRQ 220	ZCERQ 220	
Belt	50 ATL 10	75 ATL 10	
Slide	4 slides 3 rollers Ø 40		[mm]
Load bearing profile	Logyca	(see page 14)	
Pulley Ø	95.49		[mm]
Linear displacement per rev.	300		[mm]

Weights	ZCRQ 220	ZCERQ 220	
Inertia of the pulley	0.0067	0.010	[kgm^2]
Belt weight	0.34	0.51	[kg/m]
Carriage weight	26	30	[kg]
Base module (stroke=0)	M_{base}=52	M_{base}=56	[kg]
1,000 mm profile	q=33.6	q=34	[kg]

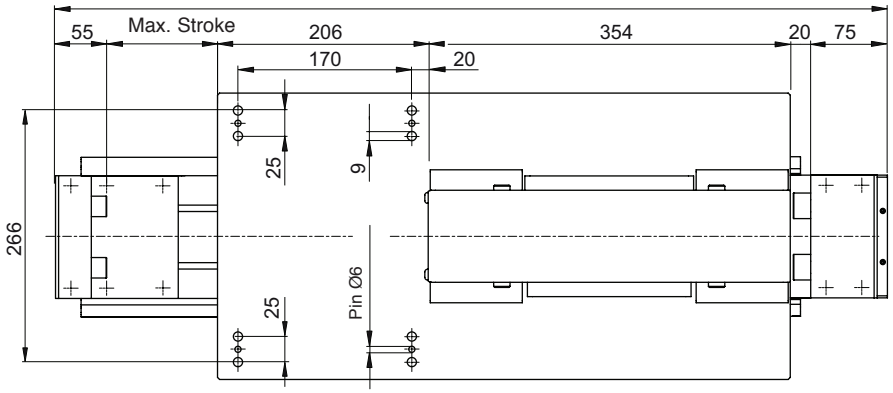
To calculate the module weight use the following formula: **$M=M_{base}+q\cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

ZCL 220 - ZCEL 220

SUITABLE FOR VERTICAL AND HORIZONTAL ASSEMBLY
Accessories: see page 11

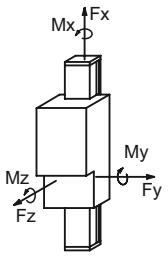


Total lenght = 710 + Max. Stroke



IMPORTANT: when pairing ZC... modules with TC... modules, please check the required Z axis stroke, as this could be limited by the size of the module plates sizes.

Performances	ZCL 220 - ZCEL 220	
Max. stroke	11,305	[mm]
Max. speed	4	[m/s]
Max. acceleration	25	[m/s^2]
Repositioning accuracy	± 0.1	[mm]



Fx= Max belt strength

Suggested working load conditions

Module	M_x[Nm]	M_y[Nm]	M_z[Nm]	F_x[N]	F_y[N]	F_z[N]
ZCL 220	810	2,940	4,560	4,000	10,400	12,000
ZCEL 220	810	2,940	4,560	6,000	10,400	12,000

The dynamic values shown do not refer to the max. theoretical load capacity.
They include a safety coefficient for automated machinery.
In case of peak forces acting together please ask the technical dept

Belt	A	B	C	D	E	F
50	140	70	70	118	395	255
75	164	82	82	143	429	265

Constructive data	ZCL 220	ZCEL 220	
Belt	50 ATL 10	75 ATL 10	
Slide	4 caged ball roller slides 25		
Load bearing profile	Logyca	(see page 14)	
Pulley Ø	95.49		[mm]
Linear displacement per rev.	300		[mm]

Weights	ZCL 220	ZCEL 220	
Inertia of the pulley	0.0067	0.010	[kgm^2]
Belt weight	0.34	0.51	[kg/m]
Carriage weight	27.5	37.5	[kg]
Base module (stroke=0)	M_{base}=53	M_{base}=57	[kg]
1,000 mm profile	q=32.3	q=32.7	[kg]

To calculate the module weight use the following formula: **$M=M_{base}+q \cdot stroke_{max}/1{,}000$** ($stroke_{max}$ in mm)

Holes in drive pulleys for shaft shrink-discs

Registered model

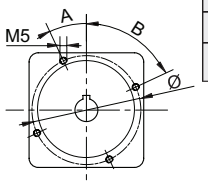
The motor connection is pre-engineered directly on the drive head by means of a removable flange, but integrated in the actual head. The drive shaft and/or the driven shaft are locked into the pulley by shrink-discs. (The gearbox can be easily removed without disassembling the head). Please see page 10 to identify the desired motor side (left or right); page 56 for shrink-disc and flange diameter and page 11 for the order code setting. Out-of-standard diameters are available upon request.

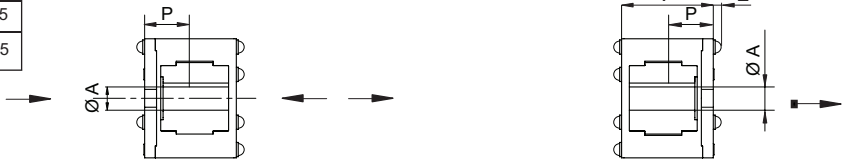
gearbox entry

:input A
:input B
output B
output A
driven shaft side

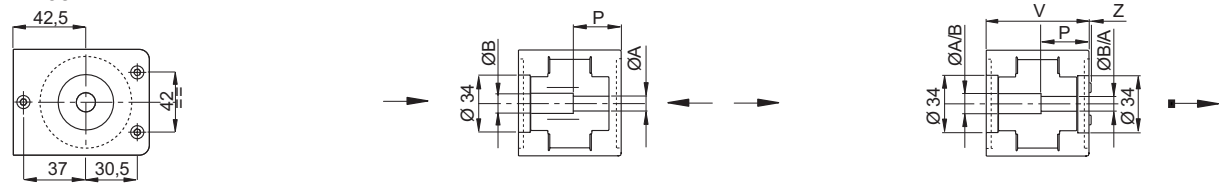
Series KC 30-50

	A	B	Ø
KCH 30	30°	60°	75
KCH 50	25°	65°	95

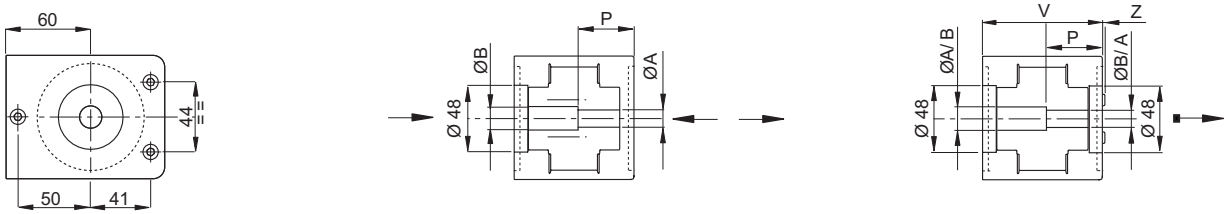




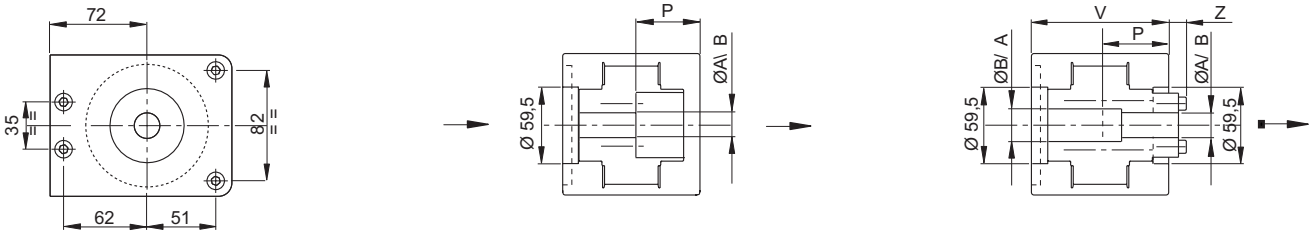
Series MC 65



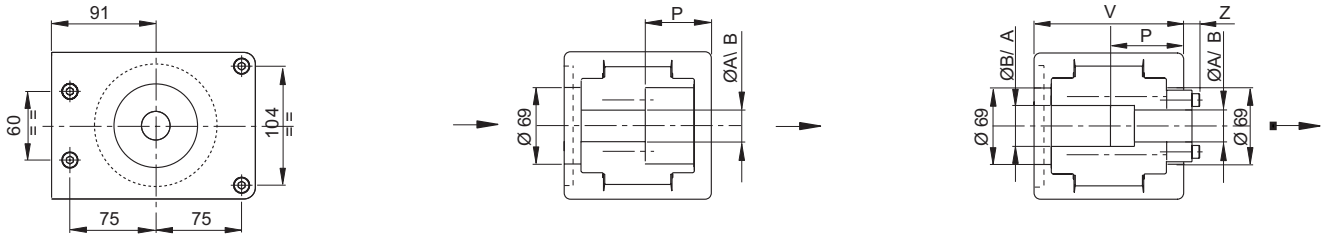
Serie MC 80



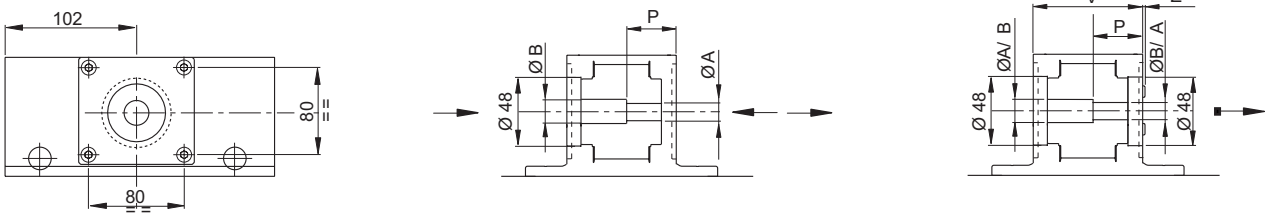
Series MC 105 - TC 180



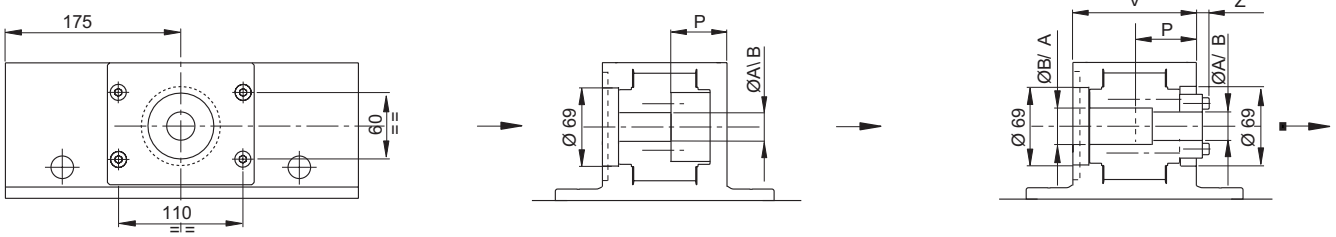
Series TC 170/200 - TC 220 - TC 280 - TC 360



Series ZC 60 - ZC 90



Series ZC 100 - ZCY 180 - ZC 170-220 - ZCE 170-220



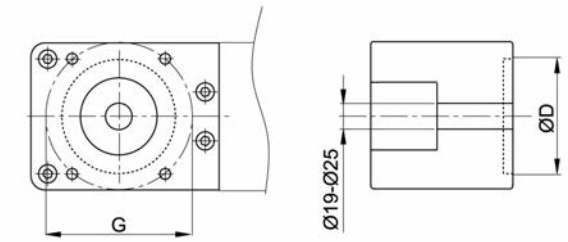
Module	A Ø [mm]	B Ø [mm]	V [mm]	P [mm]	Z [mm]
KCH30 - KCH50	12H7		40	34	4
	14H7		68	34	4
MC 65 - TC 100	12H7		67	34	0
		14H7	67	34	0
MC 80	16H7		80	52.4	1
		19H7	80	49.4	1
		20H7	80	49.4	1
MC 105 - TC 180	19H7		105	49	13.5
		25H7	105	51	8
TC 170 - TC 200	25H7		117	54.5	12.5
		32H7	117	57.5	7
TC 220 - TC 280 - TC 360	25H7		142	79.5	12.5
		32H7	142	82.5	7
		40H7	142	82.5	7
ZC 60 - ZC 90	16H7		100	62.4	0
		19H7	100	62.4	0
		20H7	100	62.4	0
ZC 100 - ZCY 180	25H7		108	48.5	11.5
		32H7	108	52.5	6
ZC 170 - 220	25H7		108	48.5	11.5
		32H7	108	52.5	6
		40H7	108	52.5	6
ZCE 170 - 220	25H7		143	65	12
		32H7	143	95	12
		40H7	143	95	12

Phosphating of drive and driven pulleys.

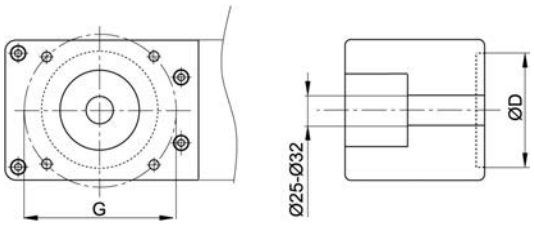
Gearbox adapting plates

Standard machining for planetary gearboxes - MP or MPTR, LP, EP series.
Machining is performed directly on the removable flange in a symmetric position, suitable for both sides.

Ex. module: MC 105



Ex. module: TC 280



Drilled flange: code E
Blind flange: code X

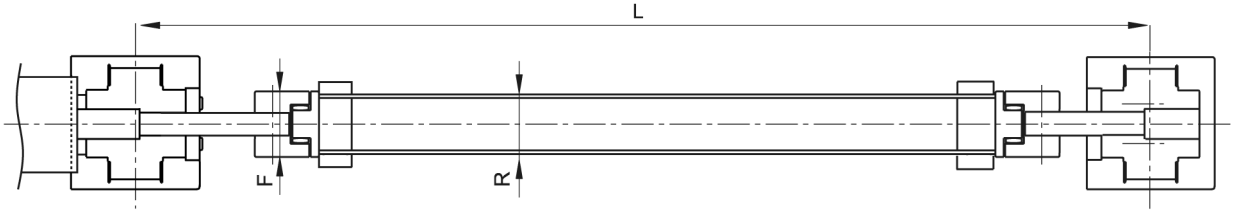
Linear module	Gearbox code			Size
Series		D	Ø	G
MC 65	LP 050	35	12	44
KC 30-50	EP55	32	12	40
	MP053	32	12	40
MC 80-105 - ZC 60	MPTR080	50	19	65
	LP070	52	16	62
ZC 90	EP75 AA	40	14	52
MC 105 - TC-ZC 100	MPTR105	70	25	85
MC 105 - TC 180	LP090	68	22	80
	EP90 TT	50	19	65
	MPTR130	80	32	110
TC 170-360	LP120	90	32	108
ZC 170-220	EP120 TT	70	25	85

Connecting shafts for parallel modules

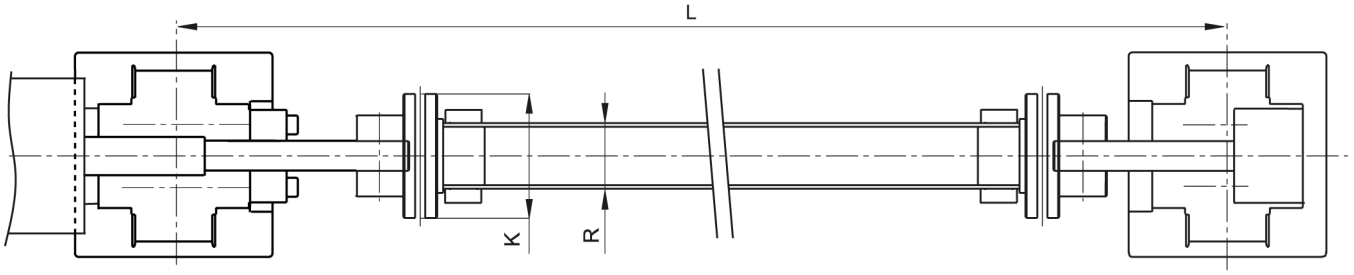
We can supply standard hollow shaft connections, according to your application requirements.
Please specify the type of module to be connected, together with speed, “L” centre-distance, working and peak torques, accuracy.
Some simplified solutions with solid shafts are available for low-speed applications and with “L” of up to 2,000 mm.
If high-speeds and/or “L” of more than 2,000 mm are needed, please ask our technical dept. for the shaft scaling.

The complete kit includes all the components needed to make the connection: tube, shrink-discs, shaft crop ends for connection between pulleys and shrink-discs, any supports.
Tube material: 6060 aluminium alloy
The customer is responsible for ensuring compliance with accident prevention rules in relation to all rotating parts.

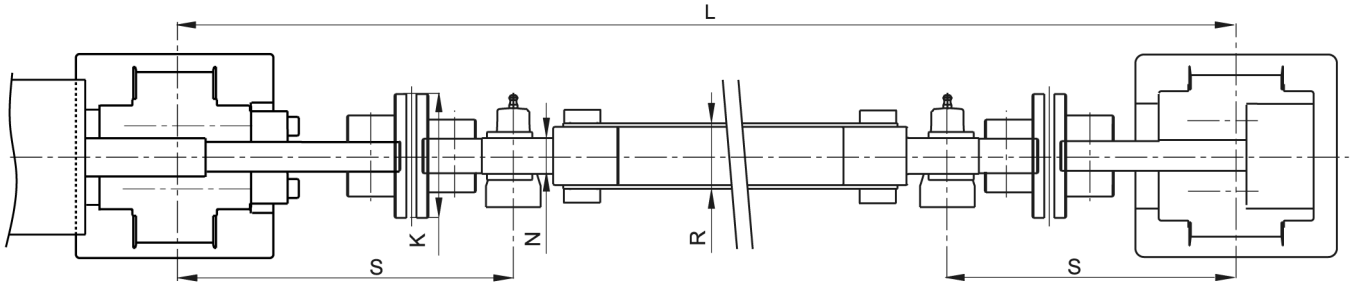
Type 1 - Elastic joint connecting shafts, normally suitable for low-speeds



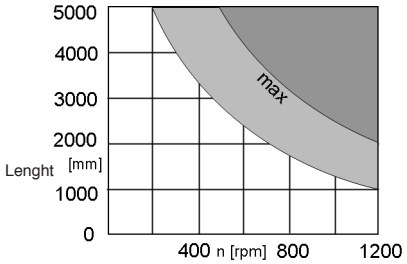
Type 2 - Stainless steel blade joint connecting shafts, suitable for backlash-free transmissions

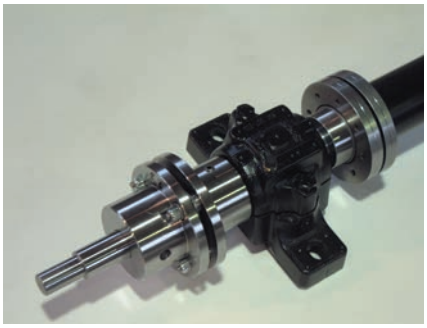


Type 3 - Stainless steel blade joint connecting shafts and pedestal bearings, suitable for backlash-free transmissions



Preliminary table n° g. max





R(*)	K	F	N	S	Lmax	MTwork [Nm]	Mom.Inertia. [Kgm²]	Type 1: Code/L	Type 2: Code/L	Type 3: Code/L
40	67	55	20	200	6,200	20	0.0028 + 0.46 x L. x10^{-6}	436.0948	436.0957	436.0965
50	81	65	25	235	6,300	35	0.0092 + 0.66 x L. x10^{-6}	436.0949	436.0958	436.0966
50	93	80	25	235	6,300	70	0.0161 + 1.34 x L. x10^{-6}	436.0951	436.0971	436.0974
70	104	95	25	235	6,400	100	0.0293 + 2.93 x L. x10^{-6}	436.0952	436.0960	436.0968
80	126	120	25	250	6,400	190	0.0793 + 4.5 x L. x10^{-6}	436.0955	436.0963	436.0984
90	143	-	-	-	6,500	300	0.1456 + 6.53 x L. x10^{-6}	-	436.0986	436.0987
110	185	-	-	-	6,000	420	0.3499 + 12.3 x L. x10^{-6}	436.0144	436.0145	436.0146

The S value can vary by ± 20%, Lmax by ± 3%, according to the chosen type. Please contact our technical dept.

Spare rollers with pins

Make sure that all the components are locked in place with the appropriate screws. The recommended tightening torque for pin locking screws and nuts is 50 Nm.

Max. load factors for hardened and tempered guides

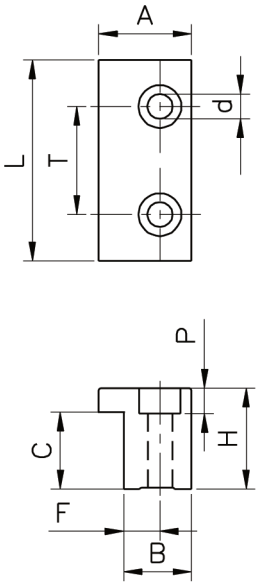
Roller	Cw [N]	C0w[N]	Fr amm.[N]	V max.
Ø30	5,000	3,000	1,350	7 m/s
Ø40	9,800	6,200	2,600	7 m/s
Ø52	15,800	10,500	4,400	6 m/s
Ø62	21,100	14,500	5,600	5 m/s

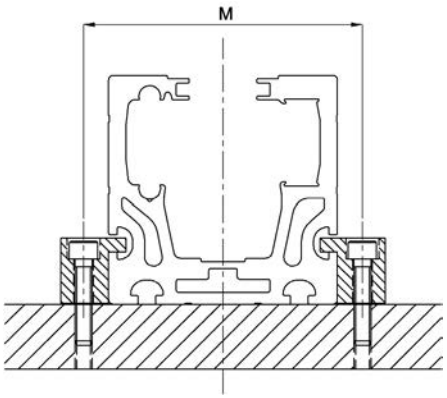
Max. load factors for hardened guides

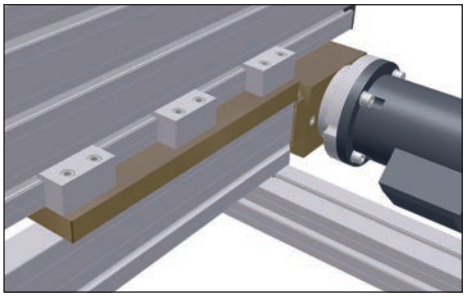
Roller	Cw [N]	C0w[N]	Fr amm.[N]	V max.
Ø30	5,000	3,000	400	2 m/s
Ø40	9,800	6,200	800	13 m/s
Ø52	15,800	10,500	1,400	2.5 m/s
Ø62	21,100	14,500	1,900	2 m/s

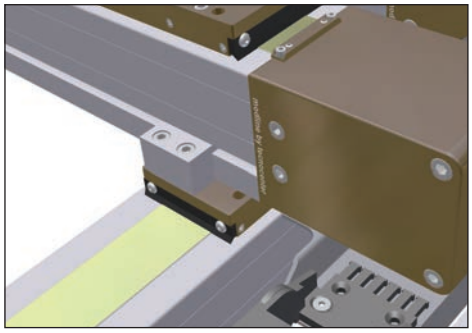
Spare roller with pin	Weight [kg]	Code
Ø30 Concentric	0.02	**406.0056**
Ø40 Concentric	0.22	**205.0464**
Ø40 Eccentric (± 0.75 mm)	0.25	**205.0463**
Ø52 Concentric	0.4	**205.0163**
Ø62 Concentric	0.55	**205.0165**

Mounting brackets







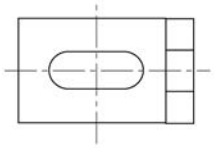


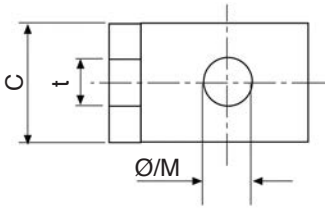
Material: aluminium alloy 6082

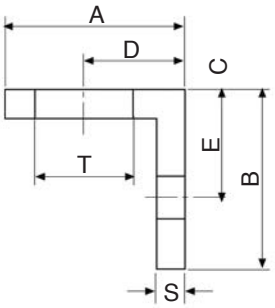
Module type	bxh	A	L	T	d	H	P	C	F	B	M	Code
KC 30	30x30	25	25	-	6.7	17	6.8	10.6	10	18	40	**415.1105**
MC 65	67x65	25	50	25	6.7	20	6.8	13.5	10	18	87	**415.0388**
MC 80	80x80	25	50	25	6.7	25	6.8	18.6	10	18	100	**415.0760**
KC 50, TC-ZC 100		25	50	25	6.7	27	6.8	20.6	10	18	120	**415.0764**
MC 105	105x105	30	50	25	9	30	9.5	23.6	12	22	129	**415.0761**
TC 180	180x90	30	50	25	9	25	9.5	18	12	25	204	**415.0773**
TC 170	120x170										198	
TC 200	120x200	30	90	50	11	40	11	28.3	14	25	228	**415.0762**
TC 220	120x220										248	
TC 280	170x280	30	90	50	11	20	11	11.3	14	25	308	**415.0763**
TC 280Vert.	280x170	30	90	50	11	20	11	13.5	14	25	198	**915.1174**

Accessories and screws

Assembly brackets





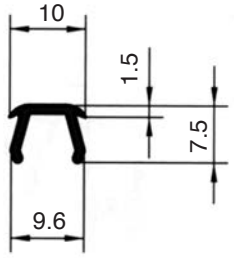


Material: natural, anodised anticorodal alloy.

Thread								Code	
A	B	C	D	E	S	Txt	ØM	Ø	M
45	45	20	25	25	5	20x6.5	6	**A30-76**	**A 30-86**
35	25	20	19	15	5	20x6.5	4	**A30-54**	**A 30-64**
35	25	20	19	15	5	20x6.5	5	**A30-55**	**A 30-65**
35	25	20	19	15	5	20x65	6	**A30-56**	**A 30-66**
25	25	15	14	15	4	13.5x5.5	3	**B30-53**	**B 30-63**
25	25	14	14	15	4	13.5x5.5	4	**B30-54**	**B 30-64**
25	25	15	14	15	4	13.5x5.5	5	**B30-55**	**B 30-65**
25	25	15	14	15	4	13.5x5.5	6	**B30-56**	**B 30-66**

Suitable for all the modules

Filler strips

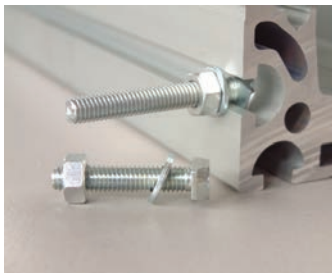


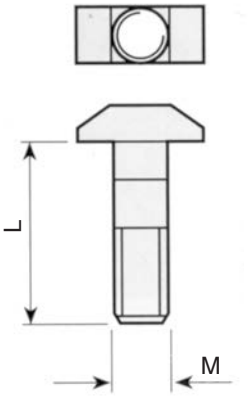
PVC filler strips, grey or black L=5,000 - 6,000 mm
for any longitudinal 8 mm slot

Suitable for series: **KC 50, MC 80-105, ZC 60-90-100-170, TC 100-180**

Color	Code A /Lenght
grey	**Cod.A39-25/5000**
black	**Cod.A39-26/5000**
orange (on request)	**Cod.A39-25/6000 A**

T Bolts





Assembly in longitudinal slots. Material: galvanised steel. Can be inserted through the profile slot.

Code A: KC 50, MC 80-105, ZC 60-90-100-170, TC 100-180
Code B: KC 30, MC 65

M x L	Code B	M x L	Code A
M 6x15	**B35-15**	M8x20	**A35-20**
M 6x20	**B35-20**	M8x25	**A35-20**
M 6x30	**B35-30**	M8x30	**A35-30**
M 6x40	**B35-40**	M8x40	**A35-40**
		M8x60	**A35-60**

Threaded inserts (suitable for the ZC series)

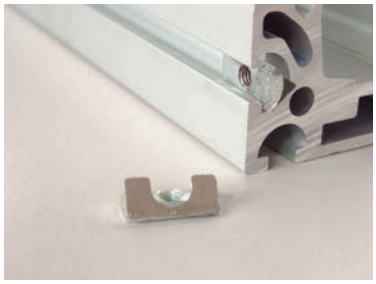
Suitable for ZC series

Material: galvanised steel

Ext. thread	Int.	a	L	Key	Code
M16	M	6	25	6	**A33-26**
M16	M	8	25	8	**A33-28**
M16	M	10	25	10	**A33-20**
M20	M	6	25	6	**207.1892**
M20	M	8	25	8	**207.1893**
M20	M	10	25	10	**207.1894**
M20	M	12	25	12	**207.2288**

Front insertable nuts and plates

Spring nut



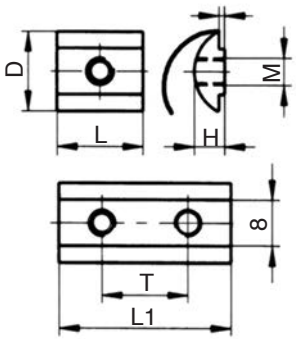


Plate suitable for every kind of module (8 mm slot).
Material: nut in galvanised steel welded to the harmonic steel spring. The B series can also be inserted through the slot.

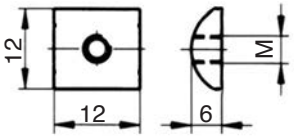
Code A: KC 50, MC 80-105, ZC 60-90-100-170, TC 100-180
Code B: KC 30, MC 65

Single plate	Code A	Code B
M5	A32-55	B32-55
M6	A32-65	B32-65
M8	A32-85	B32-85

Double plate	Code A	Code B
M6	A32-67	B32-67

Size					
Base Module	D	H	L	L1	T
MC 105, ZC 100	14	7.8	20	40	30
MC 80	11	4.1	20	40	30

Simple nut

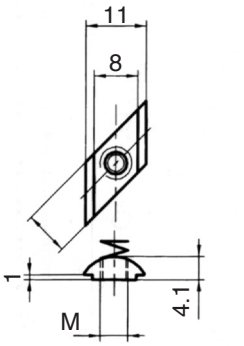


Material: galvanised steel.
Insert through the end of the profile.
Suitable for series:

KC 50, MC 80-105, ZC 60-90-100-170, TC 100-180

Thread	Code
M5	209.2431
M6	209.2432
M8	209.2433

Front insertable spring nut

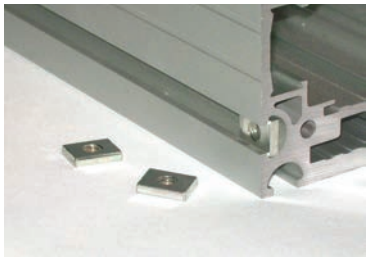


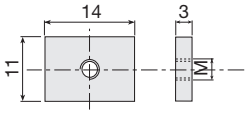
Material: galvanised steel, harmonic steel spring.
To be inserted through the slot.
Suitable for series:

KC 30, MC 65

Thread	Code B
M3	BD31-30
M4	BD31-40
M5	BD31-50
M6	BD31-60

Simple Nut





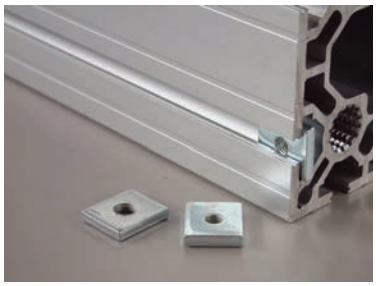
Materiale: galvanised steel.
To be inserted through the slot. Suitable for series:

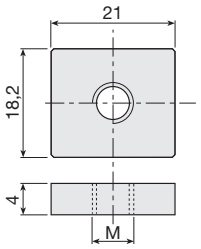
KC 30, MC 65

Thread	Code B
M4	B32.40
M5	B32.50
M6	B32.60

Threaded nuts and plates

Flat nut





Material: galvanised steel.
Insert through the end of the profile.
Retaining spring upon request.

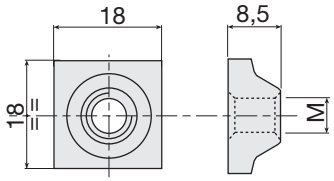
TC-ZC 100, TC 180, ZCY 180

Thread	Code
M4	**A32-40**
M5	**A32-50**
M6	**A32-60**
M8	**A32-80**
Molla	**211.1061**

Semi-rounded threaded inserts with spring

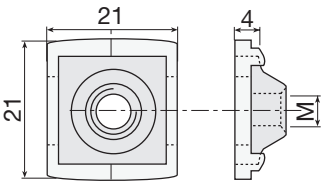
Threaded plate for base profile 45, 50 and 60. Material: galvanised steel.
Important: to be inserted through the
longitudinal slots before assembling.

Suitable for series:
TC-ZC 100, ZCY 180, TC 170-180-200-220-360, ZC 170-220



Thread	Code 18x18	Code 20x20
M4	**209.0031**	**209.0023**
M5	**209.0032**	**209.0019**
M6	**209.0033**	**209.1202**
M8	**209.0034**	**209.0467**

Plastic compound spring for vertical positioning of insert.



Spring	Code
Suitable for all inserts 18x18	**101.0732**

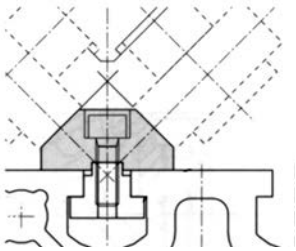
Alignment nuts

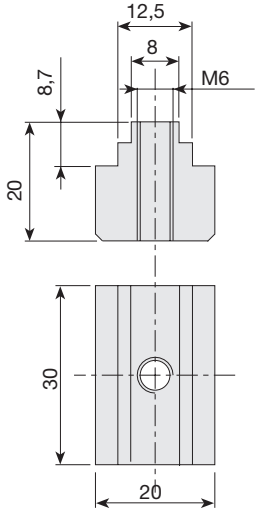
Nuts for steel guide rails

Material: galvanised steel.

Code 209.1855

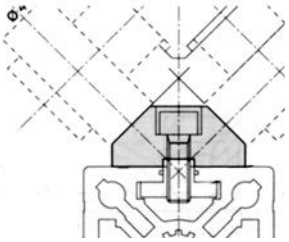
Alignment nuts.
V-shaped guide rail: 35x16
Profile with slot. 12.5 mm.
Series: **TC 170-200-220-280-360 e ZC 170-220**

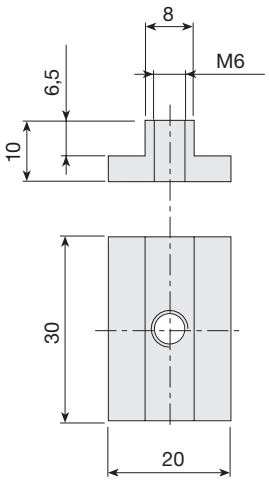




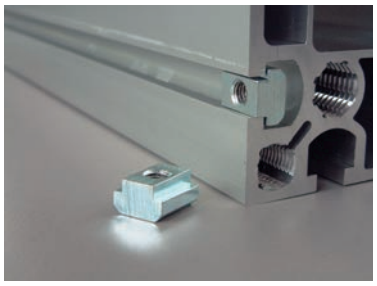
Code 209.0298

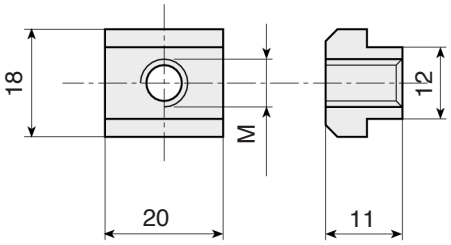
Alignment nuts.
V-shaped guide rail: 35x16
Profile with slot 8 mm.
Series: **TC-ZC 100, TC 180**





Alignment nut for slot 12.5 mm

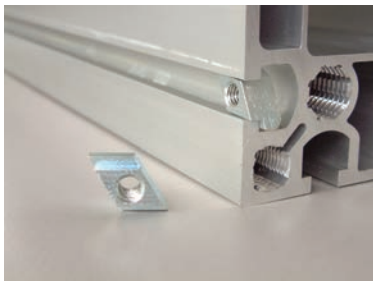


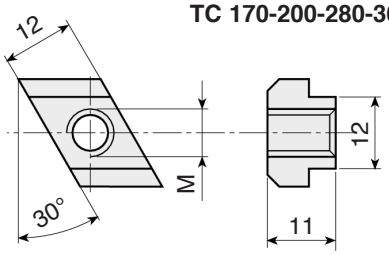


Material: galvanised steel. Suitable for series:
TC 170-200-280-360 and ZC 170-220

Thread	Code
M5	**215.1768**
M6	**215.1769**
M8	**215.1770**
M10	**215.2124**

Alignment nut for slot 12.5 mm front insertable

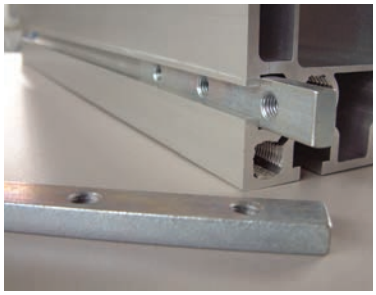


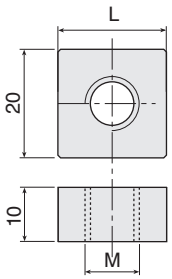


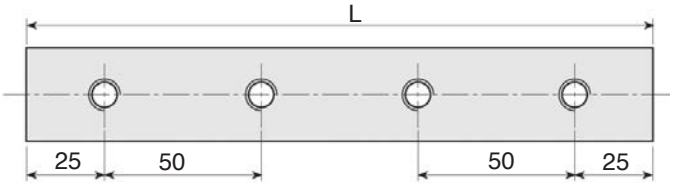
Material: galvanised steel. Suitable for series:
TC 170-200-280-360 and ZC 170-220

Thread	Code
M5	**215.1771**
M6	**215.1772**
M8	**215.1773**
M10	**215.2125**

Threaded nuts and plates







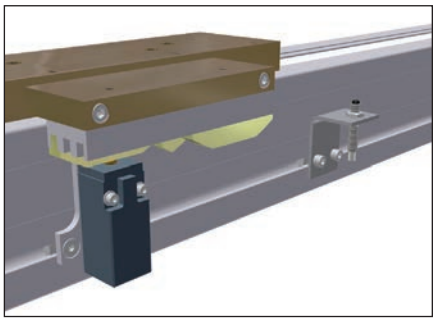
M12 (CH19) hexagonal-head screws can be used as stud bolts in profiles with 12.5 mm slots.

Material: galvanised steel. Suitable for series:
TC 170-200-220-280-360 and ZC 170-220

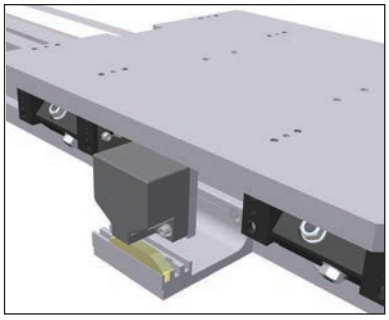
Thread	Type	L	Code
M10	1-hole plate	40	**215.0477**
M12	1-hole plate	40	**209.1281**
M10	1-hole plate	20	**209.1277**
M10	2-holes plate*	80	**209.1776**
M10	3-holes plate*	150	**209.1777**
M10	4-holes plate*	200	**209.1778**
M10	5-holes plate*	250	**209.1779**
M10	6-holes plate*	300	**209.1780**
M10	7-holes plate*	350	**209.1781**

* Hole centre-distance: 50 mm.

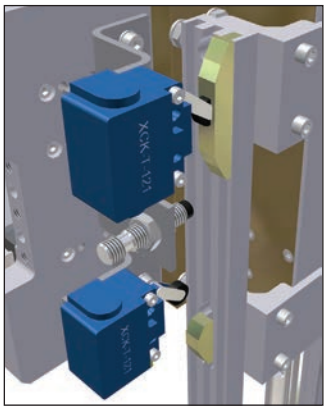
Micro-switch brackets - application examples



Mechanical and inductive micro-switches on MC series.



Multi-channel micro-switch on TC series.



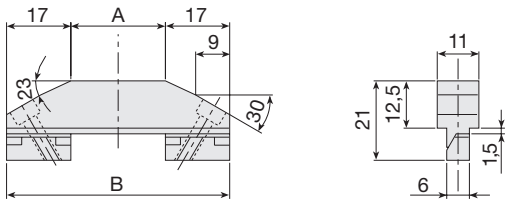
Mechanical and inductive micro-switches on MC series.

Micro-switches and brackets are supplied according to the needs of the application.
We can also supply cams and cam-holders for mechanical micro-switches in accordance with DIN standards.

Cams and cam-holders for micro-switches

Long cams

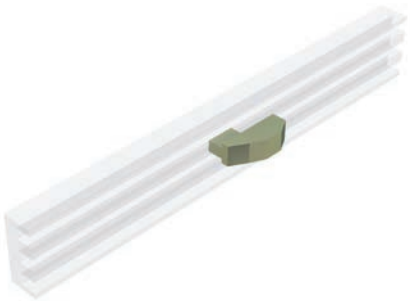
Cams in accordance with DIN 69639 except when marked "#".
Material: steel with hardened and ground surface.

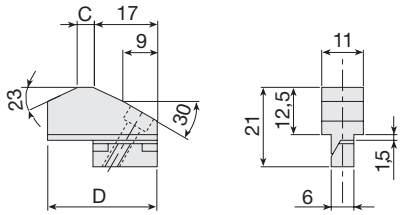


A	B	Code
25	59	**211.2132**
40	74	**211.2133**
63	97	**211.2134**
80 #	114	**211.2135**
100	134	**211.2136**

Short cams

Cams in accordance with DIN 69639
Material: steel with hardened and ground surface.

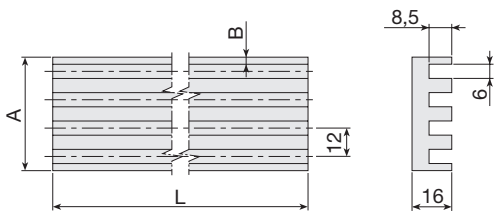




C	D	Code
0	25	**211.2128**
4	29	**211.2129**
10	35	**211.2130**
16	41	**211.2131**

Cam-holder guides

Cams in accordance with DIN 6963
Materiale: lega di alluminio 6060 anodizzato

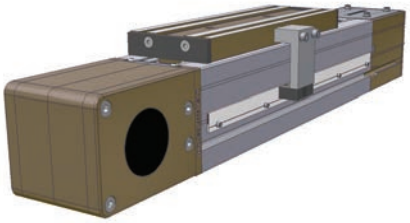


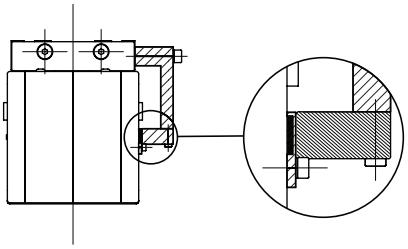
n°	B	A	L	Code
3	3	36	2,000	**202.2138**
4	5.5	53	3,000	**202.2139**
6	5.5	77	3,000	**202.2140**
8	5.5	101	3,000	**202.2141**

Special variants

Reader system with magnetic scale and sensor

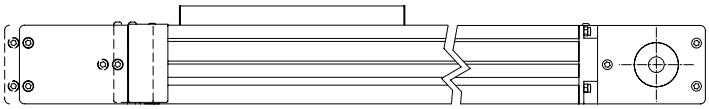
The magnetic scale is applied to the body of the module using a supporting and protective profile.
Precision of between ± 0.015 and ± 0.05 mm
Max speed = 4 ÷ 10 m/s (depending on the type)

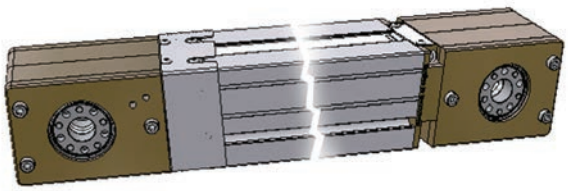




Twin drive head

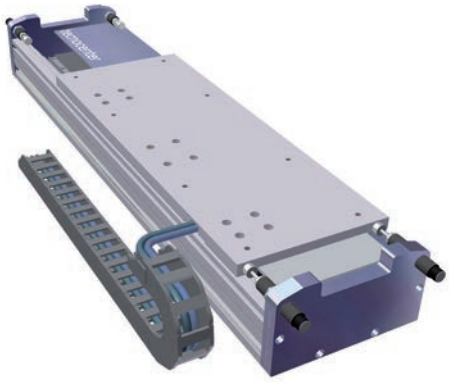
Version with drive head on both sides.

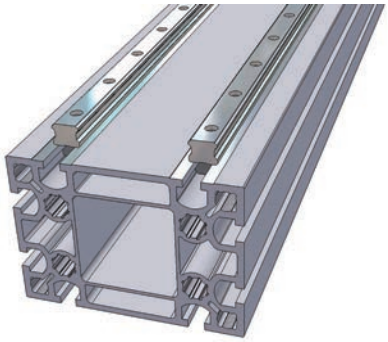




Precision profile machining

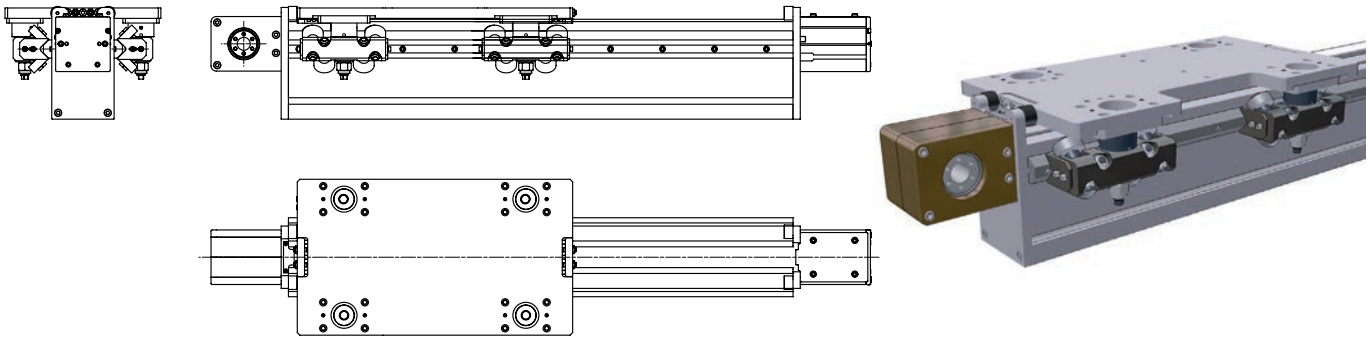
Profiles can be machined along their entire length, to provide the required precision or according to application specifications.
Example: for linear motors.





Rotatable load-bearing profile to fully exploit the moment of inertia

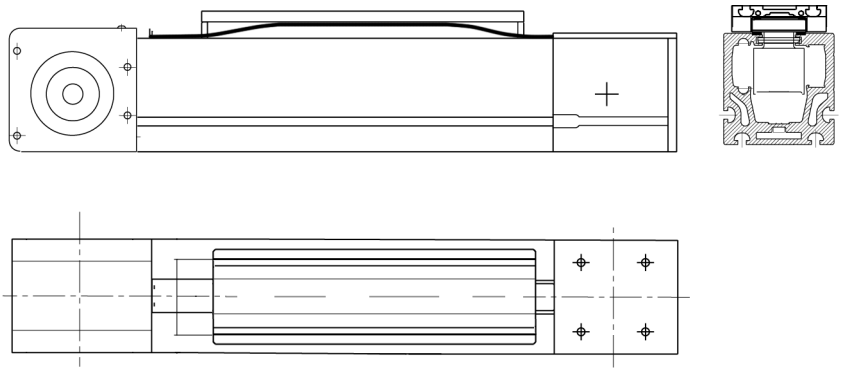
The load-bearing profile can be rotated in order to change the overall dimensions, or to fully exploit the moment of inertia.

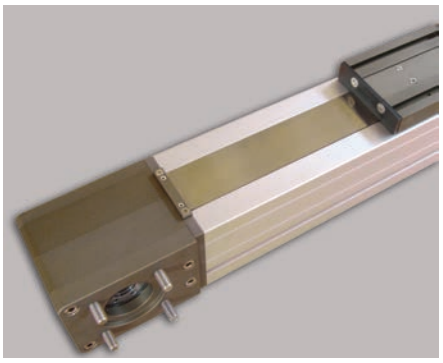


Special applications

Belt protection for series MC 65 - 80 - 105

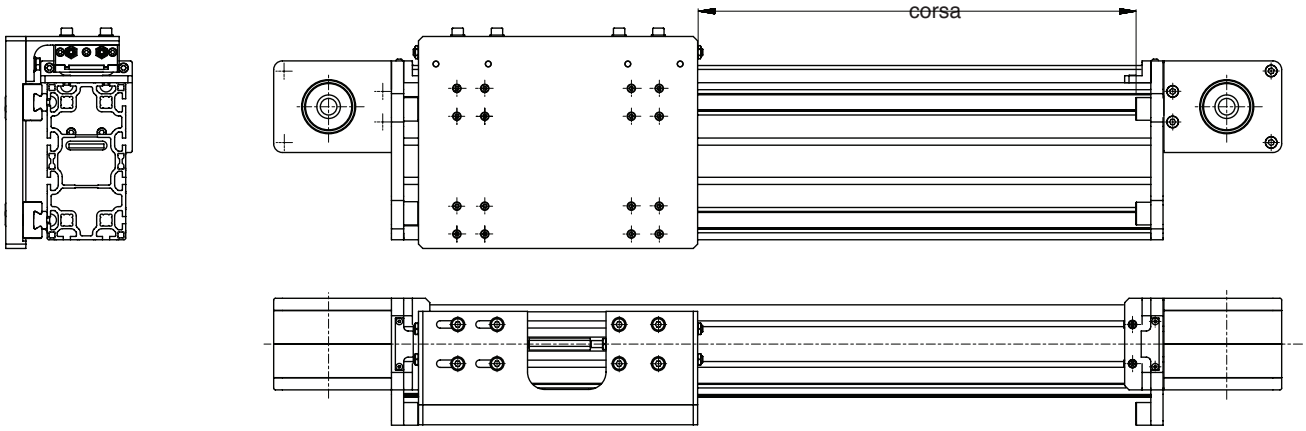
Guard system consisting of a magnetic stainless steel foil to protect the belt from dust and external agents (code: **LI**), which is attached to the profile.
NB: Avoid the use of a metallic band in the presence of ferrous filings. Optional.





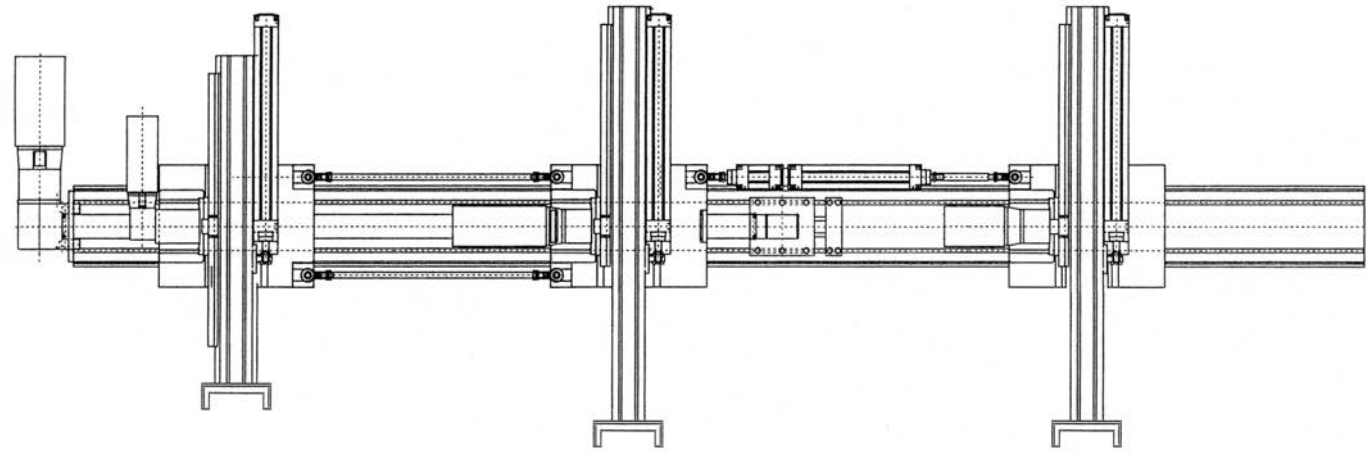
TC series of linear modules with pulley axis turned at 90°

In some applications which involve the use of high speeds and accelerations, the assembly of linear units having a vertical pulley axis and a centre-distance of more than 4 m may force the toothed belt and result in the need for premature maintenance. In this case we suggest you mount the pulleys and the belt in a horizontal position. The modification as shown in the figure below can be requested for the MODLINE TCS series. Optional.



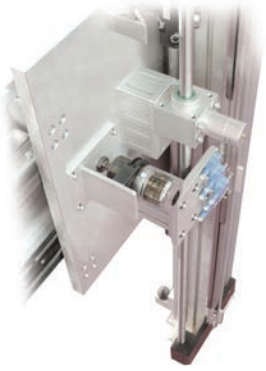
TC multi-carriage linear modules with intermediate belt transmission

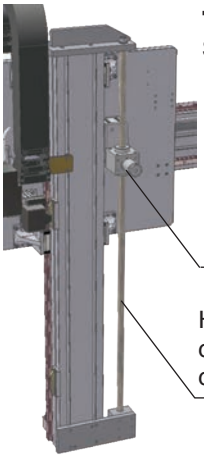
Example of horizontal transfer with integrated belt and transmission pulley support, in an intermediate position, all incorporated inside the profile. **(Registered design)**
Special feature: note the compensating cylinders and the horizontal cylinder for the different travel of carriage no. 3.



Anti-drop safety device with pneumatic brake system

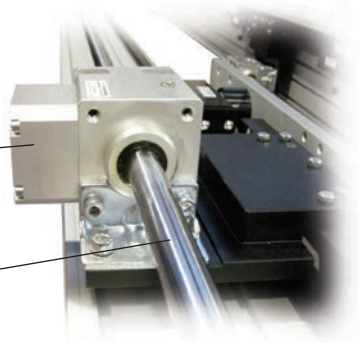
Ant-droop safety devices, available in a range of sizes, are supplied according to the type of application. For instance, they can act as a mechanical stop to block the free-falling load at any stroke point, or as a lock in static conditions at any position. Two-way blocking occurs following an unexpected pressure drop. A mechanical safety release system is available upon request (patented). Catalogue available upon request. The kit includes: braking device and rod with relative supports, micro-switch and solenoid valve.
Operating pressure 3-6 Bar.
With no pressure = locked.





Type A
Static

Type B
Dinamic,
for free-falling
loading



1- Static rod blocking device

Type	Code	Rod blocking force [N]	Stroke [mm]
A	**236.0018**	/ 1,200	/ ...
A	**236.0018**	/ 1,900	/ ...
A	**236.0018**	/ 3,000	/ ...
A	**236.0018**	/ 5,400	/ ...
A	**236.0018**	/ 7,500	/ ...
A	**236.0018**	/ 12,000	/ ...

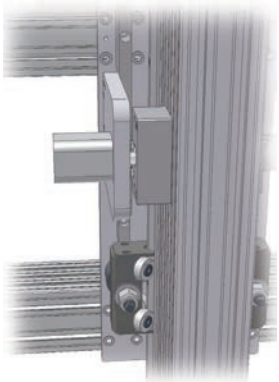
Emergency brake for free-falling load.

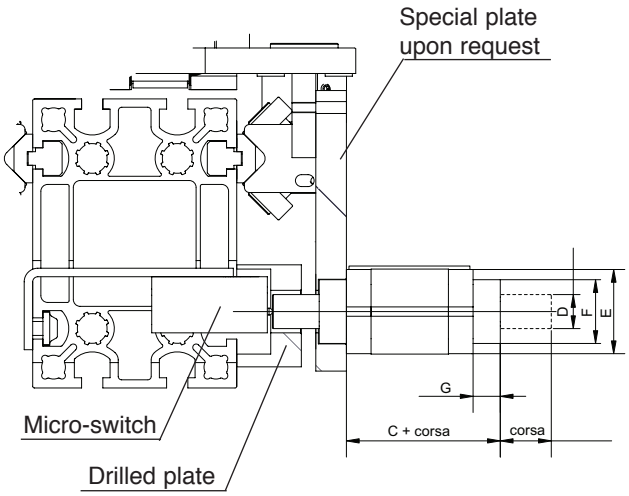
1- Dynamic rod blocking device

Type	Code	Rod blocking force [N]	Stroke [mm]
B	**236.0019**	/ 3,000	/ ...
B	**236.0019**	/ 5,400	/ ...
B	**236.0019**	/ 7,500	/ ...
B	**236.0019**	/ 12,000	/ ...

Safety lock-pin (stopper cylinders)

Lock-pin devices, available in two sizes, suitable to block the vertical axes in the safety position during horizontal movements. (e.g.: maintenance). The safety lock-pins are provided with a through rod.
Select the size according to the load. The kit includes: drilled plate for rod, stopper cylinder, micro-switch.
Max. operating pressure: 10 bar.





1- Lock-pin device

ØD rod	stroke	C	E	F	G	Kit Code
20	20	60.5	50	38	16	**236.0021**
32	30	-	-	-	-	**236.0022**

2- Accessory: drilled plate for rod

ØD rod	Base	Lenght	Thickness
20	60	100	39
32	60	100	39

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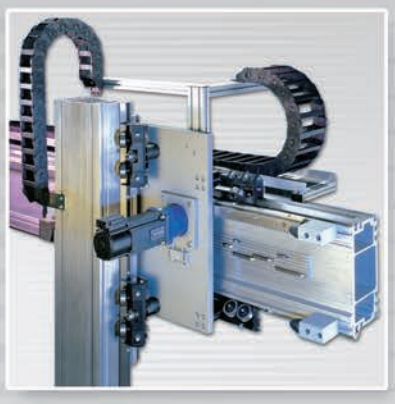
Modline

Tecline

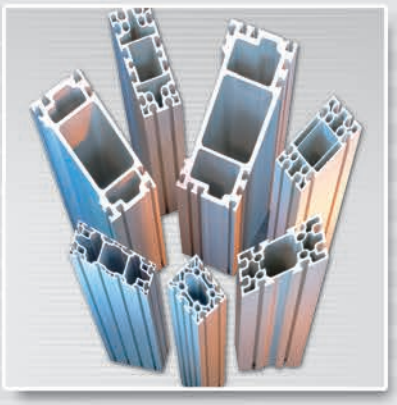


Te product range has been studied so as to promote advantageous, competitive modular integration.

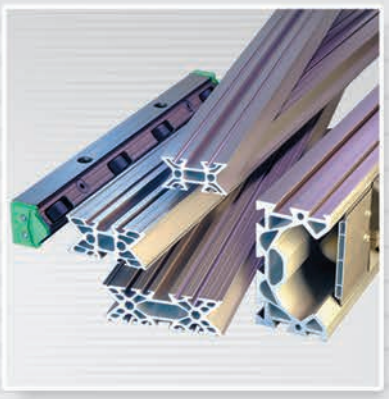
Request our assistance to discover interesting solutions to all your needs in the field of linear transfer.

Systems

Structural profiles



Sys



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